

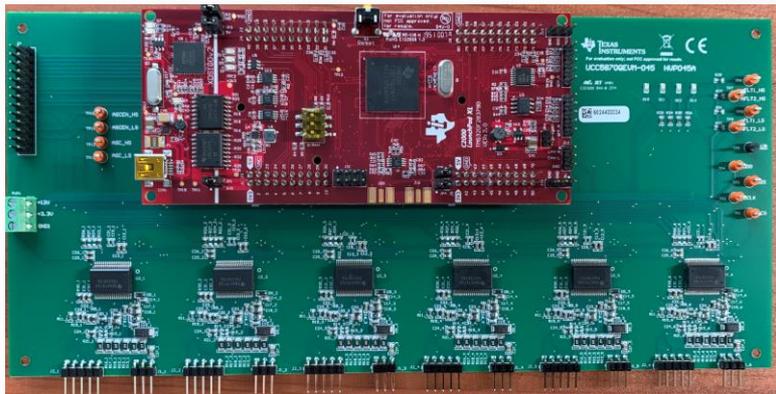
UCC5870QEVM-045 Quick Start Demo

Texas Instruments

Outline

- Introduction of UCC5870QEVM-045
- Test setup
- CCS software installation
- Open CCS and load example code into LaunchPad™ Development Kit
- Run code
- Scope measurements: output SPWMs

UCC5870QEVM-045 introduction:



Functional safety compliant 15-A isolated IGBT/SiC MOSFET gate driver three-phase EVM available now: [EVM](#)

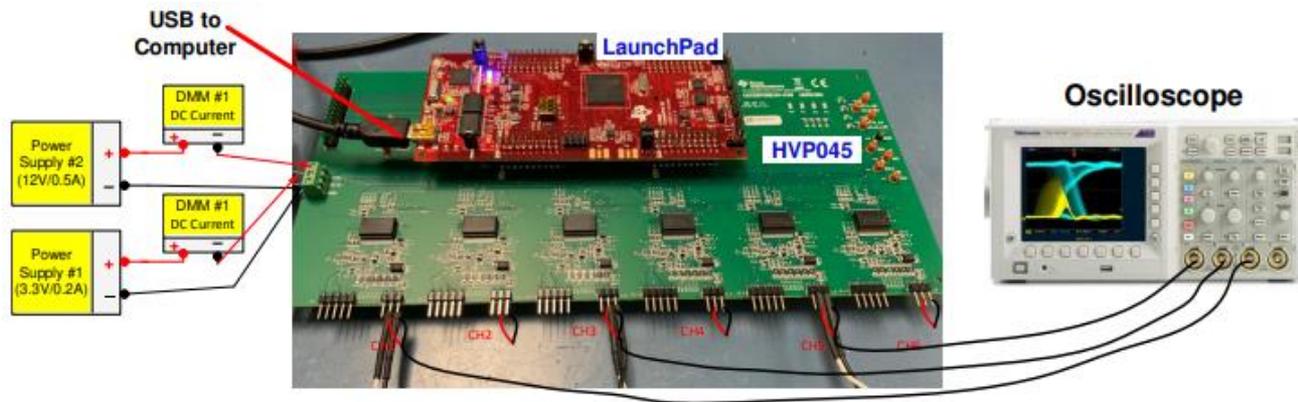
- Supports three-phase application software development
- Compatible with C2000™ MCU F28379D LaunchPad™ development kit (LAUNCHXL-F28379D)
- SPI-based device reconfiguration, verification, supervision and diagnosis
- Supports both address-mode SPI and daisy-chain mode SPI
- Power transistor protections: DESAT, OC/SC, Programmable soft turn off (STO) and two-level turn off (2LTOFF) during power transistor faults
- Split driver outputs guarantee 15-A peak source and 15-A peak sink currents

[UCC5870-Q1 three phase EVM user guide](#)

[C2000™ MCU F28379D LaunchPad™ Development Kit](#)

Test setup

1. Connect the Scope Channels as indicated. Ensure that the polarity on the channels are placed correctly
2. Connect the power supplies as indicated



Software installation

1. Visit <https://www.ti.com/tool/LAUNCHXL-F28379D> and download Code Composer Studio and C2000Ware.
2. Open the user's guide for Code Composer Studio and follow the Installation Process

Home / Design resources

CCSTUDIO-C2000

Code Composer Studio (CCS) Integrated Development Environment (IDE) for C2000 Microcontrollers

Downloads

Overview | Downloads | Technical documentation | Support & training

Overview

Code Composer Studio is an integrated development environment (IDE) that supports TI's Microcontroller and Embedded Processors portfolio. Code Composer Studio comprises a suite of tools used to develop and debug embedded applications. It includes an optimizing C/C++ compiler, source code editor, project build environment, debugger, profiler, and many other features. The intuitive IDE provides a single user interface taking you through each step of the application development flow. Familiar tools and interfaces allow users to get started faster than ever before. Code Composer Studio combines the advantages of the Eclipse software framework with advanced embedded debug capabilities from TI resulting in a compelling feature-rich development environment for embedded developers.

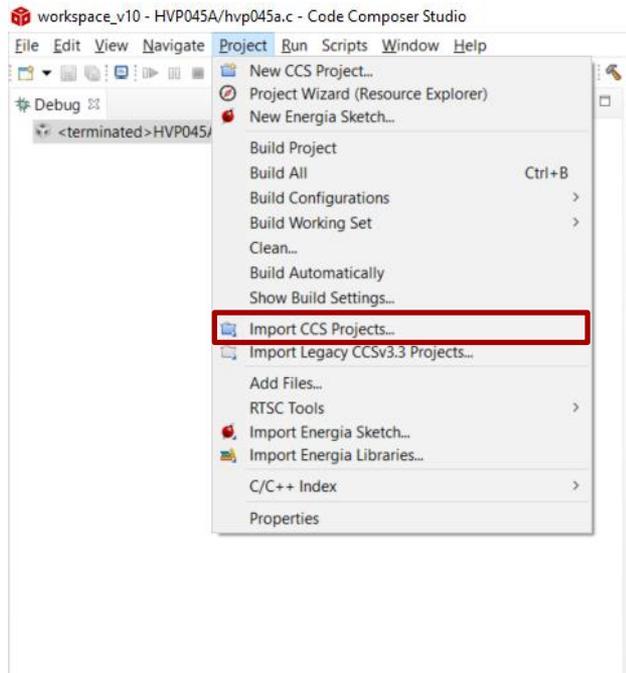
Start development in the Cloud - Visit dev.ti.com to browse through the examples available for a device, run demo applications and even develop code using CCS Cloud a cloud based integrated development environment.

Additional Information

- [Users Guide](#) - information on how to more effectively use Code Composer Studio. Also available in [Resource Explorer](#).
- [Technical documents](#) - users guides, feature overviews and application notes
- [YouTube channel](#) - selection of short videos on how to perform tasks in Code Composer Studio.
- [Training resources](#) - workshops and training modules
- [Getting Started with Code Composer Studio for C2000 Workshop](#)

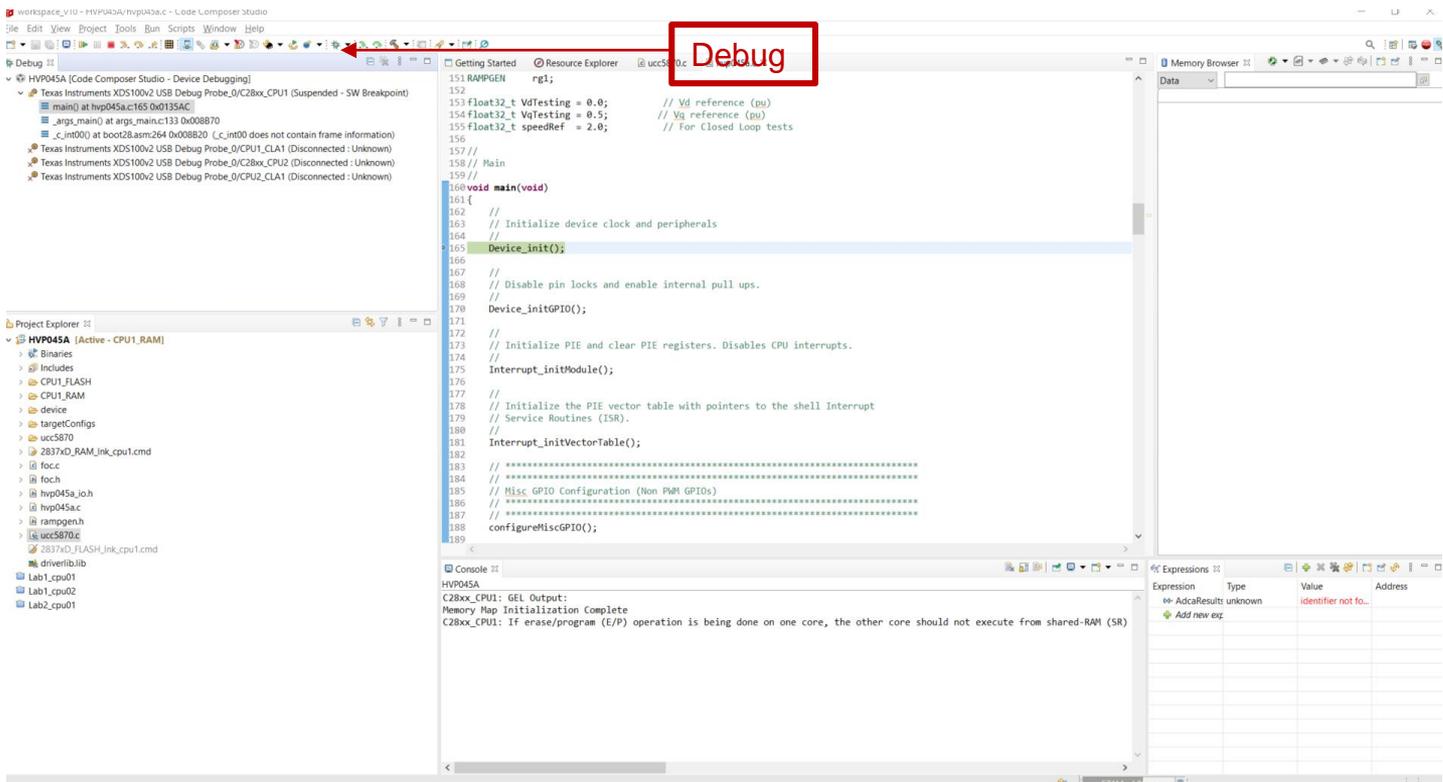
Open CCS and load example code into LaunchPad™ Development Kit

1. After Installation has been completed connect your C2000™ LaunchPad to your computer and import the project to Code Composer Studio



Load the project to the microcontroller

1. Upload the project into the microcontroller by selecting debug



The screenshot displays the Code Composer Studio (CCS) interface. The top toolbar features a red box highlighting the 'Debug' button, which is represented by a play icon. The main editor window shows the source code for the 'main' function, with the 'Device_init();' line highlighted in blue. The left sidebar contains the 'Project Explorer' and 'Debug Console' panels. The 'Project Explorer' shows the project structure for 'HVP045A', including files like 'uuc5870.c' and 'rampgen.h'. The 'Debug Console' at the bottom shows the output of the program, including the message 'C28xx_CPU1: If erase/program (E/P) operation is being done on one core, the other core should not execute from shared-RAM (SR)'. The 'Expressions' panel at the bottom right is empty.

```
151 RAMPGEN    rgl;
152
153 float32_t VdTesting = 0.0;    // Vd reference (pu)
154 float32_t VqTesting = 0.5;    // Vq reference (pu)
155 float32_t speedRef = 2.0;    // for closed loop tests
156
157 //
158 // Main
159 //
160 void main(void)
161 {
162     //
163     // Initialize device clock and peripherals
164     //
165     Device_init();
166
167     //
168     // Disable pin locks and enable internal pull ups.
169     //
170     Device_initGPIO();
171
172     //
173     // Initialize PIE and clear PIE registers. Disables CPU interrupts.
174     //
175     Interrupt_initModule();
176
177     //
178     // Initialize the PIE vector table with pointers to the shell Interrupt
179     // Service Routines (ISR).
180     //
181     Interrupt_initVectorTable();
182
183     //
184     // Misc GPIO Configuration (Non PWM GPIOs)
185     //
186     //
187     //
188     configureMiscGPIO();
189 }
```

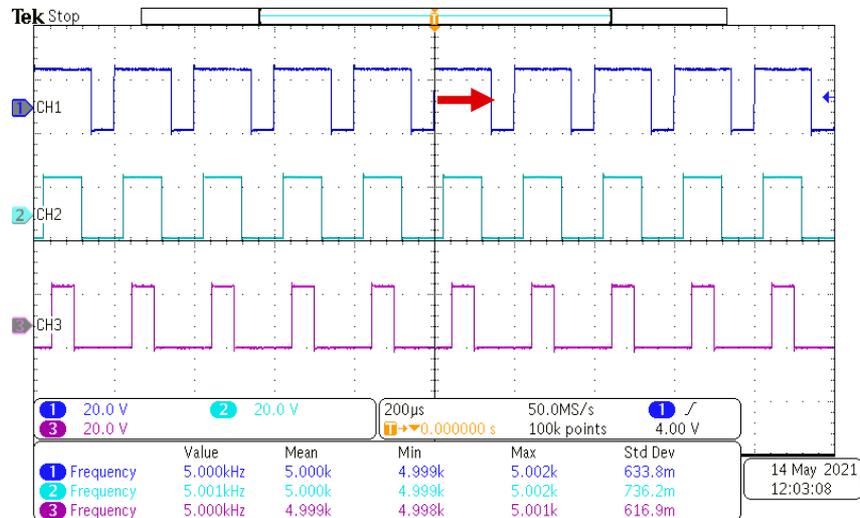
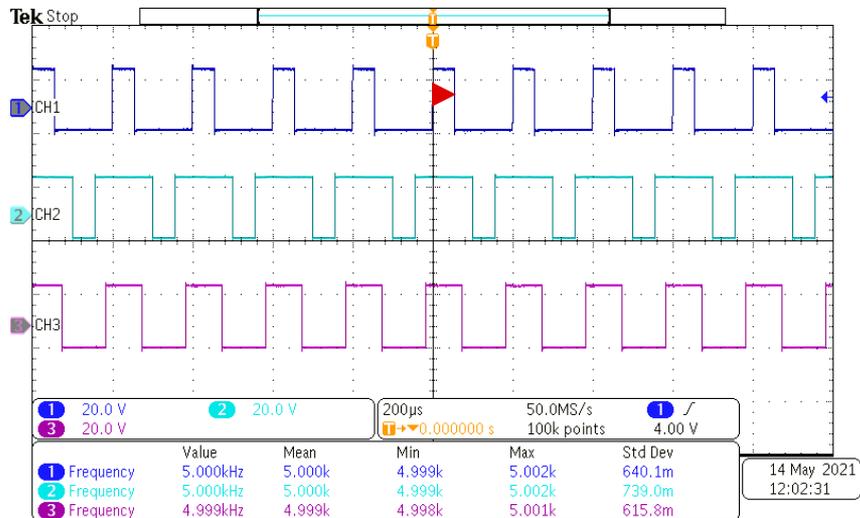
Run the code

1. Select main() and run the code.

The screenshot shows the Code Composer Studio interface with the following components:

- Debugger:** Shows the execution state with a breakpoint at `main()` at `hwp045a.c:165:0x008870`.
- Code Editor:** Displays the `main()` function starting at line 160. A red box highlights the `main()` function name. The code includes initialization for device clock and peripherals, pin locks, and interrupt vectors.
- Project Explorer:** Shows the project structure for `HVP045A`, including source files like `hwp045a.c` and `hwp045a.h`.
- Console:** Displays the output: `C28xx_CPU1: GEL Output: Memory Map Initialization Complete` and `C28xx_CPU1: If erase/program (E/P) operation is being done on one core, the other core should not execute from shared-RAM (SR)`.
- Annotations:** Two red boxes with arrows point to the `Run` button (labeled "Select resume to run the code") and the `main()` function (labeled "Select Main()").

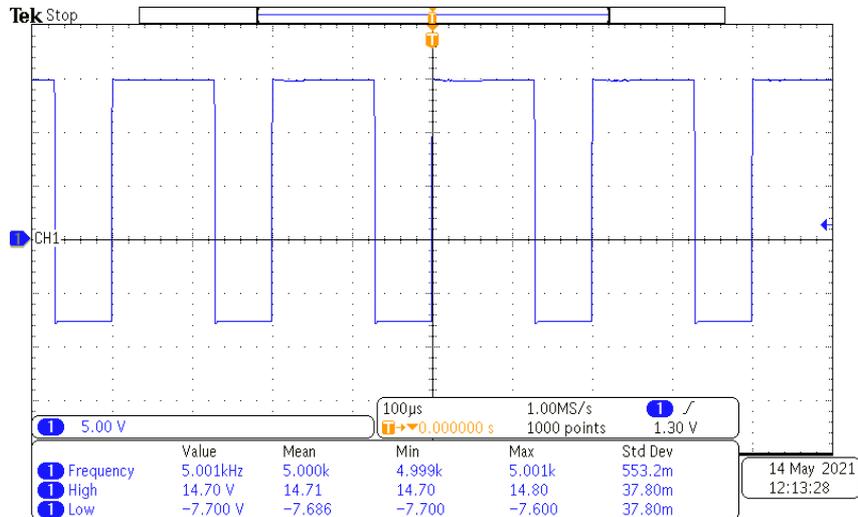
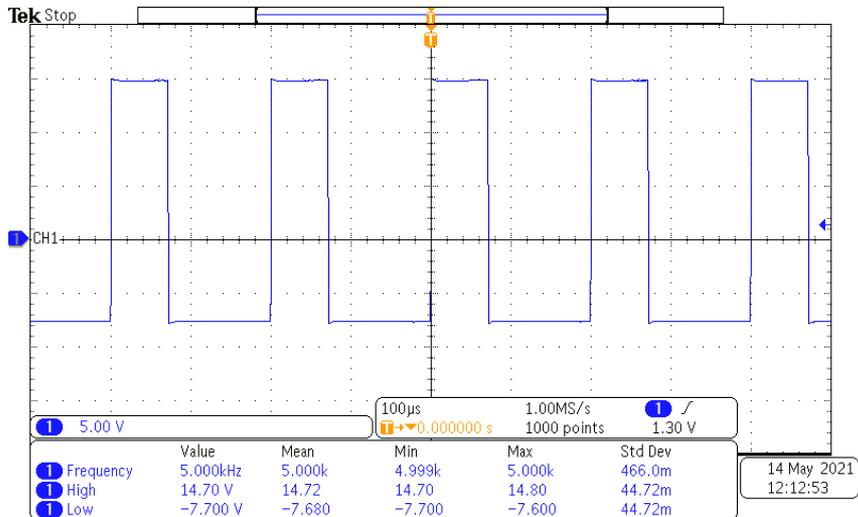
Scope measurements: output SPWMs



Notice:

1. The output is open loop SPWM for all channels (varying duty cycle)
2. Frequency is 5 kHz

Scope measurements: output SPWMs



Notice:

1. The driver voltage is +15V/-7.7V
2. Frequency is 5 kHz