



Test Plan Execution Report

Test Project: VISIONSDK

Test Plan: PSDKV_Test_Plan_3_7_Functional_TDA3xx

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2017 (c) Testlink Community

Table Of Contents

1.1.Network

1.1.1.TCP/IP

VISIONSDK-100: NW_Ctrl_cmd_echo
VISIONSDK-101: NW_Ctrl_cmd_sys_reset
VISIONSDK-102: NW_Ctrl_cmd_qspi_wr
VISIONSDK-103: NW_Ctrl_cmd_mem_rd
VISIONSDK-104: NW_Ctrl_cmd_mem_wr
VISIONSDK-105: NW_Ctrl_cmd_mem_save
VISIONSDK-106: NW_Rx_Display
VISIONSDK-109: SingleCam_Capture_NW_Tx
VISIONSDK-110: MultiCam_Capture_NW_Tx

1.1.2.TFDTP

VISIONSDK-234: NW_Rx_Display_TFDTP
VISIONSDK-237: SingleCam_Capture_NW_Tx_TFDTP
VISIONSDK-238: MultiCam_Capture_NW_Tx_TFDTP
VISIONSDK-329: TFDTP_Rx_Display
VISIONSDK-330: Multi_Plane_MetaData_Buffer_NW_Tx_TFDTP

1.2.FastBoot

VISIONSDK-118: Fast_Boot_AR140_Sensor_10inch_LCD
VISIONSDK-119: Fast_Boot_AR140_Sensor_10inch_LCD_RTI
VISIONSDK-120: Fast_Boot_AR140_Sensor_10inch_LCD_Performance

1.3.SRV

1.3.1.VIP_SRV

1.3.1.1.2D_SRV

VISIONSDK-124: VIP_2D_SRV_OV10635_913deser
VISIONSDK-146: VIP_2D_SRV_OV10635_913deser_without_TDAXX_Folder

1.3.2.CAL_SRV

1.3.2.1.2D_SRV

VISIONSDK-128: ISS_2D_SRV_960/964deser

VISIONSDK-130: ISS_2D_SRV_960/964deser_AE_AWB

VISIONSDK-148: ISS_2D_SRV_960/964deser_without_TDA3X_Folder

1.3.2.2.3D_SRV

VISIONSDK-131: ISS_3D_SRV_960/964deser

VISIONSDK-133: ISS_3D_SRV_960/964deser_360_transition

VISIONSDK-134: ISS_3D_SRV_960/964deser_Dump_Frames

VISIONSDK-135: ISS_3D_2D_SRV_960/964deser

VISIONSDK-136: ISS_3D_SRV_Rearview_960/964deser

VISIONSDK-144: ISS_3D_SRV_960/964deser_without_TDA3X_Folder

VISIONSDK-321: ISS_3D_SRV_960/964deser_Different_Output_resolution

1.3.3.SRV_Calibration

VISIONSDK-137: SRV_Calibration_UC_auto_calibration

VISIONSDK-138: SRV_Calibration_UC_manual_calibration

VISIONSDK-139: SRV_Calibration_UC_default_calibration

VISIONSDK-140: SRV_Calibration_UC_auto_calibration_Dump_Frame

VISIONSDK-141: SRV_Calibration_UC_auto_calibration_update_2D_PERSMAT

VISIONSDK-142: SRV_Calibration_UC_auto_calibration_without_MMC_SD

VISIONSDK-143: SRV_Calibration_UC_auto_calibration_without_TDAXX_Folder

1.3.4.FastBoot_SRV

VISIONSDK-255: FastBoot_ISS_3D_SRV_960/964deser

1.4.Mono_Cam

1.4.1.VIP

1.4.1.1.VIP_SingleCam_Capture_Display

VISIONSDK-1: VIP_Capture_Display_Input_OV10635_Output_7inch_LCD

VISIONSDK-2: VIP_Capture_Display_Input_OV10635_Output_HDMI_720P

VISIONSDK-5: VIP_Capture_Display_Input_OV10635_Output_HDMI_1080P

VISIONSDK-112: VIP_Capture_Display_Input_OV10635_Output_10inch_LCD

VISIONSDK-113: VIP_Capture_Display_Input_OV10635_Output_10inch OSD_LCD

VISIONSDK-114: VIP_Capture_Display_Input_OV10635_Output_SD_PAL

VISIONSDK-115: VIP_Capture_Display_Input_OV10635_Output_SD_NTSC

VISIONSDK-296: VIP_Capture_Display_without_Sensor

1.4.1.2.VIP_Capture_FrameCopy_Display

VISIONSDK-7: VIP_Capture_FrameCopy_DSP1_Display

VISIONSDK-8: VIP_Capture_FrameCopy_EVE1_Display

1.4.1.3.VIP_Capture_SubFrameCopy_Display

VISIONSDK-168: VIP_Capture_SubFrameCopy_EVE1_Display

1.4.1.4.VIP_Capture_IPC_Display

VISIONSDK-230: VIP_Capture_IPC_Display_Single_core

VISIONSDK-231: VIP_Capture_IPC_Display_Multi_core

1.4.1.5.VIP_Capture_Color_To_Gray_Display

VISIONSDK-167: VIP_Capture_Color_To_Gray_Display

1.4.1.6.VIP_Capture_DSSWB_Display

VISIONSDK-179: VIP_Capture_DSSWB_CRC_Display

VISIONSDK-180: VIP_Capture_DisplayMultipipe_DSSWB_Metadata

1.4.1.7.VIP_Capture_VPE_Display

VISIONSDK-189: VIP_Capture_VPE_Display

1.4.1.8.VIP_SingleCam_Capture_Analytics_Display

VISIONSDK-9: VIP_Capture_Edge_detect_Display

VISIONSDK-10: VIP_Capture_DOF_1Pyramid_Display

VISIONSDK-11: VIP_Capture_DOF_2Pyramid_Display

1.4.1.9.VIP_Capture_Display_IPU_SMP_BIOS

VISIONSDK-342: VIP_Capture_Display_Input_OV10635_Output_HDMI_1080P

1.4.2.HDMI

1.4.2.1.HDMI_Capture_Display

VISIONSDK-3: HDMI_Capture_Display_Input_HDMI_Output_LCD

VISIONSDK-4: HDMI_Capture_Display_Input_HDMI_Output_HDMI

1.4.2.2.HDMI_Capture_Analytics_Display

VISIONSDK-14: HDMI_Capture_SOF_Display

VISIONSDK-15: HDMI_Capture_LD_Display

VISIONSDK-16: HDMI_Capture_TLR_Display

VISIONSDK-17: HDMI_Capture_PD_Display

VISIONSDK-18: HDMI_Capture_TSR_Display

VISIONSDK-19: HDMI_Capture_VD_Display

VISIONSDK-20: HDMI_Capture_PD_TSR_VD_Display

VISIONSDK-21: HDMI_Capture_FrontCam_Analytics_Display

1.4.3.ISS

1.4.3.1.ISS_SingleCam_Capture_Display_AR140

VISIONSDK-24: ISS_Capture_AR140_LM

VISIONSDK-25: ISS_Capture_AR140_LM_Performance

VISIONSDK-26: ISS_Capture_AR140_LM_Dyanmic_Range

VISIONSDK-27: ISS_Capture_AR140_1PASS_WDR

VISIONSDK-29: ISS_Capture_AR140_2PASS_WDR
VISIONSDK-31: ISS_Capture_AR140_2PASS_WDR_Performance
VISIONSDK-32: ISS_Capture_AR140_2PASS_WDR_Dynamic_Range
VISIONSDK-33: ISS_Capture_AR140_2PASS_WDR_AE
VISIONSDK-34: ISS_Capture_AR140_2PASS_WDR_VTNF
VISIONSDK-36: ISS_Capture_AR140_2PASS_WDR_LDC
VISIONSDK-37: ISS_Capture_AR140_2PASS_WDR_LDC_VTNF
VISIONSDK-38: ISS_Capture_AR140_2PASS_WDR_Color_Fidelity
VISIONSDK-39: ISS_Capture_AR140_2PASS_WDR_Noise_Filter
VISIONSDK-40: ISS_Capture_AR140_2PASS_WDR_DUMP_RAW_FRAMES
VISIONSDK-41: ISS_Capture_AR140_2PASS_WDR_DUMP_YUV_FRAMES
VISIONSDK-42: ISS_Capture_AR140_2PASS_WDR_Read_Sensor_Reg
VISIONSDK-43: ISS_Capture_AR140_2PASS_WDR_Write_Sensor_Reg
VISIONSDK-44: ISS_Capture_AR140_2PASS_WDR_Save_DCC_Profile
VISIONSDK-45: ISS_Capture_AR140_2PASS_WDR_Send_DCC_Profile
VISIONSDK-46: ISS_Capture_AR140_2PASS_WDR_Clear_DCC_Profile

1.4.3.2.ISS_SingleCam_Capture_Display_OV10640

VISIONSDK-56: ISS_Capture_OV10640_LM_Performance
VISIONSDK-57: ISS_Capture_OV10640_LM_Dyanmic_Range
VISIONSDK-59: ISS_Capture_OV10640_2PASS_WDR
VISIONSDK-60: ISS_Capture_OV10640_2PASS_WDR_Performance
VISIONSDK-61: ISS_Capture_OV10640_2PASS_WDR_Dynamic_Range
VISIONSDK-62: ISS_Capture_OV10640_2PASS_WDR_AE
VISIONSDK-63: ISS_Capture_OV10640_2PASS_WDR_VTNF
VISIONSDK-64: ISS_Capture_OV10640_2PASS_WDR_LDC
VISIONSDK-65: ISS_Capture_OV10640_2PASS_WDR_LDC_VTNF
VISIONSDK-66: ISS_Capture_OV10640_2PASS_WDR_Color_Fidelity
VISIONSDK-67: ISS_Capture_OV10640_2PASS_WDR_Noise_Filter
VISIONSDK-68: ISS_Capture_OV10640_2PASS_WDR_DUMP_RAW_FRAMES
VISIONSDK-69: ISS_Capture_OV10640_2PASS_WDR_DUMP_YUV_FRAMES
VISIONSDK-70: ISS_Capture_OV10640_2PASS_WDR_Read_Sensor_Reg
VISIONSDK-71: ISS_Capture_OV10640_2PASS_WDR_Write_Sensor_Reg
VISIONSDK-72: ISS_Capture_OV10640_2PASS_WDR_Save_DCC_Profile
VISIONSDK-73: ISS_Capture_OV10640_2PASS_WDR_Send_DCC_Profile
VISIONSDK-74: ISS_Capture_OV10640_2PASS_WDR_Clear_DCC_Profile
VISIONSDK-47: ISS_Capture_OV10640_LM

1.4.3.3.ISS_SingleCam_Capture_Display_IMX224

VISIONSDK-77: ISS_Capture_IMX224_LM

VISIONSDK-78: ISS_Capture_IMX224_LM_Performance
VISIONSDK-79: ISS_Capture_IMX224_LM_Dyanmic_Range
VISIONSDK-80: ISS_Capture_IMX224_2PASS_WDR
VISIONSDK-81: ISS_Capture_IMX224_2PASS_WDR_Performance
VISIONSDK-82: ISS_Capture_IMX224_2PASS_WDR_Dynamic_Range
VISIONSDK-83: ISS_Capture_IMX224_2PASS_WDR_AE
VISIONSDK-84: ISS_Capture_IMX224_2PASS_WDR_VTNF
VISIONSDK-85: ISS_Capture_IMX224_2PASS_WDR_LDC
VISIONSDK-86: ISS_Capture_IMX224_2PASS_WDR_LDC_VTNF
VISIONSDK-87: ISS_Capture_IMX224_2PASS_WDR_Color_Fidelity
VISIONSDK-88: ISS_Capture_IMX224_2PASS_WDR_Noise_Filter
VISIONSDK-89: ISS_Capture_IMX224_2PASS_WDR_DUMP_RAW_FRAMES
VISIONSDK-90: ISS_Capture_IMX224_2PASS_WDR_DUMP_YUV_FRAMES
VISIONSDK-91: ISS_Capture_IMX224_2PASS_WDR_Read_Sensor_Reg
VISIONSDK-92: ISS_Capture_IMX224_2PASS_WDR_Write_Sensor_Reg
VISIONSDK-93: ISS_Capture_IMX224_2PASS_WDR_Save_DCC_Profile
VISIONSDK-94: ISS_Capture_IMX224_2PASS_WDR_Send_DCC_Profile
VISIONSDK-95: ISS_Capture_IMX224_2PASS_WDR_Clear_DCC_Profile

1.4.3.4.ISS_SingleCam_Capture_Display_OV2775

VISIONSDK-248: ISS_Capture_OV2775_LM
VISIONSDK-291: ISS_Capture_OV2775_LM_performance
VISIONSDK-315: ISS_Capture_OV2775_LM_LDC_VTNF

1.4.3.5.ISS_SingleCam_Capture_Display_AR0143

VISIONSDK-254: ISS_Capture_AR0143_LM
VISIONSDK-292: ISS_Capture_AR0143_LM_Performance
VISIONSDK-334: ISS_Capture_AR143_1PASS_WDR
VISIONSDK-335: ISS_Capture_AR143_2PASS_WDR
VISIONSDK-336: ISS_Capture_AR143_2PASS_WDR_Performance
VISIONSDK-337: ISS_Capture_AR143_2PASS_WDR_Dynamic_Range
VISIONSDK-338: ISS_Capture_AR143_2PASS_WDR_AE
VISIONSDK-339: ISS_Capture_AR143_2PASS_WDR_VTNF
VISIONSDK-340: ISS_Capture_AR143_2PASS_WDR_LDC
VISIONSDK-341: ISS_Capture_AR143_2PASS_WDR_LDC_VTNF

1.4.3.6.ISS_SingleCam_Capture_Display_AR132

VISIONSDK-263: ISS_Capture_AR132_LM
VISIONSDK-264: ISS_Capture_AR132_LM_Performance
VISIONSDK-265: ISS_Capture_AR132_LM_LDC_VTNF
VISIONSDK-266: ISS_Capture_AR132_LM_DUMP_RAW_FRAMES

VISIONSDK-267: ISS_Capture_AR132_LM_DUMP_YUV_FRAMES

VISIONSDK-268: ISS_Capture_AR132_LM_Read_Sensor_Reg

VISIONSDK-269: ISS_Capture_AR132_LM_Write_Sensor_Reg

VISIONSDK-270: ISS_Capture_AR132_LM_Save_DCC_Profile

VISIONSDK-271: ISS_Capture_AR132_LM_Send_DCC_Profile

VISIONSDK-272: ISS_Capture_AR132_LM_Clear_DCC_Profile

VISIONSDK-286: ISS_Capture_AR132_LM_Monochrome

1.4.3.7.ISS_Capture_Display_IPU_SMP_BIOS

VISIONSDK-358: ISS_Capture_Display_Input_OV10640_Output_HDMI_1080P

VISIONSDK-307: ISS_dump_frames_various_tap_points

VISIONSDK-357: ISS_Capture_OV10640_Output_ARGB32

1.4.4.TIDL

1.4.4.1.TIDL_FILE_IO

VISIONSDK-158: TIDL_File_IO_UC_DSP_Performance

VISIONSDK-159: TIDL_File_IO_UC_DSP_Dump_Frames_File

VISIONSDK-160: TIDL_File_IO_UC_DSP_Free_Run

VISIONSDK-161: TIDL_File_IO_UC_EVE_Performance

VISIONSDK-162: TIDL_File_IO_UC_EVE_Dump_Frames_File

VISIONSDK-163: TIDL_File_IO_UC_EVE_Free_Run

1.4.5.MISC

1.4.5.1.NullSrc_Null_Link

VISIONSDK-372: NullSrc_Capture_Encode_MPEG4_Null

1.4.5.2.SyncLink

VISIONSDK-187: VIP_Capture_Sync_Null

1.4.5.3.DupLink

VISIONSDK-165: VIP_Capture_Dup_Display

1.4.5.4.MergeLink

VISIONSDK-166: VIP_Capture_Merge_Display

1.4.5.5.StatisticsLogs

VISIONSDK-211: VIP_SingleCam_Capture_Display_Statistics_Logs

VISIONSDK-212: Print_PRCM_Statistics_Dpll_Status

VISIONSDK-213: Print_PRCM_Statistics_Temperature

VISIONSDK-214: Print_PRCM_Statistics_Voltage

VISIONSDK-215: Print_PRCM_Statistics_Module_Power_State

VISIONSDK-216: Print_PRCM_Statistics_CPU_Frequency

VISIONSDK-217: Print_PRCM_Statistics_Peripherals_Frequency

VISIONSDK-218: Print_PRCM_Statistics_Prcm_Register_Data

VISIONSDK-219: Print_PRCM_Statistics_Power_Consumption

VISIONSDK-220: Print_PRCM_Statistics_All_PRCM_Stats

VISIONSDK-287: VIP_SingleCam_Capture_Display_Statistics_Logs_CAN

1.4.5.6.FATFS

VISIONSDK-228: File_IO_UC_MMCS_D_IPU1_0

1.4.5.7.Limp_Home_Mode

VISIONSDK-277: Limp_Home_Mode

1.4.5.8.Task_time_measure_utility

VISIONSDK-289: VIP_Capture_Display_task_time_measure_utility

1.4.5.9.TLFW_verify

VISIONSDK-309: TLFW_verification

VISIONSDK-325: VSDK_restructuring_directory_structure

1.4.6.ECC_FFI

VISIONSDK-121: Capture_FrameCopy_FFI_DSP1_Display

VISIONSDK-122: Capture_FrameCopy_FFI_EVE1_Display

1.4.7.IPC_LIB

VISIONSDK-123: IPC_LIB

VISIONSDK-240: Low_Latency_IPC

1.4.8.RTI

VISIONSDK-226: VIP_Capture_Display_suspend_IPU1_0

VISIONSDK-227: VIP_Capture_FrameCopy_Display_suspend_DSP_EVE

1.5.Open_Compute

1.5.1.OpenVX

VISIONSDK-223: OpenVX_Confirmation_Test

VISIONSDK-224: OpenVX_Tutorials

VISIONSDK-225: VIP_Capture_OpenVX_Display_Input_OV10635_Output_HDMI_1080P

VISIONSDK-368: ISS_Capture_OpenVX_Display_Input_AR140_Output_HDMI_1080P

1.6.Multi_Cam

1.6.1.Multi_Channel_LVDS_Capture_Display

VISIONSDK-22: VIP_4CH_Capture_Display_OV10635_913deser

VISIONSDK-132: CSI2_4CH_Capture_Display_OV10635_964deser

1.6.2.SelectLink

VISIONSDK-186: VIP_4CH_Capture_Select_Display

1.6.3.VIP_4CH_Capture_Color_To_Gray_Display

VISIONSDK-188: VIP_4CH_Capture_Color_To_Gray_Display

1.6.4.VIP_4CH_Capture_VPE_Sync_DMA_SWMS_Display

VISIONSDK-192: VIP_4CH_Capture_VPE_Sync_DMA_SWMS_Display

1.6.5.Rear_View_Panorama

VISIONSDK-301: RSVP_4CH_VIP_Capture_960deser_IMI

VISIONSDK-302: RSVP_Manual_LDC_LUT_Generation

1.7.Radar

VISIONSDK-150: Radar_AR12_Capture_Null

VISIONSDK-152: Radar_AR12_Capture_Radar_FrameCopy_DSP1_Null

VISIONSDK-154: NullSrc_Capture_Radar_FFT_EVE1_Null_Read_Frames_SDcard

VISIONSDK-155: NullSrc_Capture_Radar_FFT_EVE1_Null_Write_Frames_SDcard

VISIONSDK-156: NullSrc_Capture_Radar_FFT_EVE1_Null_Read_Frames_NW

VISIONSDK-157: NullSrc_Capture_Radar_FFT_EVE1_Null_Write_Frames_NW

VISIONSDK-232: Radar_AR12_Capture_Radar_Object_Detect_EVE1_Null

VISIONSDK-233: Radar_AR12_Capture_Radar_Object_Detect_EVE1_Display

VISIONSDK-243: Radar_Flash_AR12_Firmware

VISIONSDK-313: Radar_AR12_Multi_Capture_Radar_FFT_EVE1_Display

VISIONSDK-314: Radar_Test_Source_Object_Detection

1.8.Build**1.8.1.VSDK_Builds**

VISIONSDK-249: VSDK_BIOS_different_builds

VISIONSDK-278: VSDK_KW_build

1.8.2.Radar_Builds

VISIONSDK-242: Radar_default_build

VISIONSDK-280: Radar_BIOS_different_builds

1.9.Release_Process

VISIONSDK-245: VSDK_Radar_release_check_list

VISIONSDK-246: VSDK_package_creation_and_installation

VISIONSDK-247: Radar_package_creation_and_installation

1.10.Boot_Modes

1.10.1.Secure_Boot

VISIONSDK-229: VIP_Capture_Display_UC_HS_Sample

1.10.2.QSPI_Boot

VISIONSDK-274: Load_Binaries_using_QSPI

1.10.3.QSPI_SD_Boot

VISIONSDK-275: Load_Binaries_using_QSPI_SD

1.10.4.CCS_Boot

VISIONSDK-332: Load_Binaries_using_CCS

Test Project: VISIONSDK

Project: VISIONSDK Location: TII Owner: Sivasankaran, Shiju

Test Plan: PSDKV_Test_Plan_3_7_Functional_TDA3xx

TDA3xx Functional Test Plan

Will cover all functional test for tda3xx-evm

1.1.Test Suite : Network

1.1.1.Test Suite : TCP/IP

Test Case VISIONSDK-100: NW_Ctrl_cmd_echo			
<u>Summary:</u> Network Control Command "echo"			
<u>Preconditions:</u> verify that host and target can communicate and execute command accordingly Boot with SD card Make network cable connected			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Boot EVM	EVM boots without any error and usecase menu displayed	
2	Open command prompt in host PC Execute "echo" command using network_ctrl.exe #network_ctrl --ipaddr <ipaddr> [--port <server port>] --cmd <command string> <command parameters>	EVM should not hang, and network command should work according to command on target side	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1610: Network RX and TX support on M4 Bios using NDK/NSP ADASVISION-1611: Network RX and TX support on A15 Bios using NDK/NSP		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm m_nw		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-101: NW_Ctrl_cmd_sys_reset			
<u>Summary:</u> Network Control Command "sys_reset"			
<u>Preconditions:</u> verify that host and target can communicate and execute command accordingly Boot with SD card Make network cable connected			
#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Boot EVM	EVM boots without any error and usecase menu displayed	
2	Open command prompt in host PC	EVM should not hang, and network command should work according to command on target	

	Execute "sys_reset" command using network_ctrl.exe	side	
	#network_ctrl --ipaddr <ipaddr> [--port <server port>] --cmd <command string> <command parameters>		
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1610: Network RX and TX support on M4 Bios using NDK/NSP ADASVISION-1611: Network RX and TX support on A15 Bios using NDK/NSP		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-102: NW_Ctrl_cmd_qspi_wrSummary:

Network Control Command "qspi_wr"

Preconditions:

verify that host and target can communicate and execute command accordingly

Boot with SD card

Make network cable connected

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Boot EVM	EVM boots without any error and usecase menu displayed	
2	Open command prompt in host PC Execute "qspi_wr" command using network_ctrl.exe #network_ctrl --ipaddr <ipaddr> [--port <server port>] --cmd <command string> <command parameters>	EVM should not hang, and network command should work according to command on target side	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1610: Network RX and TX support on M4 Bios using NDK/NSP ADASVISION-1611: Network RX and TX support on A15 Bios using NDK/NSP		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-103: NW_Ctrl_cmd_mem_rdSummary:

Network Control Command "mem_rd"

Preconditions:

verify that host and target can communicate and execute command accordingly

Boot with SD card

Make network cable connected

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Boot EVM	EVM boots without any error and usecase menu displayed	
2	Open command prompt in host PC Execute "mem_rd" command using network_ctrl.exe #network_ctrl --ipaddr <ipaddr> [--port <server port>] --cmd <command string> <command parameters>	EVM should not hang, and network command should work according to command on target side	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1610: Network RX and TX support on M4 Bios using NDK/NSP ADASVISION-1611: Network RX and TX support on A15 Bios using NDK/NSP		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-104: NW_Ctrl_cmd_mem_wrSummary:

Network Control Command "mem_wr"

Preconditions:

verify that host and target can communicate and execute command accordingly

Boot with SD card

Make network cable connected

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Boot EVM	EVM boots without any error and usecase menu displayed	
2	Open command prompt in host PC Execute "mem_wr" command using network_ctrl.exe #network_ctrl --ipaddr <ipaddr> [--port <server port>] --cmd <command string> <command parameters>	EVM should not hang, and network command should work according to command on target side	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		

<u>Requirements</u>	ADASVISION-1610: Network RX and TX support on M4 Bios using NDK/NSP ADASVISION-1611: Network RX and TX support on A15 Bios using NDK/NSP
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-105: NW_Ctrl_cmd_mem_saveSummary:

Network Control Command "mem_save"

Preconditions:

verify that host and target can communicate and execute command accordingly

Boot with SD card

Make network cable connected

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Boot EVM	EVM boots without any error and usecase menu displayed	
2	Open command prompt in host PC Execute "mem_save" command using network_ctrl.exe #network_ctrl --ipaddr <ipaddr> [--port <server port>] --cmd <command string> <command parameters>	EVM should not hang, and network command should work according to command on target side	

Execution type: ManualEstimated exec. duration (sec):Priority: Medium

<u>Requirements</u>	ADASVISION-1610: Network RX and TX support on M4 Bios using NDK/NSP ADASVISION-1611: Network RX and TX support on A15 Bios using NDK/NSP
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-106: NW_Rx_DisplaySummary:

Network Rx Display UC

Input : RAW frames

Output : HDMI 1080P

Preconditions:

verify that host and target can communicate and execute command accordingly

Boot with SD card

Make network cable connected

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Boot EVM	EVM boots without any error and usecase menu displayed	
2	Run "Network RX + Display" UC under Network UCs	UC should run without any issues	
3	Open command prompt in host PC & Send RAW frames to target using network_tx.exe # network_tx --host_ip <ipaddr> --target_ip <ipaddr> [--port <server port> --usetfdtp --verbose --no_loop --delay <delay in secs>] --files <CH0 file> <CH1 file>	EVM should not hang, and network command should work according to command on target side	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1263: Null & NullSrc clean-up to move Networking RX/Tx functionalities to new network_rx and network_tx li ADASVISION-1610: Network RX and TX support on M4 Bios using NDK/NSP ADASVISION-1611: Network RX and TX support on A15 Bios using NDK/NSP ADASVISION-1871: IPv6 support configuration ADASVISION-1908: Networking - Dual Ethernet support on TDA2Px ADASVISION-2016: [networking] A15 performance optimization		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm c_regression c_stress c_stability m_nw		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-109: SingleCam_Capture_NW_Tx

Summary:

1 Channel capture + Network Tx UC

Preconditions:

verify that host and target can communicate and execute command accordingly

Boot with SD card

Make network cable connected

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Boot EVM	EVM boots without any error and usecase menu displayed	
2	Run "1CH VIP Capture + Network TX" UC under Network UCs	UC should run without any issues	
3	Open command prompt in host PC & Recieve RAW frames from target using network_rx.exe # network_rx --host_ip <ipaddr> --target_ip <ipaddr> [--port <server port> --usetfdtp --verbose --no_loop --delay <delay in secs>] --files <CH0 file> <CH1 file>	EVM should not hang, and network command should work according to command on target side	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			

<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-1263: Null & NullSrc clean-up to move Networking RX/Tx functionalities to new network_rx and network_tx li ADASVISION-1610: Network RX and TX support on M4 Bios using NDK/NSP ADASVISION-1611: Network RX and TX support on A15 Bios using NDK/NSP ADASVISION-1696: Improve error diagnostic information in network_rx for the network tools
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm c_regression m_nw
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-110: MultiCam_Capture_NW_TxSummary:

4 Channel VIP capture + Network Tx UC

Preconditions:

verify that host and target can communicate and execute command accordingly

Boot with SD card

Make network cable connected

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Boot EVM	EVM boots without any error and usecase menu displayed	
2	Run "4CH VIP Capture + Network TX" UC under Network UCs	UC should run without any issues	
3	Open command prompt in host PC & Recieve RAW frames from target using network_rx.exe # network_rx --host_ip <ipaddr> --target_ip <ipaddr> [--port <server port> --usetfdtp --verbose --no_loop --delay <delay in secs>] --files <CH0 file> <CH1 file>	EVM should not hang, and network command should work according to command on target side	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1610: Network RX and TX support on M4 Bios using NDK/NSP ADASVISION-1611: Network RX and TX support on A15 Bios using NDK/NSP ADASVISION-1696: Improve error diagnostic information in network_rx for the network tools		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.1.2.Test Suite : TFDTP

Test Case VISIONSDK-234: NW_Rx_Display_TFDTP			
<u>Summary:</u>			
Network Rx Display UC using TFDTP			
Input : RAW frames			
Output : HDMI 1080P			
<u>Preconditions:</u>			
Binaries should be built with NSP_TFDTP_INCLUDE=yes			
verify that host and target can communicate and execute command accordingly			
Boot with SD card			
Make network cable connected			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Boot EVM	EVM boots without any error and usecase menu displayed	
2	Run "Network RX + Display" UC under Network UCs	UC should run without any issues	
3	Select TFDTP	TFDTP should be selected	
4	Open command prompt in host PC & Send RAW frames to target using network_tx.exe # network_tx --host_ip <ipaddr> --target_ip <ipaddr> [--port <server port> --usetfdtp --verbose --no_loop --delay <delay in secs>] --files <CH0 file> <CH1 file>	EVM should not hang, and network command should work according to command on target side	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1135: TFDTP integration with VSDK ADASVISION-1181: Retransmit support in TFDTP receive ADASVISION-1183: TFDTP support on A15 ADASVISION-1908: Networking - Dual Ethernet support on TDA2Px ADASVISION-2016: [networking] A15 performance optimization		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-237: SingleCam_Capture_NW_Tx_TFDTP			
<u>Summary:</u>			
Single Channel capture + Network Tx UC using TFDTP			
<u>Preconditions:</u>			
Binaries should be built with NSP_TFDTP_INCLUDE=yes			

verify that host and target can communicate and execute command accordingly

Boot with SD card

Make network cable connected

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Boot EVM	EVM boots without any error and usecase menu displayed	
2	Run "1CH VIP Capture + Network TX" UC under Network UCs	UC should run without any issues	
3	Select TFDTP	TFDTP should be selected	
4	Open command prompt in host PC & Recieve RAW frames from target using network_rx.exe # network_rx --host_ip <ipaddr> --target_ip <ipaddr> [--port <server port> --usetfdtp --verbose --no_loop --delay <delay in secs>] --files <CH0 file> <CH1 file>	EVM should not hang, and network command should work according to command on target side	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1135: TFDTP integration with VSDK ADASVISION-1696: Improve error diagnostic information in network_rx for the network tools		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-238: MultiCam_Capture_NW_Tx_TFDTP

Summary:

4 Channel VIP capture + Network Tx UC using TFDTP

Preconditions:

Binaries should be built with NSP_TFDTP_INCLUDE=yes

verify that host and target can communicate and execute command accordingly

Boot with SD card

Make network cable connected

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Boot EVM	EVM boots without any error and usecase menu displayed	
2	Run "4CH VIP Capture + Network TX" UC under Network UCs	UC should run without any issues	
3	Select TFDTP	TFDTP should be selected	
4	Open command prompt in host PC & Recieve RAW frames from target using network_rx.exe # network_rx --host_ip <ipaddr> --target_ip <ipaddr> [--port <server port> --usetfdtp --verbose --no_loop --delay <delay in secs>] --files <CH0 file> <CH1 file>	EVM should not hang, and network command should work according to command on target side	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1135: TFDTP integration with VSDK ADASVISION-1696: Improve error diagnostic information in network_rx for the network tools		

<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-329: TFDTP_Rx_DisplaySummary:

TFDTP Rx Display UC

Input : RAW frames

Output : HDMI 1080P

Preconditions:

Binaries should be built with NSP_TFDTP_INCLUDE=yes

verify that host and target can communicate and execute command accordingly

Boot with SD card

Make network cable connected

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Boot EVM	EVM boots without any error and usecase menu displayed	
2	Run "TFDTP RX + Display" UC under Network UCs	UC should run without any issues	
3	Open command prompt in host PC & Send RAW frames to target using network_tx.exe # network_tx --host_ip <ipaddr> --target_ip <ipaddr> [--port <server port> --usetfdtp --verbose --no_loop --delay <delay in secs>] --files <CH0 file> <CH1 file>	EVM should not hang, and network command should work according to command on target side	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1135: TFDTP integration with VSDK ADASVISION-1181: Retransmit support in TFDTP receive		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-330: Multi_Plane_MetaData_Buffer_NW_Tx_TFDTPSummary:

Single Channel capture + Network Tx UC using TFDTP

Preconditions:

Binaries should be built with NSP_TFDTP_INCLUDE=yes

verify that host and target can communicate and execute command accordingly

Boot with SD card

Make network cable connected

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Boot EVM	EVM boots without any error and usecase menu displayed	
2	Run "1CH VIP Capture + Network TX" UC under Network UCs	UC should run without any issues	
3	Select TFDTP	TFDTP should be selected	
4	Open command prompt in host PC & Recieve RAW frames from target using network_rx.exe # network_rx --host_ip <ipaddr> --target_ip <ipaddr> [--port <server port> --usetfdtp --verbose --no_loop --delay <delay in secs>] --files <CH0 file> <CH1 file>	EVM should not hang, and network command should work according to command on target side	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1135: TFDTP integration with VSDK ADASVISION-1694: Null Link to support network TFDTP transfer for multi-plane Meta data buffer ADASVISION-1696: Improve error diagnostic information in network_rx for the network tools		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.2.Test Suite : FastBoot

Test Case VISIONSDK-118: Fast_Boot_AR140_Sensor_10inch_LCD			
Summary:			
Fast Boot UC - 1CH ISS Capture + ISP + LDC + Obj detect + Display			
Capture - AR140 sensor			
Display - 10 inch LCD			
Binaries - TDA3xx FastBoot QSPI Binaries			
Preconditions:			
Verify I2C to run at 400KHz			
Binaries should be built with FAST_BOOT_INCLUDE=yes			
#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Follow UserGuide & Flash FastBoot QSPI Binaries on TDA3xx	Flashing should be successfull	
2	Boot EVM	1. Display should flash up with preview in < 1 sec 2. Usecase should switch to Object detect algorithm and Pedestrian / Traffic signs detection should start as soon as they are in field of view after boot up 3.You should see boot time printed on the LCD 4.Display must come up and no buffer drops should be observed	
Execution type:	Manual		
Estimated exec. duration (sec):			
Priority:	Medium		
Requirements	ADASVISION-1349: Fast boot mode ADASVISION-1576: First boot - Boot optimization (TDA3x)		
Keywords:	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

Test Case VISIONSDK-119: Fast_Boot_AR140_Sensor_10inch_LCD_RTI			
<u>Summary:</u>			
Fast Boot UC - 1CH ISS Capture + ISP + LDC + Obj detect + Display			
Capture - AR140 sensor			
Display - 10 inch LCD			
Binaries - TDA3xx FastBoot QSPI Binaries			
<u>Preconditions:</u>			
Verify I2C to run at 400KHz			
Verify RTI is enabled in the Build			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Follow UserGuide & Flash	Flashing should be successfull	

	FastBoot QSPI Binaries on TDA3xx		
2	Boot EVM	1. Display should flash up with preview in < 1 sec 2. Usecase should switch to Object detect algorithm and Pedestrian / Traffic signs detection should start as soon as they are in field of view after boot up 3. You should see boot time printed on the LCD 4. Display must come up and no buffer drops should be observed	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1349: Fast boot mode ADASVISION-1509: RTI support ADASVISION-1576: First boot - Boot optimization (TDA3x)		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-120: Fast_Boot_AR140_Sensor_10inch_LCD_Performance
Summary:

Fast Boot UC - 1CH ISS Capture + ISP + LDC + Obj detect + Display

Capture - AR140 sensor

Display - 10 inch LCD

Binaries - TDA3xx FastBoot QSPI Binaries

Preconditions:

Verify I2C to run at 400KHz

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Follow UserGuide & Flash FastBoot QSPI Binaries on TDA3xx	Flashing should be successfull	
2	Boot EVM	1. Display should flash up with preview in < 1 sec 2. Usecase should switch to Object detect algorithm and Pedestrian / Traffic signs detection should start as soon as they are in field of view after boot up 3. You should see boot time printed on the LCD 4. Display must come up and no buffer drops should be observed	
3	Check Performance stats for 1. SBL time 2. Sensor initialization time with I2C 400 KHz 3. Time take by Framework 4. Power On Reset to Display Time 5. Power On to reset to Object Detect 6. Low power load	Performance stats should match with datasheet of release binaries	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1349: Fast boot mode ADASVISION-1576: First boot - Boot optimization (TDA3x)		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		

Tester	x0246581
Execution Result:	Passed
Execution Mode:	Manual
Execution duration (sec):	

1.3.Test Suite : SRV

1.3.1.Test Suite : VIP_SRV

1.3.1.1.Test Suite : 2D_SRV

Test Case VISIONSDK-124: VIP_2D_SRV_OV10635_913deser

Summary:

VIP 2D SRV UC supported on TDA2x/TDA2Ex/TDA3x

Input : OV10635 with 913/914 deserializer

Output : HDMI 1080P (TDA2x/TDA2Ex) , HDMI XGA TDM mode (TDA3x ONLY)

Preconditions:

In case of TDA2x/TDA2Ex:

Ensure TDA2x folder present in SD card with CHARTPOS.BIN & LENS_2D.BIN

Run SRV calibration to generate PERSMAT.BIN if required

In case of TDA3x:

Ensure TDA3x folder present in SD card with CHARTPOS.BIN & LENS_2D.BIN

Run SRV calibration to generate LUT.BIN if required

Verify whether display shows a smooth stitching of all 4 cameras.

All running at 30fps, Also check performance stats match with datasheet

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P (TDA2x/TDA2Ex), HDMI XGA TDM mode (TDA3x ONLY)	Capture Source should be OV10635 & Display device as HDMI 1080P (TDA2x/TDA2Ex), HDMI XGA TDM mode (TDA3x ONLY)	
2	Run "4CH VIP Capture + Surround View (DSP) + Display (HDMI)" UC	Display must come up and no buffer drops should be observed	

Execution type: Automated

Estimated exec. duration (sec): 60.00

Priority: Medium

Requirements

ADASVISION-1275: VIP Capture Link to support Multi channel capture
 ADASVISION-1280: VIP Capture Link to support Inline scaling both down scale and upscale
 ADASVISION-1290: VIP Capture Link - Detect VIP port overflow & Reset
 ADASVISION-1295: Display Link support for various input data formats
 ADASVISION-1300: Display Link - Video window positioning support
 ADASVISION-1308: Display Link - support for custom resolutions
 ADASVISION-1321: Display Link - Support 8-bit TDM mode display
 ADASVISION-1582: Shall support LVDS multi-channel capture upto 4 channel
 ADASVISION-1584: Shall support all the Bios single camera usecases which use one DSP & M4
 ADASVISION-830: For all SRV - DSP load optimization using SIMD

Keywords:

tda2xx-evm
 tda2ex-evm
 tda3xx-evm
 tda2ex-entry
 tda2px-evm
 c_regression
 c_qualification
 m_capture
 m_display

Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-146: VIP_2D_SRV_OV10635_913deser_without_TDAXX_FolderSummary:

VIP 2D SRV UC supported on TDA2x/TDA2Ex/TDA3x

Input : OV10635 with 913/914 deserializer

Output : HDMI 1080P (TDA2x/TDA2Ex) , HDMI XGA TDM mode (TDA3x ONLY)

Preconditions:

In case of TDA2x/TDA2Ex:

Ensure TDA2x folder not present in SD card

In case of TDA3x:

Ensure TDA3x folder not present in SD card

Verify whether display shows a smooth stitching of all 4 cameras.

All running at 30fps, Also check performance stats match with datasheet

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P (TDA2x/TDA2Ex), HDMI XGA TDM mode (TDA3x ONLY)	Capture Source should be OV10635 & Display device as HDMI 1080P (TDA2x/TDA2Ex), HDMI XGA TDM mode (TDA3x ONLY)	
2	Run "4CH VIP Capture + Surround View (DSP) + Display (HDMI)" UC	Display must come up and no buffer drops should be observe	

Execution type: Manual

Estimated exec. duration (sec):

Priority: Medium

Requirements
ADASVISION-1275: VIP Capture Link to support Multi channel capture
ADASVISION-830: For all SRV - DSP load optimization using SIMD

Keywords:
tda2xx-evm
tda2ex-evm
tda3xx-evm
tda2ex-entry
tda2px-evm

Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

1.3.2.Test Suite : CAL_SRV

1.3.2.1.Test Suite : 2D_SRV

Test Case VISIONSDK-128: ISS_2D_SRV_960/964deser

Summary:

ISS 2D SRV UC

Input : IMI OV10640 / TIDA AR140 with 960 deserializer
or OV10635 with 964 deserializer

Output : HDMI 1080P

Binaries: 512MB & 128MB

Preconditions:

Ensure TDA3x folder present in SD card with CHARTPOS.BIN & LENS.BIN

Run SRV calibration UC if required to generate LUT.BIN

Verify whether display shows a smooth stitching of all 4 cameras.

All running at 30fps, Also check performance stats match with datasheet

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as "OV10640 Sensor for SV - IMI (TDA3x ONLY)" or "AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY)" & Display Output as HDMI 1080P	Capture Source should be OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & selected by user & Display device as HDMI 1080P	
2	Run "4CH ISS capture + ISS ISP + Simcop + Surround View (DSP1) + Display" UC	Display must come up and no buffer drops should be observe	
Execution type:	Automated		
Estimated exec. duration (sec):	60.00		
Priority:	Medium		
Requirements	ADASVISION-1396: 4ch 2D surround view with OV10640 Bayer sensors ADASVISION-1579: low cost surround view with TDA3x		
Keywords:	tda3xx-evm tda3xx_rvp c_qualification m_iss		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

Test Case VISIONSDK-130: ISS_2D_SRV_960/964deser_AE_AWB

Summary:

ISS 2D SRV UC

Input : IMI OV10640 / TIDA AR140 with 960 deserializer
or OV10635 with 964 deserializer

Output : HDMI 1080P

Preconditions:

Ensure TDA3x folder present in SD card with CHARTPOS.BIN & LENS.BIN

Run SRV calibration UC if required to generate LUT.BIN

Verify whether display shows a smooth stitching of all 4 cameras.

All running at 30fps, Also check performance stats match with datasheet

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as "OV10640 Sensor for SV - IMI (TDA3x ONLY)" or "AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY)" & Display Output as HDMI 1080P	Capture Source should be OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & selected by user & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 1 PASS WDR	Selected ISS settings will be saved	
3	Run "4CH ISS capture + ISS ISP + Simcop + Surround View (DSP1) + Display" UC	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Noise levels should be very low.	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1579: low cost surround view with TDA3x		
<u>Keywords:</u>	tda3xx-evm tda3xx_rvp		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-148: ISS_2D_SRV_960/964deser_without_TDA3X_FolderSummary:

ISS 2D SRV UC

Input : IMI OV10640 / TIDA AR140 with 960 deserializer
or OV10635 with 964 deserializer

Output : HDMI 1080P

Preconditions:

Ensure TDA3x folder not present in SD card

Verify whether display shows a smooth stitching of all 4 cameras.

All running at 30fps, Also check performance stats match with datasheet

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as "OV10640 Sensor for SV - IMI (TDA3x ONLY)" or "AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY)" & Display Output as HDMI 1080P	Capture Source should be OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & selected by user & Display device as HDMI 1080P	
2	Run "4CH ISS capture + ISS ISP + Simcop + Surround View (DSP1) + Display" UC	Display must come up and no buffer drops should be observe	
<u>Execution type:</u>		Manual	
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1167: Error handling requirements ADASVISION-1526: Error handling ADASVISION-1579: low cost surround view with TDA3x	
<u>Keywords:</u>		tda3xx-evm tda3xx_rvp	
Execution Details			
Build		REL_3_7	
Tester		x0246581	
<u>Execution Result:</u>		Passed	
<u>Execution Mode:</u>		Manual	
<u>Execution duration (sec):</u>			

1.3.2.2.Test Suite : 3D_SRV

Test Case VISIONSDK-131: ISS_3D_SRV_960/964deser			
<u>Summary:</u>			
ISS 3D SRV UC			
Input : IMI OV10640 / TIDA AR140 / TIDA AR143 with 960/964 deserializer or OV10635 with 964 deserializer			
Output : HDMI 1080P			
Binaries: 512MB & 128MB			
<u>Preconditions:</u>			
Ensure TDA3x folder present in SD card with CHARTPOS.BIN & LENS.BIN			
Run SRV calibration UC if required to generate LUT.BIN			
Verify whether display shows a smooth stitching of all 4 cameras.			
All running at 30fps, Also check performance stats match with datasheet			
#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as "OV10640 Sensor for SV - IMI (TDA3x ONLY)" or "AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY)"	Capture Source should be OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & selected by user	

	& Display Output as HDMI 1080P	& Display device as HDMI 1080P	
2	Run "3D SRV 4CH ISS capture + ISS ISP + DeWarp + Synthesis (DSP1) + Display" UC	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Noise levels should be very low.	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1037: TDA3x 3D SRV: Improve imaging for SRV with Improve AE stability & Integrate Photometric alignment ADASVISION-1068: TDA3x 3D SRV : Auto calculate number of slice parameters ADASVISION-1069: TDA3c 3D SRV: Lens type : Distortion table ADASVISION-1071: TDA3x 3D SRV : Boot time optimization ADASVISION-1087: Support synchronization of camera in UB964 ADASVISION-1090: Update TI logo ADASVISION-1257: AR0143 Sensor Support ADASVISION-1295: Display Link support for various input data formats ADASVISION-1298: Display Link - Progressive mode display ADASVISION-1300: Display Link - Video window positioning support ADASVISION-1304: Display Link - Display Multi instance support ADASVISION-1306: Display Link - HDMI display support ADASVISION-1307: Display Link - Support for standard display resolutions ADASVISION-1308: Display Link - support for custom resolutions ADASVISION-1309: Display Link - Blending support of Grpx and Video planes ADASVISION-1310: Display Link - Blending support for Video planes ADASVISION-1311: Display Link - Color keying support ADASVISION-1312: Display Link - Set back Ground Color of VENC ADASVISION-1317: Display Link - Transparency Color Key Selection support ADASVISION-1318: Display Link - VENC section ADASVISION-1324: multi sensors support ADASVISION-1325: support LVDS capture ADASVISION-1326: Support OV10640 Raw/Bayer sensors ADASVISION-1456: ISS capture - mode ADASVISION-1457: ISS capture - interface ADASVISION-1458: ISS capture - CSI2 mode ADASVISION-1459: ISS capture - resolution ADASVISION-1461: ISS capture - packing ADASVISION-1466: ISS multi-channel capture ADASVISION-1467: ISS M2M -ISP - GLBCE selection ADASVISION-1468: ISS M2M -ISP - resizer ADASVISION-1469: ISS M2M -ISP - output dataformat ADASVISION-1470: ISS M2M -ISP - input data format ADASVISION-1471: ISS M2M -ISP - NF ADASVISION-1472: ISS M2M -ISP - WDR modes ADASVISION-1473: ISS M2M -ISP - resizer ADASVISION-1474: ISS M2M -ISP multiple instance ADASVISION-1475: ISS M2M - H3A ADASVISION-1477: ISS M2M (LDC + VTNF) - LDC selection ADASVISION-1478: ISS M2M (LDC + VTNF) - LDC data format ADASVISION-1479: ISS M2M (LDC + VTNF) - VTNF data format ADASVISION-1480: ISS M2M (LDC + VTNF) - LDC create time config ADASVISION-1481: ISS M2M (LDC + VTNF) - VTNF create time config ADASVISION-1482: ISS M2M (LDC + VTNF) - general ADASVISION-1483: ISS M2M RSZ - resizer ADASVISION-1484: ISS M2M RSZ - output dataformat ADASVISION-1485: ISS M2M RSZ - input data format ADASVISION-1486: ISS M2M RSZ - Multi scale (pyramid generation for PD/TSR etc) ADASVISION-1487: ISS M2M RSZ - multi-instance ADASVISION-1488: ISS M2M RSZ - multi-instance with ISP M2M ADASVISION-1489: ISS M2M RSZ - multi-CH ADASVISION-1579: low cost surround view with TDA3x ADASVISION-1606: Algo Link DeWarp for multiple channel LDC correction. ADASVISION-1621: ISS: Capture Link & M2M ISP : Support MIPI RAW 12 dataformat ADASVISION-1643: ISP Based SRV : Split LUT's ADASVISION-1644: ISP Based SRV: Configurable blend seam angle ADASVISION-1645: ISP Based SRV: Configurable blend seam start point ADASVISION-1647: ISP Based SRV: Compression of LUT's ADASVISION-1684: ISP Based SRV: Updated interface of Mesh Generation Tool ADASVISION-1685: ISP Based SRV: Parametric transition between view points ADASVISION-1686: ISP Based SRV: Adaptive bowl support on LDC Surroundview ADASVISION-1687: ISP Based SRV: Compression and reorganization of V2W Table(s) ADASVISION-1688: ISP Based SRV: Generating Car Box Edges/view ADASVISION-1701: AR143 (MARs) Camera and Fusion board support on TDA2Px ADASVISION-1709: TDA3x SRV: Add multi camera harmonization ADASVISION-1786: SerDes cleanup for ISS sensor drivers		

	ADASVISION-830: For all SRV - DSP load optimization using SIMD ADASVISION-889: 3D SRV on TDA3x " Enhancements ADASVISION-932: TDA3x 3D SRV on 128MB memory map ADASVISION-962: TDA3x 3D SRV: Enabling 2A and WDR
Keywords:	tda3xx-evm tda3xx_rvp c_qualification
Execution Details	
Build	REL_3_7
Tester	x0246581
Execution Result:	Passed
Execution Mode:	Manual
Execution duration (sec):	

Test Case VISIONSDK-133: ISS_3D_SRV_960/964deser_360_transition			
Summary:			
ISS 3D SRV UC			
Input : IMI OV10640 / TIDA AR140 with 960 deserializer or OV10635 with 964 deserializer			
Output : HDMI 1080P			
Preconditions:			
Ensure TDA3x folder present in SD card with CHARTPOS.BIN & LENS.BIN			
Run SRV calibration UC if required to generate LUT.BIN			
Verify whether display shows a smooth stitching of all 4 cameras.			
All running at 30fps, Also check performance stats match with datasheet			
#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as "OV10640 Sensor for SV - IMI (TDA3x ONLY)" or "AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY)" & Display Output as HDMI 1080P	Capture Source should be OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & selected by user & Display device as HDMI 1080P	
2	Run "3D SRV 4CH ISS capture + ISS ISP + DeWarp + Synthesis (DSP1) + Display" UC	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Noise levels should be very low.	
3	Check for 3D SRV transition	SRV transition should cover 360 degree	
4	Check User is able to Start/Stop transition Select "s" to Start/Stop transition Select "n" to change to next View Point Select "r" to change to previous View Point	On selecting "s" Transitions should stop On selecting "n" Transition should happen to next view point On selecting "r" Transition should happen to previous view point On selecting "s" again Transition should start normally	
Execution type:	Manual		

<u>Estimated exec. duration (sec):</u>	
<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-1036: TDA3x 3D SRV: 360 degree flyaround (Phase 1) ADASVISION-1037: TDA3x 3D SRV: Improve imaging for SRV with Improve AE stability & Integrate Photometric alignment ADASVISION-1068: TDA3x 3D SRV : Auto calculate number of slice parameters ADASVISION-1069: TDA3c 3D SRV: Lens type : Distortion table ADASVISION-1071: TDA3x 3D SRV : Boot time optimization ADASVISION-1527: API config outbound check ADASVISION-1736: Enable AEWB for all 4 Channels for ISS based 3D SRV on TDA2Px and TDA3x ADASVISION-889: 3D SRV on TDA3x "Enhancements" ADASVISION-962: TDA3x 3D SRV: Enabling 2A and WDR
<u>Keywords:</u>	tda3xx-evm tda3xx_rvp c_integration
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-134: ISS_3D_SRV_960/964deser_Dump_FramesSummary:

ISS 3D SRV UC

Input : IMI OV10640 / TIDA AR140 with 960 deserializer

or OV10635 with 964 deserializer

Output : HDMI 1080P

Preconditions:

Ensure TDA3x folder present in SD card with CHARTPOS.BIN & LENS.BIN

Run SRV calibration UC if required to generate LUT.BIN

Verify whether display shows a smooth stitching of all 4 cameras.

All running at 30fps, Also check performance stats match with datasheet

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as "OV10640 Sensor for SV - IMI (TDA3x ONLY)" or "AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY)" & Display Output as HDMI 1080P	Capture Source should be OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & selected by user & Display device as HDMI 1080P	
2	Run "3D SRV 4CH ISS capture + ISS ISP + DeWarp + Synthesis (DSP1) + Display" UC	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Noise levels should be very low.	
3	Select "1" to Save a Captured RAW frame from channel 0 (Will be saved in DDR) Select "2" to Save a DeWarp Output Frame (Will be saved in DDR) Select "3" to Save ISP output frames (Will be saved in MMC/SD : All channels)	On selecting "1" RAW frame from channel 0 should be saved in DDR On selecting "2" DeWarp Output Frame should be saved in DDR	

	Select "d" to Save Display Frame to MMC/SD card	On selecting "3" ISP output frames should be saved in MMC/SD : All channels On selecting "d" Display Frame should be saved to MMC/SD card	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1036: TDA3x 3D SRV: 360 degree flyaround (Phase 1) ADASVISION-1037: TDA3x 3D SRV: Improve imaging for SRV with Improve AE stability & Integrate Photometric alignment ADASVISION-1068: TDA3x 3D SRV : Auto calculate number of slice parameters ADASVISION-1069: TDA3c 3D SRV: Lens type : Distortion table ADASVISION-1071: TDA3x 3D SRV : Boot time optimization ADASVISION-1542: Algorithm Link Support (Framework and Skeleton portion) ADASVISION-1543: Algorithm Link Support for all CPU cores ADASVISION-1544: Algorithm Link Support Prioritization ADASVISION-1545: Algorithm Link Support Multiple instantiation ADASVISION-1546: Algorithm Link Support Multiple input and output queues ADASVISION-1547: Algorithm Link Support Multiple input channels ADASVISION-1548: Algorithm Link Support Out of order release of input and output buffers ADASVISION-1549: Algorithm Link Support Memory allocations ADASVISION-1550: Algorithm Link Support DSP subsystem DMA resource allocations ADASVISION-1551: Algorithm Link Support EVE subsystem DMA resource allocations ADASVISION-1552: Algorithm Link Support System DMA resource allocations ADASVISION-1553: Algorithm Link Support In place computation support ADASVISION-1554: Algorithm Link Support Non-In place computation support ADASVISION-1555: Algorithm Link Support Multiple Algos ADASVISION-1556: Algorithm Link Support Alg Configurations ADASVISION-889: 3D SRV on TDA3x "Å" Enhancements ADASVISION-962: TDA3x 3D SRV: Enabling 2A and WDR		
<u>Keywords:</u>	tda3xx-evm tda3xx_rvp		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-135: ISS_3D_2D_SRV_960/964deser			
<u>Summary:</u>			
ISS 2D + 3D SRV UC			
Input : IMI OV10640 / TIDA AR140 / TIDA AR143 with 960/964 deserializer			
Output : HDMI 1080P			
<u>Preconditions:</u>			
Ensure TDA3x folder present in SD card with CHARTPOS.BIN & LENS.BIN			
Run SRV calibration UC if required to generate LUT.BIN			
Verify whether display shows a smooth stitching of all 4 cameras.			
All running at 30fps, Also check performance stats match with datasheet			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as "OV10640 Sensor for SV - IMI (TDA3x ONLY)" or	Capture Source should be OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY)	

	"AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY)"	depending upon the hardware connected & selected by user	
	& Display Output as HDMI 1080P	& Display device as HDMI 1080P	
2	Run "3D + 2D SRV 4CH ISS capture + ISS ISP + DeWarp + Synthesis (DSP1) + Display" UC	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Noise levels should be very low.	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1398: IPC between M4s ADASVISION-1399: IPC between DSPs ADASVISION-1402: IPC between M4 & DSP ADASVISION-1403: IPC between M4 & EVE ADASVISION-1405: IPC between DSP & EVE ADASVISION-1410: shall support link sendcmd across all cores ADASVISION-1466: ISS multi-channel capture ADASVISION-1467: ISS M2M -ISP - GLBCE selection ADASVISION-1468: ISS M2M -ISP - resizer ADASVISION-1469: ISS M2M -ISP - output dataformat ADASVISION-1470: ISS M2M -ISP - input data format ADASVISION-1472: ISS M2M -ISP - WDR modes ADASVISION-1473: ISS M2M -ISP - resizer ADASVISION-1474: ISS M2M -ISP multiple instance ADASVISION-1475: ISS M2M - H3A ADASVISION-1476: ISS M2M sub-frame ADASVISION-1483: ISS M2M RSZ - resizer ADASVISION-1484: ISS M2M RSZ - output dataformat ADASVISION-1485: ISS M2M RSZ - input data format ADASVISION-1487: ISS M2M RSZ - multi-instance ADASVISION-1488: ISS M2M RSZ - multi-instance with ISP M2M ADASVISION-1489: ISS M2M RSZ - multi-CH ADASVISION-1490: Algorithm Link ISS 2A - Auto-exposure using H3A data as input ADASVISION-1491: Algorithm Link ISS 2A - Auto-white balance using H3A data as input ADASVISION-1492: Algorithm Link ISS 2A - Auto-exposure for WDR mode operation using H3A data as input ADASVISION-1493: Algorithm Link ISS 2A - multi-CH mode of operation for H3A for surround view cameras ADASVISION-1503: ESM support ADASVISION-1504: DAP MPU support ADASVISION-1518: Synchronization of frames across multiple channels ADASVISION-1519: duplication of output ADASVISION-1520: Merging of multiple outputs ADASVISION-1701: AR143 (MARs) Camera and Fusion board support on TDA2Px ADASVISION-882: 2D+3D SRV on TDA3x		
<u>Keywords:</u>	tda3xx-evm tda3xx_rvp c_regression c_stress c_qualification c_stability m_iss m_algorithm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-136: ISS_3D_SRV_Rearview_960/964deserSummary:

ISS 3D SRV + Rearview UC

Input : IMI OV10640 / TIDA AR140 with 960 deserializer

or OV10635 with 964 deserializer

Output : HDMI 1080P

Preconditions:

Ensure TDA3x folder present in SD card with CHARTPOS.BIN & LENS.BIN

Run SRV calibration UC if required to generate LUT.BIN

Verify whether display shows a smooth stitching of all 4 cameras.

All running at 30fps, Also check performance stats match with datasheet

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as "OV10640 Sensor for SV - IMI (TDA3x ONLY)" or "AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY)" & Display Output as HDMI 1080P	Capture Source should be OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & selected by user & Display device as HDMI 1080P	
2	Run "3D SRV 4CH ISS capture + ISS ISP + DeWarp + Synthesis (DSP1) + RearView + Display" UC	Display must come up with 3D SRV output & Rear view camera output and no buffer drops should be observed	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1038: TDA3x 3D SRV: 3D + Rear view UC ADASVISION-1397: Rear Camera usecase ADASVISION-1518: Synchronization of frames across multiple channels ADASVISION-1519: duplication of output ADASVISION-1520: Merging of multiple outputs ADASVISION-1521: select a particular channel ADASVISION-1522: Dummy Sink (Null Link) ADASVISION-1523: Dummy source (NullSrc Link) ADASVISION-269: TDA3x: CMS & Rear Camera augmented reality visualization on rear view mirror ADASVISION-830: For all SRV - DSP load optimization using SIMD		
<u>Keywords:</u>	tda3xx-evm tda3xx_rvp		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-144: ISS_3D_SRV_960/964deser_without_TDA3X_Folder

Summary:

ISS 3D SRV UC

Input : IMI OV10640 / TIDA AR140 with 960 deserializer

or OV10635 with 964 deserializer

Output : HDMI 1080P

Preconditions:

Ensure TDA3x folder not present in SD card

Verify whether display shows a smooth stitching of all 4 cameras.

All running at 30fps, Also check performance stats match with datasheet

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as "OV10640 Sensor for SV - IMI (TDA3x ONLY)" or "AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY)" & Display Output as HDMI 1080P	Capture Source should be OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & selected by user & Display device as HDMI 1080P	
2	Run "3D SRV 4CH ISS capture + ISS ISP + DeWarp + Synthesis (DSP1) + Display" UC	It throws error	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1036: TDA3x 3D SRV: 360 degree flyaround (Phase 1) ADASVISION-1037: TDA3x 3D SRV: Improve imaging for SRV with Improve AE stability & Integrate Photometric alignment ADASVISION-1068: TDA3x 3D SRV : Auto calculate number of slice parameters ADASVISION-1069: TDA3c 3D SRV: Lens type : Distortion table ADASVISION-1071: TDA3x 3D SRV : Boot time optimization ADASVISION-1167: Error handling requirements ADASVISION-1526: Error handling ADASVISION-962: TDA3x 3D SRV: Enabling 2A and WDR		
<u>Keywords:</u>	tda3xx-evm tda3xx_rvp		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-321: ISS_3D_SRV_960/964deser_Different_Output_resolution

Summary:

ISS 3D SRV UC

Input : IMI OV10640 / TIDA AR140 with 960 deserializer

or OV10635 with 964 deserializer

Output : HDMI 1080P

Binaries: 512MB & 128MB

Preconditions:

Ensure TDA3x folder present in SD card with CHARTPOS,CARIMG,V2W & LENS.BIN

Using Mesh generation tool generate V2W with resolution same as set in UC

Run SRV calibration UC if required to generate LUT.BIN

Verify whether display shows a smooth stitching of all 4 cameras.

All running at 30fps, Also check performance stats match with datasheet

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Change output resolution for 3D SRV UC & build	User should be able to build for different resolution than default	
2	Go to System Settings Select Capture Source as	Capture Source should be	

	"OV10640 Sensor for SV - IMI (TDA3x ONLY)" or "AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY)" & Display Output as HDMI 1080P	OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & selected by user & Display device as HDMI 1080P	
3	Run "3D SRV 4CH ISS capture + ISS ISP + DeWarp + Synthesis (DSP1) + Display" UC	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Noise levels should be very low.	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1036: TDA3x 3D SRV: 360 degree flyaround (Phase 1) ADASVISION-1037: TDA3x 3D SRV: Improve imaging for SRV with Improve AE stability & Integrate Photometric alignment ADASVISION-1068: TDA3x 3D SRV : Auto calculate number of slice parameters ADASVISION-1069: TDA3x 3D SRV: Lens type : Distortion table ADASVISION-1071: TDA3x 3D SRV : Boot time optimization ADASVISION-1466: ISS multi-channel capture ADASVISION-1467: ISS M2M -ISP - GLBCE selection ADASVISION-1468: ISS M2M -ISP - resizer ADASVISION-1469: ISS M2M -ISP - output dataformat ADASVISION-1470: ISS M2M -ISP - input data format ADASVISION-1472: ISS M2M -ISP - WDR modes ADASVISION-1473: ISS M2M -ISP - resizer ADASVISION-1474: ISS M2M -ISP multiple instance ADASVISION-1475: ISS M2M - H3A ADASVISION-1483: ISS M2M RSZ - resizer ADASVISION-1484: ISS M2M RSZ - output dataformat ADASVISION-1485: ISS M2M RSZ - input data format ADASVISION-1487: ISS M2M RSZ - multi-instance ADASVISION-1488: ISS M2M RSZ - multi-instance with ISP M2M ADASVISION-1489: ISS M2M RSZ - multi-CH ADASVISION-1579: low cost surround view with TDA3x ADASVISION-1606: Algo Link DeWarp for multiple channel LDC correction. ADASVISION-1621: ISS: Capture Link & M2M ISP : Support MIPI RAW 12 dataformat ADASVISION-1643: ISP Based SRV : Split LUT's ADASVISION-1644: ISP Based SRV: Configurable blend seam angle ADASVISION-1645: ISP Based SRV: Configurable blend seam start point ADASVISION-1647: ISP Based SRV: Compression of LUT's ADASVISION-1684: ISP Based SRV: Updated interface of Mesh Generation Tool ADASVISION-1685: ISP Based SRV: Parametric transition between view points ADASVISION-1686: ISP Based SRV: Adaptive bowl support on LDC Surroundview ADASVISION-1687: ISP Based SRV: Compression and reorganization of V2W Table(s) ADASVISION-1688: ISP Based SRV: Generating Car Box Edges/view ADASVISION-1715: [TDA3x 3D SRV]: Add support for Output Resolution change ADASVISION-1761: [TDA3x 3D SRV] Update Mesh tool for output resolution change ADASVISION-830: For all SRV - DSP load optimization using SIMD ADASVISION-889: 3D SRV on TDA3x "Enhancements" ADASVISION-932: TDA3x 3D SRV on 128MB memory map ADASVISION-962: TDA3x 3D SRV: Enabling 2A and WDR		
<u>Keywords:</u>	tda3xx-evm tda3xx_rvp c_qualification		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.3.3.Test Suite : SRV_Calibration

Test Case VISIONSDK-137: SRV_Calibration_UC_auto_calibration

Summary:

SRV Calibration UC supported on TDA2x/TDA2ex/TDA3x

Input : OV10635 with 913/914 deserializer or

Imx290 with 913/914 deserializer or

OV10635 with 964 deserializer or

IMI OV10640 / TIDA AR140 with 960 deserializer

Output : HDMI 1080P (TDA2x/TDA2Ex/TDA3x) , HDMI XGA TDM mode (TDA3x ONLY)

Preconditions:

In case of TDA2x/TDA2Ex:

Ensure TDA2x folder present in SD card with CHARTPOS.BIN,LENS_2D.BIN & LENS.BIN

Run SRV calibration UC to generate PERSMAT.BIN

In case of TDA3x:

Ensure TDA3x folder present in SD card with CHARTPOS.BIN & LENS.BIN

Run SRV calibration UC to generate LUT.BIN

Verify whether display shows a smooth stitching of all 4 cameras.

All running at 30fps, Also check performance stats match with datasheet

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10635 Sensor 720P30 or OV10635 Sensor for Mosaic Display - SAT0088/OV10635 (TDA2EX ONLY) or OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & Display Output as HDMI 1080P (TDA2x/TDA2Ex/TDA3x), HDMI XGA TDM mode (TDA3x ONLY)	Capture Source should be OV10635 Sensor 720P30 or OV10635 Sensor for Mosaic Display - SAT0088/OV10635 (TDA2EX ONLY) or OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & Display device as HDMI 1080P (TDA2x/TDA2Ex/TDA3x), HDMI XGA TDM mode (TDA3x ONLY)	
2	Run "SRV Calibration" UC	Display must come up with mosaic view of all 4 cameras 8 Red color rectangle boxes (2 in each quadrant) should be visible and no buffer drops should be observed	
3	Select Auto Calibration	On selecting Auto calibration It will detect corners for all 4 cameras & generate	

		PERSMAT.BIN (in case of TDA2x/TDA2ex)	
		LUT.BIN (in case of TDA3x)	
4	Run any SRV UC & verify the output	SRV Output should be proper	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1762: SRV Auto calibration - auto selection of ROI for Surround View (1MB Vs 2MB) ADASVISION-854: Support for handling region-of-interest input frame for 3DSRV & 2DSRV use-cases ADASVISION-883: Improved auto-calibration for 2D & 3D ADASVISION-999: Performance: Complex algorithm should work on shadowed buffers		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp c_qualification		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-138: SRV_Calibration_UC_manual_calibrationSummary:

SRV Calibration UC supported on TDA2x/TDA2ex/TDA3x

Input : OV10635 with 913/914 deserializer or

Imx290 with 913/914 deserializer or

OV10635 with 964 deserializer or

IMI OV10640 / TIDA AR140 with 960 deserializer

Output : HDMI 1080P (TDA2x/TDA2Ex/TDA3x) , HDMI XGA TDM mode (TDA3x ONLY)

Preconditions:

In case of TDA2x/TDA2Ex:

Ensure TDA2x folder present in SD card with CHARTPOS.BIN, LENS_2D.BIN & LENS.BIN

Run SRV calibration UC to generate PERSMAT.BIN

In case of TDA3x:

Ensure TDA3x folder present in SD card with CHARTPOS.BIN & LENS.BIN

Run SRV calibration UC to generate LUT.BIN

Verify whether display shows a smooth stitching of all 4 cameras.

All running at 30fps, Also check performance stats match with datasheet

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635 Sensor 720P30 or OV10635 Sensor for Mosaic Display - SAT0088/OV10635 (TDA2EX ONLY) or OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY)	Capture Source should be OV10635 Sensor 720P30 or OV10635 Sensor for Mosaic Display - SAT0088/OV10635 (TDA2EX ONLY) or	

	depending upon the hardware connected & Display Output as HDMI 1080P (TDA2x/TDA2Ex/TDA3x), HDMI XGA TDM mode (TDA3x ONLY)	OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & Display device as HDMI 1080P (TDA2x/TDA2Ex/TDA3x), HDMI XGA TDM mode (TDA3x ONLY)	
2	Run "SRV Calibration" UC	Display must come up with mosaic view of all 4 cameras and no buffer drops should be observe	
3	Select Manual Calibration & generate CALMAT	should be able to generate CALMAT.BIN	
4	Remove the card & refer "VisionSDK_UserGuide_3D_SurroundView_Manual_CalibTool.pdf" useguide to generate PERSMAT.BIN (in case of TDA2x/TDA2ex) & LUT.BIN (in case of TDA3x)	Should be able to generate PERSMAT.BIN (in case of TDA2x/TDA2ex) & LUT.BIN (in case of TDA3x)	
5	Copy the PERSMAT.BIN (in case of TDA2x/TDA2ex) & LUT.BIN (in case of TDA3x) to MMC/SD card & insert into EVM & Run any SRV UC	SRV output should be proper	
<u>Execution type:</u>		Manual	
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-854: Support for handling region-of-interest input frame for 3DSRV & 2DSRV use-cases ADASVISION-984: Calibration: Allow to pass a parameter where all the generated files get read from/written ADASVISION-999: Performance: Complex algorithm should work on shadowed buffers	
<u>Keywords:</u>		tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp	
Execution Details			
Build		REL_3_7	
Tester		x0246581	
<u>Execution Result:</u>		Passed	
<u>Execution Mode:</u>		Manual	
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-139: SRV_Calibration_UC_default_calibrationSummary:

SRV Calibration UC supported on TDA2x/TDA2ex/TDA3x

Input : OV10635 with 913/914 deserializer or

Imx290 with 913/914 deserializer or

OV10635 with 964 deserializer or

IMI OV10640 / TIDA AR140 with 960 deserializer

Output : HDMI 1080P (TDA2x/TDA2Ex/TDA3x) , HDMI XGA TDM mode (TDA3x ONLY)

Preconditions:

In case of TDA2x/TDA2Ex:

Ensure TDA2x folder present in SD card with CHARTPOS.BIN, LENS_2D.BIN & LENS.BIN

Run SRV calibration UC to generate PERSMAT.BIN

In case of TDA3x:

Ensure TDA3x folder present in SD card with CHARTPOS.BIN & LENS.BIN

Run SRV calibration UC to generate LUT.BIN

Verify whether display shows a smooth stitching of all 4 cameras.

All running at 30fps, Also check performance stats match with datasheet

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635 Sensor 720P30 or OV10635 Sensor for Mosaic Display - SAT0088/OV10635 (TDA2EX ONLY) or OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & Display Output as HDMI 1080P (TDA2x/TDA2Ex/TDA3x), HDMI XGA TDM mode (TDA3x ONLY)	Capture Source should be OV10635 Sensor 720P30 or OV10635 Sensor for Mosaic Display - SAT0088/OV10635 (TDA2EX ONLY) or OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & Display device as HDMI 1080P (TDA2x/TDA2Ex/TDA3x), HDMI XGA TDM mode (TDA3x ONLY)	
2	Run "SRV Calibration" UC	Display must come up with mosaic view of all 4 cameras and no buffer drops should be observe	
3	Select Default Calibration	On selecting Default calibration It will generate PERSMAT.BIN (in case of TDA2x/TDA2ex) LUT.BIN (in case of TDA3x)	
4	Run any SRV UC & verify the output	SRV Output should be proper	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-854: Support for handling region-of-interest input frame for 3DSRV & 2DSRV use-cases		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-140: SRV_Calibration_UC_auto_calibration_Dump_FrameSummary:

SRV Calibration UC supported on TDA2x/TDA2ex/TDA3x

Input : OV10635 with 913/914 deserializer or

Imx290 with 913/914 deserializer or

OV10635 with 964 deserializer or

IMI OV10640 / TIDA AR140 with 960 deserializer

Output : HDMI 1080P (TDA2x/TDA2Ex/TDA3x) , HDMI XGA TDM mode (TDA3x ONLY)

Preconditions:

In case of TDA2x/TDA2Ex:

Ensure TDA2x folder present in SD card with CHARTPOS.BIN, LENS_2D.BIN & LENS.BIN

Run SRV calibration UC to generate PERSMAT.BIN

In case of TDA3x:

Ensure TDA3x folder present in SD card with CHARTPOS.BIN & LENS.BIN

Run SRV calibration UC to generate LUT.BIN

Verify whether display shows a smooth stitching of all 4 cameras.

All running at 30fps, Also check performance stats match with datasheet

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10635 Sensor 720P30 or OV10635 Sensor for Mosaic Display - SAT0088/OV10635 (TDA2EX ONLY) or OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & Display Output as HDMI 1080P (TDA2x/TDA2Ex/TDA3x), HDMI XGA TDM mode (TDA3x ONLY)	Capture Source should be OV10635 Sensor 720P30 or OV10635 Sensor for Mosaic Display - SAT0088/OV10635 (TDA2EX ONLY) or OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & Display device as HDMI 1080P (TDA2x/TDA2Ex/TDA3x), HDMI XGA TDM mode (TDA3x ONLY)	
2	Run "SRV Calibration" UC	Display must come up with mosaic view of all 4 cameras and no buffer drops should be observe	
3	Select Auto Calibration	On selecting Auto calibration It will detect corners for all 4 cameras & generate PERSMAT.BIN (in case of TDA2x/TDA2ex) LUT.BIN (in case of TDA3x)	
4	Select "d" to Save Display Frame to MMC/SD card	On selecting "d" Display Frame should be saved to MMC/SD card	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1601: SD card file system support with VSDK		

	ADASVISION-854: Support for handling region-of-interest input frame for 3DSRV & 2DSRV use-cases ADASVISION-883: Improved auto-calibration for 2D & 3D
Keywords:	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp
Execution Details	
Build	REL_3_7
Tester	x0246581
Execution Result:	Passed
Execution Mode:	Manual
Execution duration (sec):	

Test Case VISIONSDK-141: SRV_Calibration_UC_auto_calibration_update_2D_PERSMAT

Summary:

SRV Calibration UC supported on TDA2x/TDA2ex/TDA3x

Input : OV10635 with 913/914 deserializer or

Imx290 with 913/914 deserializer or

OV10635 with 964 deserializer or

IMI OV10640 / TIDA AR140 with 960 deserializer

Output : HDMI 1080P (TDA2x/TDA2Ex/TDA3x) , HDMI XGA TDM mode (TDA3x ONLY)

Preconditions:

In case of TDA2x/TDA2Ex:

Ensure TDA2x folder present in SD card with CHARTPOS.BIN,LENS_2D.BIN & LENS.BIN

Run SRV calibration UC to generate PERSMAT.BIN

In case of TDA3x:

Ensure TDA3x folder present in SD card with CHARTPOS.BIN & LENS.BIN

Run SRV calibration UC to generate LUT.BIN

Verify whether display shows a smooth stitching of all 4 cameras.

All running at 30fps, Also check performance stats match with datasheet

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10635 Sensor 720P30 or OV10635 Sensor for Mosaic Display - SAT0088/OV10635 (TDA2EX ONLY) or OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & Display Output as HDMI 1080P (TDA2x/TDA2Ex/TDA3x), HDMI XGA TDM mode (TDA3x ONLY)	Capture Source should be OV10635 Sensor 720P30 or OV10635 Sensor for Mosaic Display - SAT0088/OV10635 (TDA2EX ONLY) or OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & Display device as HDMI 1080P (TDA2x/TDA2Ex/TDA3x), HDMI XGA TDM mode (TDA3x ONLY)	
2	Run "SRV Calibration" UC	Display must come up with mosaic view of all 4 cameras and no buffer drops should be observe	

3	Select Auto Calibration	On selecting Auto calibration It will detect corners for all 4 cameras & generate PERSMAT.BIN (in case of TDA2x/TDA2ex) LUT.BIN (in case of TDA3x)	
4	Select "7" to Update 2D Pers Mat (after auto/manual calibration if required)	On selecting "7" 2D Pers Mat should be updated	
<u>Execution type:</u>		Manual	
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-854: Support for handling region-of-interest input frame for 3DSRV & 2DSRV use-cases ADASVISION-883: Improved auto-calibration for 2D & 3D	
<u>Keywords:</u>		tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp	
Execution Details			
Build		REL_3_7	
Tester		x0246581	
<u>Execution Result:</u>		Passed	
<u>Execution Mode:</u>		Manual	
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-142: SRV_Calibration_UC_auto_calibration_without MMC_SDSummary:

SRV Calibration UC supported on TDA2x/TDA2ex/TDA3x

Input : OV10635 with 913/914 deserializer or

OV10635 with 964 deserializer or

IMI OV10640 / TIDA AR140 with 960 deserializer

Output : HDMI 1080P (TDA2x/TDA2Ex/TDA3x) , HDMI XGA TDM mode (TDA3x ONLY)

Preconditions:

Boot from QSPI

No MMC/SD card present

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635 Sensor 720P30 or OV10635 Sensor for Mosaic Display - SAT0088/OV10635 (TDA2EX ONLY) or OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & Display Output as HDMI 1080P (TDA2x/TDA2Ex/TDA3x), HDMI XGA TDM mode (TDA3x ONLY)	Capture Source should be OV10635 Sensor 720P30 or OV10635 Sensor for Mosaic Display - SAT0088/OV10635 (TDA2EX ONLY) or OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & Display device as HDMI 1080P (TDA2x/TDA2Ex/TDA3x), HDMI XGA TDM mode (TDA3x ONLY)	
2	Run "SRV Calibration" UC	It throws error	

<u>Execution type:</u>	Manual
<u>Estimated exec. duration (sec):</u>	
<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-854: Support for handling region-of-interest input frame for 3DSRV & 2DSRV use-cases ADASVISION-883: Improved auto-calibration for 2D & 3D
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-143: SRV_Calibration_UC_auto_calibration_without_TDAXX_Folder

Summary:

SRV Calibration UC supported on TDA2x/TDA2ex/TDA3x

Input : OV10635 with 913/914 deserializer or

Imx290 with 913/914 deserializer or

OV10635 with 964 deserializer or

IMI OV10640 / TIDA AR140 with 960 deserializer

Output : HDMI 1080P (TDA2x/TDA2Ex/TDA3x) , HDMI XGA TDM mode (TDA3x ONLY)

Preconditions:

In case of TDA2x/TDA2Ex:

Ensure TDA2x folder not present in SD card

Run SRV calibration UC to generate PERSMAT.BIN

In case of TDA3x:

Ensure TDA3x folder not present in SD card

Run SRV calibration UC to generate LUT.BIN

Verify whether display shows a smooth stitching of all 4 cameras.

All running at 30fps, Also check performance stats match with datasheet

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635 Sensor 720P30 or OV10635 Sensor for Mosaic Display - SAT0088/OV10635 (TDA2EX ONLY) or OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & Display Output as HDMI 1080P	Capture Source should be OV10635 Sensor 720P30 or OV10635 Sensor for Mosaic Display - SAT0088/OV10635 (TDA2EX ONLY) or OV10640 Sensor for SV - IMI (TDA3x ONLY) or AR0140 Sensor for SV - TIDA00262 (TDA3x ONLY) depending upon the hardware connected & Display device as HDMI 1080P (TDA2x/TDA2Ex/TDA3x), HDMI XGA TDM mode (TDA3x ONLY)	

	(TDA2x/TDA2Ex/TDA3x), HDMI XGA TDM mode (TDA3x ONLY)		
2	Run "SRV Calibration" UC	It throws error	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-854: Support for handling region-of-interest input frame for 3DSRV & 2DSRV use-cases ADASVISION-883: Improved auto-calibration for 2D & 3D		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.3.4.Test Suite : FastBoot_SRV

Test Case VISIONSDK-255: FastBoot_ISS_3D_SRV_960/964deser			
<u>Summary:</u>			
ISS 3D SRV UC			
Input : IMI OV10640 with 960/964 deserializer			
Output : HDMI 1080P			
Binaries: 512MB			
<u>Preconditions:</u>			
Build binaries with SRV_FAST_BOOT_INCLUDE=yes			
Ensure TDA3x folder present in SD card with CHARTPOS.BIN & LENS.BIN			
Run SRV calibration UC if required to generate LUT.BIN			
Verify whether display shows a smooth stitching of all 4 cameras.			
All running at 30fps, Also check performance stats match with datasheet			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Boot EVM with Fastboot SRV binaries	EVM should boot with Fastboot SRV binaries & Display should come up no buffer drops should observe	
2	Check Boot time	Boot time should match with release numbers	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1036: TDA3x 3D SRV: 360 degree flyaround (Phase 1) ADASVISION-1037: TDA3x 3D SRV: Improve imaging for SRV with Improve AE stability & Integrate Photometric alignment ADASVISION-1068: TDA3x 3D SRV : Auto calculate number of slice parameters ADASVISION-1069: TDA3c 3D SRV: Lens type : Distortion table ADASVISION-1071: TDA3x 3D SRV : Boot time optimization ADASVISION-830: For all SRV - DSP load optimization using SIMD ADASVISION-889: 3D SRV on TDA3x "Enhancements" ADASVISION-932: TDA3x 3D SRV on 128MB memory map ADASVISION-962: TDA3x 3D SRV: Enabling 2A and WDR		
<u>Keywords:</u>	tda3xx-evm tda3xx_rvp		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.4.Test Suite : Mono_Cam

1.4.1.Test Suite : VIP

1.4.1.1.Test Suite : VIP_SingleCam_Capture_Display

Test Case VISIONSDK-1: VIP_Capture_Display_Input_OV10635_Output_7inch_LCD

Summary:

Capture Display UC

Input : OV10635

Output : 7" LCD

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10635 Sensor & Display Output as 7" LCD	Capture Source should be OV10635 Sensor & Display device as 7" LCD	
2	Run 1 Ch VIP capture + Display UC	Display must come up and no buffer drops should be observed	

Execution type: Automated

Estimated exec. duration (sec): 60.00

Priority: Medium

Requirements

ADASVISION-1274: VIP Capture Link to support Single channel capture
 ADASVISION-1291: VIP Capture Link to support Cropping of output video
 ADASVISION-1305: Display Link - LCD display support
 ADASVISION-1311: Display Link - Color keying support
 ADASVISION-1312: Display Link - Set back Ground Color of VENC
 ADASVISION-1316: Display Link - LCD timing configuration
 ADASVISION-1318: Display Link - VENC section
 ADASVISION-1322: Support OV10635 video sensors
 ADASVISION-1330: support LCD displays
 ADASVISION-1332: Set Brightness levels of LCD display
 ADASVISION-1381: 1CH VIP capture + Display

Keywords:

tda2xx-evm
 tda2ex-evm
 tda3xx-evm
 tda2ex-entry
 tda2px-evm
 m_capture
 m_display

Execution Details

Build REL_3_7

Tester x0246581

Execution Result: **Passed**

Execution Mode: **Manual**

Execution duration (sec):

Test Case VISIONSDK-2: VIP_Capture_Display_Input_OV10635_Output_HDMI_720P

Summary:

Capture Display UC

Input : OV10635

Output : HDMI 720P

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10635 Sensor & Display Output as HDMI 720P	Capture Source shuld be OV10635 Sensor & Display device as HDMI 720P	
2	Run 1 Ch VIP capture + Display UC	Display must come up and no buffer drops should be observe	

Execution type: AutomatedEstimated exec. duration (sec): 60.00Priority: Medium

Requirements

ADASVISION-1279: VIP Capture Link to support Sensor capture
 ADASVISION-1284: VIP Capture Link to support Non-mux Discrete sync Hsync style capture modes
 ADASVISION-1285: VIP Capture Link to support Non-mux Discrete sync ACTVID style capture modes
 ADASVISION-1288: VIP Capture Link to support Progressive mode capture
 ADASVISION-1291: VIP Capture Link to support Cropping of output video
 ADASVISION-1293: VIP Capture Link - Capture HW configuration
 ADASVISION-1295: Display Link support for various input data formats
 ADASVISION-1298: Display Link - Progressive mode display
 ADASVISION-1299: Display Link - Inline scaling support in display
 ADASVISION-1306: Display Link - HDMI display support
 ADASVISION-1307: Display Link - Support for standard display resolutions
 ADASVISION-1311: Display Link - Color keying support
 ADASVISION-1312: Display Link - Set back Ground Color of VENC
 ADASVISION-1317: Display Link - Transparency Color Key Selection support
 ADASVISION-1318: Display Link - VENC section
 ADASVISION-1322: Support OV10635 video sensors
 ADASVISION-1329: Shall support multiple dsplay devices - HDMI (on-chip) & LCD displays
 ADASVISION-1627: DSS Link: support override the input data format of the link.

Keywords:

tda2xx-evm
 tda2ex-evm
 tda3xx-evm
 tda2ex-entry
 tda2px-evm

Execution Details

Build REL_3_7

Tester x0246581

Execution Result: **Passed**Execution Mode: **Manual**Execution duration (sec):**Test Case VISIONSDK-5: VIP_Capture_Display_Input_OV10635_Output_HDMI_1080P**Summary:

Capture Display UC

supported on all platforms

Input : OV10635/OV10640

Output : HDMI 1080P

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

should not change Capture output dynamically

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10635	Capture Source shuld be OV10635 & Display device as HDMI 1080P	

	& Display Output as HDMI 1080P		
2	Run 1 Ch VIP capture + Display UC	Display must come up and no buffer drops should be observe	
3	Check for graphics elements displayed on screen	TI logo should be on left top corner All load bars should be on left bottom corner	
4	Press "P"	Check performance stats Should print CPU Load of all cores, Capture & Display FPS numbers DDR, Heap memory, OCMC, SR1, remote log buffer memory usage	
<u>Execution type:</u>		Automated	
<u>Estimated exec. duration (sec):</u>		60.00	
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1090: Update TI logo ADASVISION-1274: VIP Capture Link to support Single channel capture ADASVISION-1279: VIP Capture Link to support Sensor capture ADASVISION-1281: VIP Capture Link -VIP capture with Dynamic output resolution change will not be supported ADASVISION-1284: VIP Capture Link to support Non-mux Discrete sync Hsync style capture modes ADASVISION-1285: VIP Capture Link to support Non-mux Discrete sync ACTVID style capture modes ADASVISION-1287: VIP Capture Link to support 8 bit, 16bit & 24bit Capture bus width ADASVISION-1288: VIP Capture Link to support Progressive mode capture ADASVISION-1298: Display Link - Progressive mode display ADASVISION-1301: Display Link - Dynamic resolution change of input video ADASVISION-1303: Display Link - Dynamic output image resolution change ADASVISION-1306: Display Link - HDMI display support ADASVISION-1309: Display Link - Blending support of Grpx and Video planes ADASVISION-1310: Display Link - Blending support for Video planes ADASVISION-1311: Display Link - Color keying support ADASVISION-1312: Display Link - Set back Ground Color of VENC ADASVISION-1318: Display Link - VENC section ADASVISION-1322: Support OV10635 video sensors ADASVISION-1329: Shall support multiple dsisplay devices - HDMI (on-chip) & LCD displays ADASVISION-1381: 1CH VIP capture + Display ADASVISION-1429: Capture + Display generic usecase using OV10640 ADASVISION-1529: Multiple heap support ADASVISION-1530: Cache configuration ADASVISION-1531: Memory config ADASVISION-1532: External Memory allocation ADASVISION-1533: Internal memory allocation from OCMC ADASVISION-1534: Internal memory allocation from DSP L2 SRAM at create time only, no run time allocation and de-alloc ADASVISION-1535: Internal memory allocation from DSP L1 SRAM ADASVISION-1581: TDA2Ex - shall support single channel capture ADASVISION-1584: Shall support all the Bios single multi camera usecases which use one DSP & M4 ADASVISION-1604: Support sensor frame work	
<u>Keywords:</u>		tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm c_stress c_performance c_qualification c_stability	
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-112: VIP_Capture_Display_Input_OV10635_Output_10inch_LCDSummary:

Capture Display UC

Input : OV10635

Output : 10" LCD

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635 Sensor & Display Output as 10" LCD	Capture Source should be OV10635 Sensor & Display device as 10" LCD	
2	Run 1 Ch VIP capture + Display UC	Display must come up and no buffer drops should be observe	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1274: VIP Capture Link to support Single channel capture ADASVISION-1305: Display Link - LCD display support ADASVISION-1329: Shall support multiple display devices - HDMI (on-chip) & LCD displays		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm c_regression c_integration		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-113: VIP_Capture_Display_Input_OV10635_Output_10inch_OSD_LCDSummary:

Capture Display UC

Input : OV10635

Output : 10" OSD LCD

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635 Sensor & Display Output as 10" OSD LCD	Capture Source should be OV10635 Sensor & Display device as 10" OSD LCD	
2	Run 1 Ch VIP capture + Display UC	Display must come up and no buffer drops should be observe	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1274: VIP Capture Link to support Single channel capture		

	ADASVISION-1305: Display Link - LCD display support
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-114: VIP_Capture_Display_Input_OV10635_Output_SD_PALSummary:

Capture Display UC

Input : OV10635

Output : SD PAL

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635 Sensor & Display Output as SD PAL	Capture Source should be OV10635 Sensor & Display device as SD PAL	
2	Run 1 Ch VIP capture + Display UC	Display must come up and no buffer drops should be observe	

Execution type: AutomatedEstimated exec. duration (sec): 60.00Priority: Medium

Requirements

ADASVISION-1274: VIP Capture Link to support Single channel capture
 ADASVISION-1279: VIP Capture Link to support Sensor capture
 ADASVISION-1284: VIP Capture Link to support Non-mux Discrete sync Hsync style capture modes
 ADASVISION-1285: VIP Capture Link to support Non-mux Discrete sync ACTVID style capture modes
 ADASVISION-1287: VIP Capture Link to support 8 bit, 16bit & 24bit Capture bus width
 ADASVISION-1289: VIP Capture Link to support Interlace mode capture
 ADASVISION-1295: Display Link support for various input data formats
 ADASVISION-1297: Display Link - Interlace mode display
 ADASVISION-1307: Display Link - Support for standard display resolutions
 ADASVISION-1320: Display Link - SDDAC

Keywords: tda3xx-evm**Execution Details**

Build REL_3_7

Tester x0246581

Execution Result: **Passed**Execution Mode: **Manual**Execution duration (sec):**Test Case VISIONSDK-115: VIP_Capture_Display_Input_OV10635_Output_SD_NTSC**Summary:

Capture Display UC

Input : OV10635

Output : SD NTSC

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10635 Sensor & Display Output as SD NTSC	Capture Source should be OV10635 Sensor & Display device as SD NTSC	
2	Run 1 Ch VIP capture + Display UC	Display must come up and no buffer drops should be observed	
Execution type:	Automated		
Estimated exec. duration (sec):	60.00		
Priority:	Medium		
Requirements	ADASVISION-1284: VIP Capture Link to support Non-mux Discrete sync Hsync style capture modes ADASVISION-1287: VIP Capture Link to support 8 bit, 16bit & 24bit Capture bus width ADASVISION-1289: VIP Capture Link to support Interlace mode capture ADASVISION-1295: Display Link support for various input data formats ADASVISION-1297: Display Link - Interlace mode display ADASVISION-1307: Display Link - Support for standard display resolutions ADASVISION-1320: Display Link - SDDAC		
Keywords:	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

Test Case VISIONSDK-296: VIP_Capture_Display_without_SensorSummary:

Capture Display UC without sensor connected

supported on all platforms

Input : No Sensor connected

Output : HDMI 1080P

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

None of the sensors are connected

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P	Capture Source shuld be OV10635 & Display device as HDMI 1080P	
2	Run 1 Ch VIP capture + Display UC	Assert with sensor initialization fails	
Execution type:	Manual		
Estimated exec. duration (sec):			
Priority:	Medium		
Requirements	ADASVISION-1167: Error handling requirements ADASVISION-1526: Error handling		
Keywords:	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm		
Execution Details			

Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

1.4.1.2.Test Suite : VIP_Capture_FrameCopy_Display

Test Case VISIONSDK-7: VIP_Capture_FrameCopy_DSP1_Display

Summary:

Capture FrameCopy Display UC on DSP1

Input : OV10635

Output : HDMI 1080P

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P	Capture Source should be OV10635 & Display device as HDMI 1080P	
2	Run 1 Ch VIP capture + FrameCopy (DSP1) + Display UC	Display must come up and no buffer drops should be observe	
Execution type:	Automated		
Estimated exec. duration (sec):	60.00		
Priority:	Medium		
Requirements	ADASVISION-1382: 1CH VIP capture + Alg Frame Copy (DSP1) + Display ADASVISION-1550: Algorithm Link Support DSP subsystem DMA resource allocations ADASVISION-1557: Support Sample Algorithm Link with separate input output buffers (Frame Copy Plug-Ins) ADASVISION-1584: Shall support all the Bios single multi camera usecases which use one DSP & M4		
Keywords:	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm c_regression c_qualification m_algorithm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

Test Case VISIONSDK-8: VIP_Capture_FrameCopy_EVE1_Display			
<u>Summary:</u>			
Capture FrameCopy Display UC on EVE1			
Input : OV10635			
Output : HDMI 1080P			
<u>Preconditions:</u>			
Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>

1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P	Capture Source should be OV10635 & Display device as HDMI 1080P	
2	Run 1 Ch VIP capture + FrameCopy (EVE1) + Display UC	Display must come up and no buffer drops should be observe	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1383: 1CH VIP capture + Alg Frame Copy (EVE1)+ Display ADASVISION-1551: Algorithm Link Support EVE subsystem DMA resource allocations ADASVISION-1557: Support Sample Algorithm Link with separate input output buffers (Frame Copy Plug-Ins)		
<u>Keywords:</u>	tda2xx-evm tda3xx-evm tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.4.1.3.Test Suite : VIP_Capture_SubFrameCopy_Display

Test Case VISIONSDK-168: VIP_Capture_SubFrameCopy_EVE1_Display			
<u>Summary:</u>			
Capture Sub Frame Copy Display UC with EVE1			
Input : OV10635			
Output : HDMI 1080P			
<u>Preconditions:</u>			
Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P	Capture Source should be OV10635 & Display device as HDMI 1080P	
2	Run 1 Ch VIP capture + SubFrameCopy (EVE1) + Display UC	Display must come up and no buffer drops should be observe	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1292: VIP Capture Link to support Slice/sub-frame wise capture		
<u>Keywords:</u>	tda2xx-evm tda3xx-evm tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.4.1.4.Test Suite : VIP_Capture_IPC_Display

Test Case VISIONSDK-230: VIP_Capture_IPC_Display_Single_coreSummary:

Capture IPC Display UC with Single core

supported on TDA2x/TDA2Ex/TDA3x

Input : OV10635 Sensor

Output : HDMI 1080P

Scenrios:

IPU1_0 -> DSP1 -> IPU1_0

IPU1_0 -> DSP2 -> IPU1_0

IPU1_0 -> EVE1 -> IPU1_0

IPU1_0 -> EVE2 -> IPU1_0

IPU1_0 -> EVE3 -> IPU1_0

IPU1_0 -> EVE4 -> IPU1_0

IPU1_0 -> IPU1_1 -> IPU1_0

IPU1_0 -> A15 -> IPU1_0

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Run Testsuite	Check Logs of Capture IPC Display UC Capture should be running on IPU1-0 at 30fps and Display should be running on IPU1-0 at 60fps	

Execution type: Manual

Estimated exec. duration (sec):

Priority: Medium

Requirements

ADASVISION-1398: IPC between M4s
 ADASVISION-1399: IPC between DSPs
 ADASVISION-1400: IPC between EVEs
 ADASVISION-1401: IPC between M4 & A15
 ADASVISION-1402: IPC between M4 & DSP
 ADASVISION-1403: IPC between M4 & EVE
 ADASVISION-1404: IPC between DSP & A15
 ADASVISION-1405: IPC between DSP & EVE
 ADASVISION-1406: IPC between EVE & A15

Keywords:

tda2xx-evm
 tda2ex-evm
 tda3xx-evm
 tda2ex-entry
 tda2px-evm
 m_ipc

Execution Details

Build REL_3_7

Tester x0246581

Execution Result: **Passed**

Execution Mode: **Manual**

Execution duration (sec):

Test Case VISIONSDK-231: VIP_Capture_IPC_Display_Multi_coreSummary:

Capture IPC Display UC with Multi core

supported on TDA2x/TDA2Ex/TDA3x

Input : OV10635 Sensor

Output : HDMI 1080P

Scenarios:

IPU1_0 -> DSP1 -> IPU1_1 -> DSP2 -> IPU1_0

IPU1_0 -> EVE1 -> DSP1 -> A15_0 -> DSP1 -> IPU1_0

IPU1_0 -> EVE1 -> DSP1 -> A15_0 -> IPU1_0

IPU1_0 -> A15_0 -> DSP1 -> DSP2 -> IPU1_1 -> EVE1 -> IPU1_0

IPU1_0 -> EVE1 -> DSP1 -> EVE2 -> DSP2 -> EVE3 -> A15_0 -> IPU1_1 -> EVE4 (Repeated twice) -> IPU1_0

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Run Testsuite	Check Logs of Capture IPC Display UC Capture should be running on IPU1-0 at 30fps and Display should be running on IPU1-0 at 60fps	

Execution type: ManualEstimated exec. duration (sec):Priority: Medium

Requirements

ADASVISION-1398: IPC between M4s
 ADASVISION-1399: IPC between DSPs
 ADASVISION-1400: IPC between EVEs
 ADASVISION-1401: IPC between M4 & A15
 ADASVISION-1402: IPC between M4 & DSP
 ADASVISION-1403: IPC between M4 & EVE
 ADASVISION-1404: IPC between DSP & A15
 ADASVISION-1405: IPC between DSP & EVE
 ADASVISION-1406: IPC between EVE & A15
 ADASVISION-1410: shall support link sendcmd across all cores

Keywords:

tda2xx-evm
 tda2ex-evm
 tda3xx-evm
 tda2ex-entry
 tda2px-evm

Execution Details

Build REL_3_7

Tester x0246581

Execution Result: **Passed**Execution Mode: **Manual**Execution duration (sec):**1.4.1.5.Test Suite : VIP_Capture_Color_To_Gray_Display****Test Case VISIONSDK-167: VIP_Capture_Color_To_Gray_Display**Summary:

Single Cam Capture Color to Gray Display UC

supported on TDA2x/TDA2Ex/TDA3x

Input : OV10635 Sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Run Testsuite	Check Logs of Capture Color to Gray Display UC Capture should be running on IPU1-0 at 30fps and display should be running on IPU1-0 at 60fps	

Execution type: ManualEstimated exec. duration (sec):

<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-1553: Algorithm Link Support In place computation support ADASVISION-1558: Support Sample Algorithm Link (Color to Gray Plug-Ins) with inplace buffer processing
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

1.4.1.6.Test Suite : VIP_Capture_DSSWB_Display

Test Case VISIONSDK-179: VIP_Capture_DSSWB_CRC_Display			
<u>Summary:</u> Single Cam Capture DSSWB CRC Display UC supported on TDA3x Input : OV10635 Sensor Output : HDMI 1080P			
<u>Preconditions:</u> Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P	Capture Source should be OV10635 & Display device as HDMI 1080P	
2	Run "1CH VIP capture + DSSWB + CRC + Display (Supported only on TDA3x)" UC	Display must come up & no buffer drop should be observed	
3	Pause the video Play the video	After pause, frame freeze event detect should be displayed On resume, frame freeze event detect display should be erased	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1264: DSS M2M link in VSDK to support overlay write back ADASVISION-1283: VIP Capture Link to support DSS write back capture ADASVISION-1507: CRC support ADASVISION-1589: Support Frame Freeze detection with TDA3x using Display write back & CRC		
<u>Keywords:</u>	tda3xx-evm c_qualification		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-180: VIP_Capture_DisplayMultiPipe_DSSWB_Metadata

<u>Summary:</u> Single Cam Capture Display MultiPipe DSSWB Metadata UC

supported on TDA3x

Input : OV10635 Sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P	Capture Source should be OV10635 & Display device as HDMI 1080P	
2	Run "1CH VIP capture + DisplayMultiPipe + DSSWb + Metadata" UC	Display must come up & no buffer drop should be observed	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1136: New display Module supporting multiple display sync'd pipes ADASVISION-1319: Display DSS write back Link		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.4.1.7.Test Suite : VIP_Capture_VPE_Display**Test Case VISIONSDK-189: VIP_Capture_VPE_Display**Summary:

Single Cam Capture VPE Display UC

supported on TDA2x/TDA2Ex/TDA3x

Input : OV10635 Sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Run Testsuite	Check Logs of Capture VPE Display UC Capture should be running on IPU1-0 at 30fps and display should be running on IPU1-0 at 60fps	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1369: VPE link to support scaling of input video ADASVISION-1370: VPE link to support de-interlacing ADASVISION-1371: VPE link to support multiple output queues ADASVISION-1372: VPE link to support Multi instance ADASVISION-1373: VPE link to support input type progressive ADASVISION-1374: VPE link to support various Input Data Formats ADASVISION-1375: VPE link to support various output data format ADASVISION-1376: VPE link to support De-interlaced enable/disable ADASVISION-1377: VPE link to support input resolution change ADASVISION-1378: VPE link to support output resolution change ADASVISION-1379: VPE link to support frame rate down sampling		
<u>Keywords:</u>	tda2xx-evm		

	tda2ex-evm tda2ex-entry tda2px-evm m_vpe
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

1.4.1.8.Test Suite : VIP_SingleCam_Capture_Analytics_Display

Test Case VISIONSDK-9: VIP_Capture_Edge_detect_Display			
<u>Summary:</u>			
VIP Capture Edge Detect Display UC with EVE1			
Input : OV10635			
Output : HDMI 1080P			
<u>Preconditions:</u>			
Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P	Capture Source should be OV10635 & Display device as HDMI 1080P	
2	Run 1 Ch VIP capture + Edge Detect (EVE1) + Display UC	Display must come up and no buffer drops should be observe	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1385: 1CH VIP capture + Edge Detect (EVE1) + Display		
<u>Keywords:</u>	tda2xx-evm tda3xx-evm tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-10: VIP_Capture_DOF_1Pyramid_Display			
<u>Summary:</u>			
VIP Capture DOF Display UC with 1 Pyramid			
Input : OV10635			
Output : HDMI 1080P			
<u>Preconditions:</u>			
Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635	Capture Source should be OV10635 & Display device as HDMI 1080P	

	& Display Output as HDMI 1080P		
2	Run 1 Ch VIP capture + Dense Optical Flow (EVEEx) + Display UC with 1 Pyramid	Display must come up and no buffer drops should be observe	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1386: 1CH HDMI capture + Dense Optical Flow (EVEEx) + Display ADASVISION-1554: Algorithm Link Support Non-In place computation support		
<u>Keywords:</u>	tda2xx-evm tda3xx-evm tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-11: VIP_Capture_DOF_2Pyramid_Display

Summary:

VIP Capture DOF Display UC with 2 Pyramid

Input : OV10635

Output : HDMI 1080P

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P	Capture Source shuld be OV10635 & Display device as HDMI 1080P	
2	Run 1 Ch VIP capture + Dense Optical Flow (EVEEx) + Display UC with 2 Pyramid	Display must come up and no buffer drops should be observe	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1386: 1CH HDMI capture + Dense Optical Flow (EVEEx) + Display		
<u>Keywords:</u>	tda2xx-evm tda3xx-evm tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.4.1.9.Test Suite : VIP_Capture_Display_IPU_SMP_BIOS

Test Case VISIONSDK-342: VIP_Capture_Display_Input_OV10635_Output_HDMI_1080P

Summary:

Capture Display UC with IPU SMP BIOS

supported on TDA3x

Input : OV10635

Output : HDMI 1080P

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

Binaries should be built with IPU_SMP_BIOS=yes

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P	Capture Source should be OV10635 & Display device as HDMI 1080P	
2	Run 1 Ch VIP capture + Display UC	Display must come up and no buffer drops should be observe	
3	Run other available UCs	Should be able to run UCs without any issues	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1835: Enable SMP support for IPU1_0 and IPU1_1		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.4.2.Test Suite : HDMI

1.4.2.1.Test Suite : HDMI_Capture_Display

Test Case VISIONSDK-3: HDMI_Capture_Display_Input_HDMI_Output_LCD

Summary:

Capture Display UC

Input : HDMI

Output : LCD

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as HDMI & Display Output as LCD	Capture Source should be HDMI & Display device as LCD	
2	Run 1 Ch VIP capture + Display UC	Display must come up and no buffer drops should be observe	
Execution type:	Automated		
Estimated exec. duration (sec):	60.00		
Priority:	Medium		
Requirements	ADASVISION-1278: VIP Capture Link to support HDMI capture ADASVISION-1305: Display Link - LCD display support ADASVISION-1323: capture from HDMI source ADASVISION-1330: support LCD displays ADASVISION-1331: support for HDMI (off chip) via ADV chip		
Keywords:	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm c_regression m_capture m_display		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

Test Case VISIONSDK-4: HDMI_Capture_Display_Input_HDMI_Output_HDMI

Summary:

Capture Display UC

Input : HDMI

Output : HDMI

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

#:	Step actions:	PASS/FAIL Criteria:	Execution
----	---------------	---------------------	-----------

			<u>Status:</u>
1	Go to System Settings Select Capture Source as HDMI & Display Output as HDMI	Capture Source should be HDMI & Display device as HDMI	
2	Run 1 Ch VIP capture + Display UC	Display must come up and no buffer drops should be observe	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1278: VIP Capture Link to support HDMI capture ADASVISION-1286: VIP Capture Link to support Non-mux Embedded sync capture modes ADASVISION-1287: VIP Capture Link to support 8 bit, 16bit & 24bit Capture bus width ADASVISION-1288: VIP Capture Link to support Progressive mode capture ADASVISION-1296: Display Link - Display support for ARGB 16/24/32 bit data formats ADASVISION-1298: Display Link - Progressive mode display ADASVISION-1300: Display Link - Video window positioning support ADASVISION-1302: Display Link - Active video channel selection ADASVISION-1306: Display Link - HDMI display support ADASVISION-1315: Display Link - Digital Output data format with discrete sync ADASVISION-1318: Display Link - VENC section ADASVISION-1323: capture from HDMI source ADASVISION-1331: support for HDMI (off chip) via ADV chip		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm c_qualification c_integration		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.4.2.2.Test Suite : HDMI_Capture_Analytics_Display

Test Case VISIONSDK-14: HDMI_Capture_SOF_Display			
<u>Summary:</u>			
HDMI Capture SOF Display UC			
Input : HDMI			
Output : HDMI			
<u>Preconditions:</u>			
Verify whether display shows flow vectors of the captured input Also check performance stats match with datasheet			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as HDMI & Display Output as HDMI 1080P	Capture Source should be HDMI & Display device as HDMI 1080P	
2	Run 1CH VIP capture (HDMI) + Sparse Optical Flow (EVE1) + Display UC	Display must come up and no buffer drops should be observe Flow vectors of the captured input should be displayed	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		

<u>Requirements</u>	ADASVISION-1389: 1CH HDMI capture + Sparse Optical Flow (EVE) + Display
<u>Keywords:</u>	tda2xx-evm tda3xx-evm tda2px-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-15: HDMI_Capture_LD_DisplaySummary:

HDMI Capture Lane Detect Display UC

Input : HDMI

Output : HDMI 1080P

Preconditions:

Verify whether display shows a smooth stitching of the single cam views Lane detection
All running at 30fps, Also check performance stats match with datasheet

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as HDMI & Display Output as HDMI 1080P	Capture Source should be HDMI & Display device as HDMI 1080P	
2	Run 1CH VIP capture (HDMI) + Lane Detect (DSP1 + EVE1) + Display UC	Display must come up and no buffer drops should be observe	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1391: 1CH HDMI capture + Lane Detection (DSP+EVE) + Display		
<u>Keywords:</u>	tda2xx-evm tda3xx-evm tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-16: HDMI_Capture_TLR_DisplaySummary:

HDMI Capture Traffic Light Display UC

Input : HDMI

Output : HDMI 1080P

Preconditions:

Verify whether display shows a smooth stitching of the single cam views Traffic Light detection
All running at 30fps, Also check performance stats match with datasheet

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as HDMI	Capture Source should be HDMI & Display device as HDMI 1080P	

	& Display Output as HDMI 1080P		
2	Run 1CH VIP capture (HDMI) + Traffic Light Recognition (TLR) (DSP1) + Display UC	Display must come up and no buffer drops should be observe	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1278: VIP Capture Link to support HDMI capture ADASVISION-1323: capture from HDMI source ADASVISION-1331: support for HDMI (off chip) via ADV chip		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-17: HDMI_Capture_PD_DisplaySummary:

HDMI Capture Pedestrian Detect Display UC

Input : HDMI

Output : HDMI 1080P

Preconditions:

Verify whether display shows a smooth stitching of the single cam views Pedestrian detection
All running at 30fps, Also check performance stats match with datasheet

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as HDMI & Display Output as HDMI 1080P	Capture Source should be HDMI & Display device as HDMI 1080P	
2	Run 1CH VIP capture (HDMI) + PD + Display UC	Display must come up and no buffer drops should be observe	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1390: 1CH HDMI capture + Pedestrian Detection (EVE+DSP) + Display ADASVISION-2129: Update OD demo to provide adaboost weights externally		
<u>Keywords:</u>	tda2xx-evm tda3xx-evm tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-18: HDMI_Capture_TSR_DisplaySummary:

HDMI Capture Traffic Sign Detect Display UC

Input : HDMI

Output : HDMI 1080P

Preconditions:

Verify whether display shows a smooth stitching of the single cam views Traffic Sign detection
All running at 30fps, Also check performance stats match with datasheet

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as HDMI & Display Output as HDMI 1080P	Capture Source should be HDMI & Display device as HDMI 1080P	
2	Run 1CH VIP capture (HDMI) + TSR + Display UC	Display must come up and no buffer drops should be observe	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1392: 1CH HDMI capture + Traffic sign detection (DSP1 + DSP2) + Display ADASVISION-2129: Update OD demo to provide adaboost weights externally		
<u>Keywords:</u>	tda2xx-evm tda3xx-evm tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-19: HDMI_Capture_VD_DisplaySummary:

HDMI Capture Vehicle Detect Display UC

Input : HDMI

Output : HDMI 1080P

Preconditions:

Verify whether display shows a smooth stitching of the single cam views Vehicle detection
All running at 30fps, Also check performance stats match with datasheet

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as HDMI & Display Output as HDMI 1080P	Capture Source should be HDMI & Display device as HDMI 1080P	
2	Run 1CH VIP capture (HDMI) + VD + Display UC	Display must come up and no buffer drops should be observe	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1278: VIP Capture Link to support HDMI capture ADASVISION-1323: capture from HDMI source ADASVISION-2129: Update OD demo to provide adaboost weights externally		
<u>Keywords:</u>	tda2xx-evm tda3xx-evm tda2px-evm		
Execution Details			
Build	REL_3_7		

Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-20: HDMI_Capture_PD_TSR_VD_DisplaySummary:

HDMI Capture Pedestrian, Traffic Sign, Vehicle Detect Display UC

Input : HDMI

Output : HDMI 1080P

Preconditions:

Verify whether display shows a smooth stitching of the single cam views Pedestrian, Traffic Sign, Vehicle Detect
All running at 30fps, Also check performance stats match with datasheet

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as HDMI & Display Output as HDMI 1080P	Capture Source should be HDMI & Display device as HDMI 1080P	
2	Run 1CH VIP capture (HDMI) + PD+TSR+VD + Display UC	Display must come up and no buffer drops should be observe	
Execution type:	Automated		
Estimated exec. duration (sec):	60.00		
Priority:	Medium		
Requirements	ADASVISION-1555: Algorithm Link Support Multiple Algos ADASVISION-2129: Update OD demo to provide adaboost weights externally		
Keywords:	tda2xx-evm tda3xx-evm tda2px-evm m_algorithm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

Test Case VISIONSDK-21: HDMI_Capture_FrontCam_Analytics_DisplaySummary:

HDMI Capture FrontCam Analytics Display UC

Input : HDMI

Output : HDMI 1080P

Preconditions:

Verify whether display shows a smooth stitching of the single cam views PD+TSR+VD+LD+TLR+SFM
All running at 15fps, Also check performance stats match with datasheet

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as HDMI & Display Output as HDMI 1080P	Capture Source should be HDMI & Display device as HDMI 1080P	
2	Run 1CH VIP capture (HDMI) + FrontCam Analytics 2 (PD+TSR+VD+LD+TLR+SFM) (DSPx, EVEx) + Display UC	Display must come up and no buffer drops should be observe	

<u>Execution type:</u>	Automated
<u>Estimated exec. duration (sec):</u>	60.00
<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-1380: Support ISS based Multi scale (pyramid generation for PD/TSR etc) ADASVISION-1486: ISS M2M RSZ - Multi scale (pyramid generation for PD/TSR etc) ADASVISION-1542: Algorithm Link Support (Framework and Skeleton portion) ADASVISION-1543: Algorithm Link Support for all CPU cores ADASVISION-1544: Algorithm Link Support Prioritization ADASVISION-1545: Algorithm Link Support Multiple instantiation ADASVISION-1546: Algorithm Link Support Multiple input and output queues ADASVISION-1547: Algorithm Link Support Multiple input channels ADASVISION-1548: Algorithm Link Support Out of order release of input and output buffers ADASVISION-1549: Algorithm Link Support Memory allocations ADASVISION-1555: Algorithm Link Support Multiple Algos ADASVISION-1556: Algorithm Link Support Alg Configurations ADASVISION-1602: Support Image pyramid using ISS ADASVISION-1603: support for Image pyramid using VPE ADASVISION-1607: EU-NCAP demo support with TDA2X/3X
<u>Keywords:</u>	tda2xx-evm tda3xx-evm tda2px-evm c_stress c_stability m_algorithm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

1.4.3.Test Suite : ISS

1.4.3.1.Test Suite : ISS_SingleCam_Capture_Display_AR140

Test Case VISIONSDK-24: ISS_Capture_AR140_LM

Summary:

Linear mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/Display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source shuld be AR140 & Display device as HDMI 1080P	
2	Run "1CH ISS capture + ISS ISP + ISS LDC+VTNF + Display" UC	Display must come up and no buffer drops should be observed Exposure and colors should look correct. Most important - white/grey objects should not have any color cast	

Execution type: Automated

Estimated exec. duration (sec): 60.00

Priority: Medium

Requirements
 ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display
 ADASVISION-1436: Basic Capture + ISP processing + display use case
 ADASVISION-1461: ISS capture - packing
 ADASVISION-1464: ISS capture -non OTF mode - output dataformat
 ADASVISION-1465: ISS capture -OTF and non-OTF mode - input data format
 ADASVISION-1587: TDA3x ISS UC - SDK links and Utils to support static memory allocation
 ADASVISION-1604: Support sensor frame work

Keywords:
 tda3xx-evm
 c_qualification
 c_integration

Execution Details

Build: REL_3_7

Tester: x0246581

Execution Result: **Passed**

Execution Mode: **Manual**

Execution duration (sec):

Test Case VISIONSDK-25: ISS_Capture_AR140_LM_Performance

Summary:

Linear mode - basic ISS, performance test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source should be AR140 & Display device as HDMI 1080P	
2	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed	
3	Press "P" & check for FPS	FPS should be in the range 29.5 - 30.5	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Parallel capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1456: ISS capture - mode		
<u>Keywords:</u>	tda3xx-evm c_regression c_performance m_iss		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-26: ISS_Capture_AR140_LM_Dynamic_RangeSummary:

Linear mode - dynamic range test

ISS Single channel Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source should be AR140 & Display device as HDMI 1080P	
2	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. AE should adjust such that lowlights are visible and highlights are overexposed.	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Parallel capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1456: ISS capture - mode		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		

Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-27: ISS_Capture_AR140_1PASS_WDRSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source shuld be AR140 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 1 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	

Execution type: AutomatedEstimated exec. duration (sec): 60.00Priority: Medium

Requirements

ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display
 ADASVISION-1456: ISS capture - mode
 ADASVISION-1472: ISS M2M -ISP - WDR modes

Keywords: tda3xx-evm**Execution Details**

Build REL_3_7

Tester x0246581

Execution Result: **Passed**Execution Mode: **Manual**Execution duration (sec):**Test Case VISIONSDK-29: ISS_Capture_AR140_2PASS_WDR**Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR140	Capture Source shuld be AR140 & Display device as HDMI 1080P	

	& Display Output as HDMI 1080P		
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes		
<u>Keywords:</u>	tda3xx-evm c_stress c_stability		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-31: ISS_Capture_AR140_2PASS_WDR_PerformanceSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source shuld be AR140 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed	
4	Press "P" & check for FPS	FPS should be in the range 29.5 - 30.5	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		

<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-32: ISS_Capture_AR140_2PASS_WDR_Dynamic_RangeSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source shuld be AR140 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct in dark as well as bright regions. Dark regions maybe noisier than bright regions but NSF effect should be visible.	

Execution type: ManualEstimated exec. duration (sec):Priority: Medium

Requirements

ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display
 ADASVISION-1456: ISS capture - mode
 ADASVISION-1472: ISS M2M -ISP - WDR modes

Keywords: tda3xx-evm**Execution Details**

Build REL_3_7

Tester x0246581

Execution Result: **Passed**Execution Mode: **Manual**Execution duration (sec):**Test Case VISIONSDK-33: ISS_Capture_AR140_2PASS_WDR_AE**Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings	Capture Source shuld be AR140	

	Select Capture Source as AR140 & Display Output as HDMI 1080P	& Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Noise levels should be very low. Moving to dark scene should cause AE adjustment and increase in noise level.	
<u>Execution type:</u>		Manual	
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes ADASVISION-1490: Algorithm Link ISS 2A - Auto-exposure using H3A data as input ADASVISION-1491: Algorithm Link ISS 2A - Auto-white balance using H3A data as input ADASVISION-1492: Algorithm Link ISS 2A - Auto-exposure for WDR mode operation using H3A data as input	
<u>Keywords:</u>		tda3xx-evm	
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-34: ISS_Capture_AR140_2PASS_WDR_VTNFSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source shuld be AR140 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = ON, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Preview maybe noisy. Toggling between VTNF (0/1) should have visible impact on temporal noise.	
<u>Execution type:</u>		Automated	
<u>Estimated exec. duration (sec):</u>		60.00	
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1456: ISS capture - mode ADASVISION-1457: ISS capture - interface	

	ADASVISION-1459: ISS capture - resolution ADASVISION-1467: ISS M2M -ISP - GLBCE selection ADASVISION-1468: ISS M2M -ISP - resizer ADASVISION-1469: ISS M2M -ISP - output dataformat ADASVISION-1470: ISS M2M -ISP - input data format ADASVISION-1472: ISS M2M -ISP - WDR modes ADASVISION-1473: ISS M2M -ISP - resizer ADASVISION-1475: ISS M2M - H3A ADASVISION-1479: ISS M2M (LDC + VTNF) - VTNF data format ADASVISION-1481: ISS M2M (LDC + VTNF) - VTNF create time config ADASVISION-1483: ISS M2M RSZ - resizer ADASVISION-1484: ISS M2M RSZ - output dataformat ADASVISION-1485: ISS M2M RSZ - input data format ADASVISION-1490: Algorithm Link ISS 2A - Auto-exposure using H3A data as input ADASVISION-1491: Algorithm Link ISS 2A - Auto-white balance using H3A data as input ADASVISION-1492: Algorithm Link ISS 2A - Auto-exposure for WDR mode operation using H3A data as input
<u>Keywords:</u>	tda3xx-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-36: ISS_Capture_AR140_2PASS_WDR_LDCSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source shuld be AR140 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed Preview must look undistorted	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		

Requirements

ADASVISION-1456: ISS capture - mode
 ADASVISION-1457: ISS capture - interface
 ADASVISION-1459: ISS capture - resolution
 ADASVISION-1467: ISS M2M -ISP - GLBCE selection
 ADASVISION-1468: ISS M2M -ISP - resizer
 ADASVISION-1469: ISS M2M -ISP - output dataformat
 ADASVISION-1470: ISS M2M -ISP - input data format
 ADASVISION-1472: ISS M2M -ISP - WDR modes
 ADASVISION-1473: ISS M2M -ISP - resizer
 ADASVISION-1475: ISS M2M - H3A
 ADASVISION-1477: ISS M2M (LDC + VTNF) - LDC selection
 ADASVISION-1478: ISS M2M (LDC + VTNF) - LDC data format
 ADASVISION-1480: ISS M2M (LDC + VTNF) - LDC create time config
 ADASVISION-1483: ISS M2M RSZ - resizer
 ADASVISION-1484: ISS M2M RSZ - output dataformat

	ADASVISION-1485: ISS M2M RSZ - input data format ADASVISION-1490: Algorithm Link ISS 2A - Auto-exposure using H3A data as input ADASVISION-1491: Algorithm Link ISS 2A - Auto-white balance using H3A data as input ADASVISION-1492: Algorithm Link ISS 2A - Auto-exposure for WDR mode operation using H3A data as input
<u>Keywords:</u>	tda3xx-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-37: ISS_Capture_AR140_2PASS_WDR_LDC_VTNFSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source shuld be AR140 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = ON, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed LDC effect should be visible. If LDC has not been tuned for the lens used, it is OK if correction is not perfect but there should be no crash or corruption.	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		

Requirements

ADASVISION-1456: ISS capture - mode
 ADASVISION-1457: ISS capture - interface
 ADASVISION-1459: ISS capture - resolution
 ADASVISION-1467: ISS M2M -ISP - GLBCE selection
 ADASVISION-1468: ISS M2M -ISP - resizer
 ADASVISION-1469: ISS M2M -ISP - output dataformat
 ADASVISION-1470: ISS M2M -ISP - input data format
 ADASVISION-1472: ISS M2M -ISP - WDR modes
 ADASVISION-1473: ISS M2M -ISP - resizer
 ADASVISION-1475: ISS M2M - H3A
 ADASVISION-1477: ISS M2M (LDC + VTNF) - LDC selection
 ADASVISION-1478: ISS M2M (LDC + VTNF) - LDC data format
 ADASVISION-1479: ISS M2M (LDC + VTNF) - VTNF data format
 ADASVISION-1480: ISS M2M (LDC + VTNF) - LDC create time config
 ADASVISION-1481: ISS M2M (LDC + VTNF) - VTNF create time config
 ADASVISION-1482: ISS M2M (LDC + VTNF) - general
 ADASVISION-1483: ISS M2M RSZ - resizer
 ADASVISION-1484: ISS M2M RSZ - output dataformat
 ADASVISION-1485: ISS M2M RSZ - input data format
 ADASVISION-1490: Algorithm Link ISS 2A - Auto-exposure using H3A data as input
 ADASVISION-1491: Algorithm Link ISS 2A - Auto-white balance using H3A data as input
 ADASVISION-1492: Algorithm Link ISS 2A - Auto-exposure for WDR mode operation using H3A data as input

<u>Keywords:</u>	tda3xx-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-38: ISS_Capture_AR140_2PASS_WDR_Color_Fidelity

Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source shuld be AR140 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Noise levels should be very low. Sharpness should be good. No color cast should be visible on lightbox walls and gray row of colorchecker. Colored patches should have the right hue.	

Execution type: Manual

Estimated exec. duration (sec):

Priority: Medium

Requirements
 ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display
 ADASVISION-1456: ISS capture - mode
 ADASVISION-1472: ISS M2M -ISP - WDR modes

Keywords: tda3xx-evm

Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-39: ISS_Capture_AR140_2PASS_WDR_Noise_Filter

Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source shuld be AR140 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC Adjust lens to right focal length. Ensure dark lighting.	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Noise levels should be very low. Sharpness should be good.	

Execution type: ManualEstimated exec. duration (sec):Priority: MediumRequirements

ADASVISION-1456: ISS capture - mode
 ADASVISION-1457: ISS capture - interface
 ADASVISION-1459: ISS capture - resolution
 ADASVISION-1467: ISS M2M -ISP - GLBCE selection
 ADASVISION-1468: ISS M2M -ISP - resizer
 ADASVISION-1469: ISS M2M -ISP - output dataformat
 ADASVISION-1470: ISS M2M -ISP - input data format
 ADASVISION-1471: ISS M2M -ISP - NF
 ADASVISION-1472: ISS M2M -ISP - WDR modes
 ADASVISION-1473: ISS M2M -ISP - resizer
 ADASVISION-1475: ISS M2M - H3A
 ADASVISION-1477: ISS M2M (LDC + VTNF) - LDC selection
 ADASVISION-1483: ISS M2M RSZ - resizer
 ADASVISION-1484: ISS M2M RSZ - output dataformat
 ADASVISION-1485: ISS M2M RSZ - input data format
 ADASVISION-1490: Algorithm Link ISS 2A - Auto-exposure using H3A data as input
 ADASVISION-1491: Algorithm Link ISS 2A - Auto-white balance using H3A data as input
 ADASVISION-1492: Algorithm Link ISS 2A - Auto-exposure for WDR mode operation using H3A data as input

Keywords: tda3xx-evm**Execution Details**

Build REL_3_7

Tester x0246581

Execution Result: **Passed**Execution Mode: **Manual**Execution duration (sec):**Test Case VISIONSDK-40: ISS_Capture_AR140_2PASS_WDR_DUMP_RAW_FRAMES**Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution
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			<u>Status:</u>
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source should be AR140 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC Capture RAW images using n/w tool	Display must come up and no buffer drops should be observed Captured images must be free of artifacts.	
<u>Execution type:</u>		Manual	
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes	
<u>Keywords:</u>		tda3xx-evm	
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-41: ISS_Capture_AR140_2PASS_WDR_DUMP_YUV_FRAMESSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source should be AR140 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC Capture YUV images using n/w tool	Display must come up and no buffer drops should be observed Captured images must be free of artifacts. YUV frame must match the display.	
<u>Execution type:</u>		Manual	
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes	
<u>Keywords:</u>		tda3xx-evm	

Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-42: ISS_Capture_AR140_2PASS_WDR_Read_Sensor_Reg

Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source shuld be AR140 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine Use the command iss_read_sensor_reg to read chip ID (0x3000) and exposure register (0x3082)	Chip ID and exposure value must be read correctly	

Execution type: Manual

Estimated exec. duration (sec):

Priority: Medium

Requirements
 ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display
 ADASVISION-1456: ISS capture - mode
 ADASVISION-1472: ISS M2M -ISP - WDR modes

Keywords: tda3xx-evm

Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-43: ISS_Capture_AR140_2PASS_WDR_Write_Sensor_Reg

Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source should be AR140 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine Use the command iss_write_sensor_reg to write 0, 4, 8 and c one by one to the exposure register (0x3082)	Change of exposure value must be clearly visible on the display	
Execution type:	Manual		
Estimated exec. duration (sec):			
Priority:	Medium		
Requirements	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Parallel capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes		
Keywords:	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

Test Case VISIONSDK-44: ISS_Capture_AR140_2PASS_WDR_Save_DCC_ProfileSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source should be AR140 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine Get the sensor.bin file from driver	There should not be any error/assertion in saving dcc file	

	and save it using iss_save_dcc_file network command		
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-45: ISS_Capture_AR140_2PASS_WDR_Send_DCC_ProfileSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source shuld be AR140 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine and send new sensor.bin file using iss_send_dcc_file network command	New DCC profile must be used from the QSPI memory There should be a print on console indicating that	

<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-46: ISS_Capture_AR140_2PASS_WDR_Clear_DCC_ProfileSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR140

Input : AR140 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR140 & Display Output as HDMI 1080P	Capture Source shuld be AR140 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine and clear DCC profile from QSPI using iss_clear_dcc_qspi_mem network command	There should not be any error/assertion in cleaning dcc profile in qspi	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.4.3.2.Test Suite : ISS_SingleCam_Capture_Display_OV10640**Test Case VISIONSDK-56: ISS_Capture_OV10640_LM_Performance**Summary:

Linear mode - basic ISS, performance test

ISS Single channle Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10640	Capture Source shuld be OV10640 & Display device as HDMI 1080P	

	& Display Output as HDMI 1080P		
2	Run "1CH ISS capture + ISS ISP + ISS LDC+VTNF + Display" UC	Display must come up and no buffer drops should be observed	
3	Press "P" & check for FPS	FPS should be in the range 29.5 - 30.5	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1429: Capture + Display generic usecase using OV10640 ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1456: ISS capture - mode ADASVISION-1457: ISS capture - interface ADASVISION-1458: ISS capture - CSI2 mode ADASVISION-1459: ISS capture - resolution ADASVISION-1467: ISS M2M -ISP - GLBCE selection ADASVISION-1468: ISS M2M -ISP - resizer ADASVISION-1469: ISS M2M -ISP - output dataformat ADASVISION-1470: ISS M2M -ISP - input data format ADASVISION-1473: ISS M2M -ISP - resizer ADASVISION-1475: ISS M2M - H3A ADASVISION-1483: ISS M2M RSZ - resizer ADASVISION-1484: ISS M2M RSZ - output dataformat ADASVISION-1485: ISS M2M RSZ - input data format ADASVISION-1490: Algorithm Link ISS 2A - Auto-exposure using H3A data as input ADASVISION-1491: Algorithm Link ISS 2A - Auto-white balance using H3A data as input ADASVISION-1492: Algorithm Link ISS 2A - Auto-exposure for WDR mode operation using H3A data as input ADASVISION-1604: Support sensor frame work		
<u>Keywords:</u>	tda3xx-evm tda2px-evm c_regression c_performance m_iss		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-57: ISS_Capture_OV10640_LM_Dyanmic_RangeSummary:

Linear mode - dynamic range test

ISS Single channle Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source shuld be OV10640 & Display device as HDMI 1080P	
2	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. AE should adjust such that lowlights are visible and highlights are overexposed.	
<u>Execution type:</u>	Manual		

<u>Estimated exec. duration (sec):</u>	
<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1429: Capture + Display generic usecase using OV10640 ADASVISION-1456: ISS capture - mode
<u>Keywords:</u>	tda3xx-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-59: ISS_Capture_OV10640_2PASS_WDR

Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source shuld be OV10640 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	

<u>Execution type:</u>	Automated
<u>Estimated exec. duration (sec):</u>	60.00
<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1429: Capture + Display generic usecase using OV10640 ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes
<u>Keywords:</u>	tda3xx-evm c_stress c_stability
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-60: ISS_Capture_OV10640_2PASS_WDR_Performance

Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source shuld be OV10640 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed	
4	Press "P" & check for FPS	FPS should be in the range 29.5 - 30.5	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1429: Capture + Display generic usecase using OV10640 ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-61: ISS_Capture_OV10640_2PASS_WDR_Dynamic_Range

Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source shuld be OV10640 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct in dark as well as bright regions.	

	Dark regions maybe noisier than bright regions but NSF effect should be visible.	
<u>Execution type:</u>	Manual	
<u>Estimated exec. duration (sec):</u>		
<u>Priority:</u>	Medium	
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1429: Capture + Display generic usecase using OV10640 ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes	
<u>Keywords:</u>	tda3xx-evm	
Execution Details		
Build	REL_3_7	
Tester	x0246581	
<u>Execution Result:</u>	Passed	
<u>Execution Mode:</u>	Manual	
<u>Execution duration (sec):</u>		

Test Case VISIONSDK-62: ISS_Capture_OV10640_2PASS_WDR_AESummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source should be OV10640 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Noise levels should be very low. Moving to dark scene should cause AE adjustment and increase in noise level.	

<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1456: ISS capture - mode ADASVISION-1457: ISS capture - interface ADASVISION-1458: ISS capture - CSI2 mode ADASVISION-1459: ISS capture - resolution ADASVISION-1467: ISS M2M -ISP - GLBCE selection ADASVISION-1468: ISS M2M -ISP - resizer ADASVISION-1469: ISS M2M -ISP - output dataformat ADASVISION-1470: ISS M2M -ISP - input data format ADASVISION-1472: ISS M2M -ISP - WDR modes ADASVISION-1473: ISS M2M -ISP - resizer ADASVISION-1475: ISS M2M - H3A ADASVISION-1483: ISS M2M RSZ - resizer ADASVISION-1484: ISS M2M RSZ - output dataformat ADASVISION-1485: ISS M2M RSZ - input data format ADASVISION-1490: Algorithm Link ISS 2A - Auto-exposure using H3A data as input ADASVISION-1491: Algorithm Link ISS 2A - Auto-white balance using H3A data as input		

	ADASVISION-1492: Algorithm Link ISS 2A - Auto-exposure for WDR mode operation using H3A data as input
<u>Keywords:</u>	tda3xx-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-63: ISS_Capture_OV10640_2PASS_WDR_VTNF

Summary:

WDR mode - basic ISS functionality test

ISS Single channel Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source should be OV10640 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = ON, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Preview maybe noisy. Toggling between VTNF (0/1) should have visible impact on temporal noise.	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Parallel capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1429: Capture + Display generic usecase using OV10640 ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-64: ISS_Capture_OV10640_2PASS_WDR_LDC

Summary:

WDR mode - basic ISS functionality test

ISS Single channel Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source should be OV10640 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed Preview must look undistorted	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1429: Capture + Display generic usecase using OV10640 ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-65: ISS_Capture_OV10640_2PASS_WDR_LDC_VTNFSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source should be OV10640 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = ON, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed LDC effect should be visible. If LDC has not been tuned for the lens used, it is OK if correction is not perfect but there should be no crash or corruption.	

<u>Execution type:</u>	Automated
<u>Estimated exec. duration (sec):</u>	60.00
<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1429: Capture + Display generic usecase using OV10640 ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes
<u>Keywords:</u>	tda3xx-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-66: ISS_Capture_OV10640_2PASS_WDR_Color_FidelitySummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source shuld be OV10640 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Noise levels should be very low. Sharpness should be good. No color cast should be visible on lightbox walls and gray row of colorchecker. Colored patches should have the right hue.	

<u>Execution type:</u>	Manual
<u>Estimated exec. duration (sec):</u>	
<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1429: Capture + Display generic usecase using OV10640 ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes
<u>Keywords:</u>	tda3xx-evm
Execution Details	
Build	REL_3_7
Tester	x0246581

<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-67: ISS_Capture_OV10640_2PASS_WDR_Noise_FilterSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source should be OV10640 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC Adjust lens to right focal length. Ensure dark lighting.	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Noise levels should be very low. Sharpness should be good.	

Execution type: ManualEstimated exec. duration (sec):Priority: Medium

Requirements

ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display
 ADASVISION-1429: Capture + Display generic usecase using OV10640
 ADASVISION-1436: Basic Capture + ISP processing + display use case
 ADASVISION-1456: ISS capture - mode
 ADASVISION-1472: ISS M2M -ISP - WDR modes

Keywords: tda3xx-evm**Execution Details**

Build REL_3_7

Tester x0246581

Execution Result: **Passed**Execution Mode: **Manual**Execution duration (sec):**Test Case VISIONSDK-68: ISS_Capture_OV10640_2PASS_WDR_DUMP_RAW_FRAMES**Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution</u>
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			<u>Status:</u>
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source should be OV10640 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC Capture RAW images using n/w tool	Display must come up and no buffer drops should be observed Captured images must be free of artifacts	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1429: Capture + Display generic usecase using OV10640 ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-69: ISS_Capture_OV10640_2PASS_WDR_DUMP_YUV_FRAMES
Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source should be OV10640 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC Capture YUV images using n/w tool	Display must come up and no buffer drops should be observed Captured images must be free of artifacts YUV frame must match the display.	
<u>Execution type:</u>		Manual	
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1429: Capture + Display generic usecase using OV10640 ADASVISION-1436: Basic Capture + ISP processing + display use case	

	ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes
<u>Keywords:</u>	tda3xx-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-70: ISS_Capture_OV10640_2PASS_WDR_Read_Sensor_Reg
Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source should be OV10640 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine Use the command iss_read_sensor_reg to read chip ID (0x3000) and exposure register (0x3082)	Chip ID and exposure value must be read correctly	

<u>Execution type:</u>	Manual
<u>Estimated exec. duration (sec):</u>	
<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1429: Capture + Display generic usecase using OV10640 ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes
<u>Keywords:</u>	tda3xx-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-71: ISS_Capture_OV10640_2PASS_WDR_Write_Sensor_Reg
Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source shuld be OV10640 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine Use the command iss_write_sensor_reg to write 0, 4, 8 and c one by one to the exposure register (0x3082)	Change of exposure value must be clearly visible on the display	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1429: Capture + Display generic usecase using OV10640 ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-72: ISS_Capture_OV10640_2PASS_WDR_Save_DCC_Profile

Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source shuld be OV10640 & Display device as HDMI 1080P	
2	Go to ISS setting	Selected ISS settings will be saved	

	Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR		
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine Get the sensor.bin file from driver and save it using iss_save_dcc_file network command	There should not be any error/assertion in saving dcc file	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1429: Capture + Display generic usecase using OV10640 ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-73: ISS_Capture_OV10640_2PASS_WDR_Send_DCC_ProfileSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source shuld be OV10640 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine and send new sensor.bin file using iss_send_dcc_file network command	New DCC profile must be used from the QSPI memory There should be a print on console indicating that	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1429: Capture + Display generic usecase using OV10640		

	ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes
<u>Keywords:</u>	tda3xx-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-74: ISS_Capture_OV10640_2PASS_WDR_Clear_DCC_ProfileSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source shuld be OV10640 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine and clear DCC profile from QSPI using iss_clear_dcc_qspi_mem network command	There should not be any error/assertion in cleaning dcc profile in qspi	

Execution type: ManualEstimated exec. duration (sec):Priority: Medium

Requirements
 ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display
 ADASVISION-1429: Capture + Display generic usecase using OV10640
 ADASVISION-1436: Basic Capture + ISP processing + display use case
 ADASVISION-1456: ISS capture - mode
 ADASVISION-1472: ISS M2M -ISP - WDR modes

Keywords: tda3xx-evm**Execution Details**

Build REL_3_7

Tester x0246581

Execution Result: **Passed**Execution Mode: **Manual**Execution duration (sec):**Test Case VISIONSDK-47: ISS_Capture_OV10640_LM**Summary:

Linear mode - basic ISS functionality test

ISS Single channle Capture UC with OV10640

Input : OV10640 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/Display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source shuld be OV10640 & Display device as HDMI 1080P	
2	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed Exposure and colors should look correct. Most important - white/grey objects should not have any color cast	
Execution type:	Automated		
Estimated exec. duration (sec):	60.00		
Priority:	Medium		
Requirements	ADASVISION-1326: Support OV10640 Raw/Bayer sensors ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1429: Capture + Display generic usecase using OV10640 ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1461: ISS capture - packing ADASVISION-1621: ISS: Capture Link & M2M ISP : Support MIPI RAW 12 dataformat		
Keywords:	tda3xx-evm c_qualification c_integration		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

1.4.3.3.Test Suite : ISS_SingleCam_Capture_Display_IMX224

Test Case VISIONSDK-77: ISS_Capture_IMX224_LM

Summary:

Linear mode - basic ISS functionality test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/Display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source shuld be IMX224 & Display device as HDMI 1080P	
2	Run "1CH ISS capture + ISS ISP + ISS LDC+VTNF + Display" UC	Display must come up and no buffer drops should be observed Exposure and colors should look correct. Most important - white/grey objects should not have any color cast	

<u>Execution type:</u>	Automated
<u>Estimated exec. duration (sec):</u>	60.00
<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1577: iMX224 sensor support on TDA3x ADASVISION-1604: Support sensor frame work
<u>Keywords:</u>	tda3xx-evm c_qualification
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-78: ISS_Capture_IMX224_LM_PerformanceSummary:

Linear mode - basic ISS, performance test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source shuld be IMX224 & Display device as HDMI 1080P	
2	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed	
3	Press "P" & check for FPS	FPS should be in the range 29.5 - 30.5	

<u>Execution type:</u>	Automated
<u>Estimated exec. duration (sec):</u>	60.00
<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-1577: iMX224 sensor support on TDA3x
<u>Keywords:</u>	tda3xx-evm c_regression c_performance m_iss
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-79: ISS_Capture_IMX224_LM_Dyanmic_RangeSummary:

Linear mode - dynamic range test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source should be IMX224 & Display device as HDMI 1080P	
2	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. AE should adjust such that lowlights are visible and highlights are overexposed.	
Execution type:	Manual		
Estimated exec. duration (sec):			
Priority:	Medium		
Requirements	ADASVISION-1577: iMX224 sensor support on TDA3x		
Keywords:	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

Test Case VISIONSDK-80: ISS_Capture_IMX224_2PASS_WDRSummary:

WDR mode - basic ISS functionality test

ISS Single channel Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source should be IMX224 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR Line Interleaved	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
<u>Execution type:</u>		Automated	
<u>Estimated exec. duration (sec):</u>		60.00	
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1577: iMX224 sensor support on TDA3x	
<u>Keywords:</u>		tda3xx-evm c_stress c_stability	

Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-81: ISS_Capture_IMX224_2PASS_WDR_PerformanceSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source shuld be IMX224 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR Line Interleaved	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed	
4	Press "P" & check for FPS	FPS should be in the range 29.5 - 30.5	

Execution type: AutomatedEstimated exec. duration (sec): 60.00Priority: MediumRequirements ADASVISION-1577: iMX224 sensor support on TDA3xKeywords: tda3xx-evm**Execution Details**

Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-82: ISS_Capture_IMX224_2PASS_WDR_Dynamic_RangeSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as IMX224	Capture Source should be IMX224 & Display device as HDMI 1080P	

	& Display Output as HDMI 1080P		
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR Line Interleaved	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct in dark as well as bright regions. Dark regions maybe noisier than bright regions but NSF effect should be visible.	
<u>Execution type:</u>		Manual	
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1577: iMX224 sensor support on TDA3x	
<u>Keywords:</u>		tda3xx-evm	
Execution Details			
Build		REL_3_7	
Tester		x0246581	
<u>Execution Result:</u>		Passed	
<u>Execution Mode:</u>		Manual	
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-83: ISS_Capture_IMX224_2PASS_WDR_AESummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source shuld be IMX224 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR Line Interleaved	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Noise levels should be very low. Moving to dark scene should cause AE adjustment and increase in noise level.	
<u>Execution type:</u>		Manual	
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1577: iMX224 sensor support on TDA3x	
<u>Keywords:</u>		tda3xx-evm	
Execution Details			
Build		REL_3_7	
Tester		x0246581	
<u>Execution Result:</u>		Passed	
<u>Execution Mode:</u>		Manual	

Execution duration (sec):

Test Case VISIONSDK-84: ISS_Capture_IMX224_2PASS_WDR_VTNF

Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source should be IMX224 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = ON, WDR = 2 PASS WDR Line Interleaved	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Preview maybe noisy. Toggling between VTNF (0/1) should have visible impact on temporal noise.	
Execution type:	Automated		
Estimated exec. duration (sec):	60.00		
Priority:	Medium		
Requirements	ADASVISION-1577: iMX224 sensor support on TDA3x		
Keywords:	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

Test Case VISIONSDK-85: ISS_Capture_IMX224_2PASS_WDR_LDC

Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source shuld be IMX224 & Display device as HDMI 1080P	
2	Go to ISS setting	Selected ISS settings will be saved	

	Select LDC = ON, VTNF = OFF, WDR = 2 PASS WDR Line Interleaved		
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed Preview must look undistorted	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1577: iMX224 sensor support on TDA3x		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-86: ISS_Capture_IMX224_2PASS_WDR_LDC_VTNFSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source shuld be IMX224 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = ON, WDR = 2 PASS WDR Line Interleaved	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed LDC effect should be visible. If LDC has not been tuned for the lens used, it is OK if correction is not perfect but there should be no crash or corruption.	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1577: iMX224 sensor support on TDA3x		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-87: ISS_Capture_IMX224_2PASS_WDR_Color_FidelitySummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source shuld be IMX224 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR Line Interleaved	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Noise levels should be very low. Sharpness should be good. No color cast should be visible on lightbox walls and gray row of colorchecker. Colored patches should have the right hue.	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1577: iMX224 sensor support on TDA3x		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-88: ISS_Capture_IMX224_2PASS_WDR_Noise_FilterSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source shuld be IMX224 & Display device as HDMI 1080P	
2	Go to ISS setting	Selected ISS settings will be saved	

	Select LDC = ON, VTNF = OFF, WDR = 2 PASS WDR Line Interleaved		
3	Run 1CH ISS capture + ISS + Display UC Adjust lens to right focal length. Ensure dark lighting.	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Noise levels should be very low. Sharpness should be good.	
<u>Execution type:</u>		Manual	
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1577: iMX224 sensor support on TDA3x	
<u>Keywords:</u>		tda3xx-evm	
Execution Details			
Build		REL_3_7	
Tester		x0246581	
<u>Execution Result:</u>		Passed	
<u>Execution Mode:</u>		Manual	
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-89: ISS_Capture_IMX224_2PASS_WDR_DUMP_RAW_FRAMESSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source shuld be IMX224 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = OFF, WDR = 2 PASS WDR Line Interleaved	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC Capture RAW images using n/w tool	Display must come up and no buffer drops should be observed Captured images must be free of artifacts.	
<u>Execution type:</u>		Manual	
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1577: iMX224 sensor support on TDA3x	
<u>Keywords:</u>		tda3xx-evm	
Execution Details			
Build		REL_3_7	
Tester		x0246581	
<u>Execution Result:</u>		Passed	
<u>Execution Mode:</u>		Manual	
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-90: ISS_Capture_IMX224_2PASS_WDR_DUMP_YUV_FRAMESSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source shuld be IMX224 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = OFF, WDR = 2 PASS WDR Line Interleaved	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC Capture YUV images using n/w tool	Display must come up and no buffer drops should be observed Captured images must be free of artifacts YUV frame must match the display.	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1577: iMX224 sensor support on TDA3x		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-91: ISS_Capture_IMX224_2PASS_WDR_Read_Sensor_RegSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source shuld be IMX224 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR Line Interleaved	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	

4	Open Command Prompt on Host machine Use the command iss_read_sensor_reg to read chip ID (0x3000) and exposure register (0x3082)	Chip ID and exposure value must be read correctly
<u>Execution type:</u>	Manual	
<u>Estimated exec. duration (sec):</u>		
<u>Priority:</u>	Medium	
<u>Requirements</u>	ADASVISION-1577: iMX224 sensor support on TDA3x	
<u>Keywords:</u>	tda3xx-evm	
Execution Details		
Build	REL_3_7	
Tester	x0246581	
<u>Execution Result:</u>	Passed	
<u>Execution Mode:</u>	Manual	
<u>Execution duration (sec):</u>		

Test Case VISIONSDK-92: ISS_Capture_IMX224_2PASS_WDR_Write_Sensor_RegSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source shuld be IMX224 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR Line Interleaved	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine Use the command iss_write_sensor_reg to write 0, 4, 8 and c one by one to the exposure register (0x3082)	Change of exposure value must be clearly visible on the display	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1577: iMX224 sensor support on TDA3x		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-93: ISS_Capture_IMX224_2PASS_WDR_Save_DCC_ProfileSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source shuld be IMX224 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR Line Interleaved	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine Get the sensor.bin file from driver and save it using iss_save_dcc_file network command	There should not be any error/assertion in saving dcc file	

Execution type: ManualEstimated exec. duration (sec):Priority: MediumRequirements ADASVISION-1577: iMX224 sensor support on TDA3xKeywords: tda3xx-evm**Execution Details**

Build REL_3_7

Tester x0246581

Execution Result: **Passed**Execution Mode: **Manual**Execution duration (sec):**Test Case VISIONSDK-94: ISS_Capture_IMX224_2PASS_WDR_Send_DCC_Profile**Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source shuld be IMX224 & Display device as HDMI 1080P	
2	Go to ISS setting	Selected ISS settings will be saved	

	Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR Line Interleaved		
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine and send new sensor.bin file using iss_send_dcc_file network command	New DCC profile must be used from the QSPI memory There should be a print on console indicating that	
<u>Execution type:</u> Manual			
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u> Medium			
<u>Requirements</u> ADASVISION-1577: iMX224 sensor support on TDA3x			
<u>Keywords:</u> tda3xx-evm			
Execution Details			
Build REL_3_7			
Tester x0246581			
<u>Execution Result:</u> Passed			
<u>Execution Mode:</u> Manual			
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-95: ISS_Capture_IMX224_2PASS_WDR_Clear_DCC_ProfileSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with IMX224

Input : IMX224 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as IMX224 & Display Output as HDMI 1080P	Capture Source shuld be IMX224 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR Line Interleaved	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine and clear DCC profile from QSPI using iss_clear_dcc_qspi_mem network command	There should not be any error/assertion in cleaning dcc profile in qspi	
<u>Execution type:</u> Manual			
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u> Medium			
<u>Requirements</u> ADASVISION-1577: iMX224 sensor support on TDA3x			
<u>Keywords:</u> tda3xx-evm			
Execution Details			
Build REL_3_7			
Tester x0246581			
<u>Execution Result:</u> Passed			
<u>Execution Mode:</u> Manual			

Execution duration (sec):

1.4.3.4.Test Suite : ISS_SingleCam_Capture_Display_OV2775

Test Case VISIONSDK-248: ISS_Capture_OV2775_LM

Summary:

Linear mode - basic ISS functionality test

ISS Single channle Capture UC with OV2775

Input : OV2775 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/Display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV2775 & Display Output as HDMI 1080P	Capture Source shuld be OV2775 & Display device as HDMI 1080P	
2	Run "1CH ISS capture + ISS ISP + ISS LDC+VTNF + Display" UC	Display must come up and no buffer drops should be observed Exposure and colors should look correct. Most important - white/grey objects should not have any color cast	

Execution type: Automated

Estimated exec. duration (sec): 60.00

Priority: Medium

Requirements
 ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display
 ADASVISION-1436: Basic Capture + ISP processing + display use case
 ADASVISION-1604: Support sensor frame work

Keywords:
 tda3xx-evm
 tda2px-evm
 c_stress
 c_qualification
 c_stability

Execution Details

Build REL_3_7

Tester x0246581

Execution Result: **Passed**

Execution Mode: **Manual**

Execution duration (sec):

Test Case VISIONSDK-291: ISS_Capture_OV2775_LM_performance

Summary:

Linear mode - basic ISS functionality test

ISS Single channle Capture UC with OV2775

Input : OV2775 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/Display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV2775	Capture Source should be OV2775 & Display device as HDMI 1080P	

	& Display Output as HDMI 1080P		
2	Run "1CH ISS capture + ISS ISP + ISS LDC+VTNF + Display" UC	Display must come up and no buffer drops should be observed Exposure and colors should look correct. Most important - white/grey objects should not have any color cast	
3	Press "P" & check for FPS	FPS should be in the range 29.5 - 30.5	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1604: Support sensor frame work		
<u>Keywords:</u>	tda3xx-evm tda2px-evm c_regression c_performance c_qualification m_iss		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-315: ISS_Capture_OV2775_LM_LDC_VTNFSummary:

Linear mode - basic ISS functionality test

ISS Single channle Capture UC with OV2775

Input : OV2775 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/Display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV2775 & Display Output as HDMI 1080P	Capture Source shuld be OV2775 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = ON, WDR = OFF	Selected ISS settings will be saved	
3	Run "1CH ISS capture + ISS ISP + ISS LDC+VTNF + Display" UC	Display must come up and no buffer drops should be observed Exposure and colors should look correct. Most important - white/grey objects should not have any color cast	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1604: Support sensor frame work		
<u>Keywords:</u>	tda3xx-evm tda2px-evm c_stress		

	c_qualification c_stability
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

1.4.3.5.Test Suite : ISS_SingleCam_Capture_Display_AR0143

Test Case VISIONSDK-254: ISS_Capture_AR0143_LM			
<u>Summary:</u>			
Linear mode - basic ISS functionality test			
ISS Single channle Capture UC with AR0143			
Input : AR0143 sensor			
Output : HDMI 1080P			
<u>Preconditions:</u>			
Verify that Capture/Display is running on IPU1-0 at 30fps			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR0143 & Display Output as HDMI 1080P	Capture Source should be AR0143 & Display device as HDMI 1080P	
2	Run "1CH ISS capture + ISS ISP + ISS LDC+VTNF + Display" UC	Display must come up and no buffer drops should be observed Exposure and colors should look correct. Most important - white/grey objects should not have any color cast	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1257: AR0143 Sensor Support ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1604: Support sensor frame work ADASVISION-1701: AR143 (MARs) Camera and Fusion board support on TDA2Px		
<u>Keywords:</u>	tda3xx-evm c_stress c_qualification c_stability		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-292: ISS_Capture_AR0143_LM_Performance			
<u>Summary:</u>			
Linear mode - basic ISS functionality test			
ISS Single channle Capture UC with AR0143			
Input : AR0143 sensor			

Output : HDMI 1080P

Preconditions:

Verify that Capture/Display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as AR0143 & Display Output as HDMI 1080P	Capture Source should be AR0143 & Display device as HDMI 1080P	
2	Run "1CH ISS capture + ISS ISP + ISS LDC+VTNF + Display" UC	Display must come up and no buffer drops should be observed Exposure and colors should look correct. Most important - white/grey objects should not have any color cast	
3	Press "P" & check for FPS	FPS should be in the range 29.5 - 30.5	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1257: AR0143 Sensor Support ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1604: Support sensor frame work ADASVISION-1701: AR143 (MARs) Camera and Fusion board support on TDA2Px		
<u>Keywords:</u>	tda3xx-evm c_regression c_performance c_qualification m_iss		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-334: ISS_Capture_AR143_1PASS_WDRSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR143

Input : AR143 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as AR143 & Display Output as HDMI 1080P	Capture Source should be AR143 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 1 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
<u>Execution type:</u>	Automated		

<u>Estimated exec. duration (sec):</u>	60.00
<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-1257: AR0143 Sensor Support ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes ADASVISION-1604: Support sensor frame work
<u>Keywords:</u>	tda3xx-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-335: ISS_Capture_AR143_2PASS_WDR

Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR143

Input : AR143 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR143 & Display Output as HDMI 1080P	Capture Source shuld be AR143 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	

<u>Execution type:</u>	Automated
<u>Estimated exec. duration (sec):</u>	60.00
<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-1257: AR0143 Sensor Support ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes
<u>Keywords:</u>	tda3xx-evm c_stress c_stability
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Failed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	
Execution notes	ADASVISION-1848: [TDA3x/TDA2Px] Known Image Quality issue with 2A & AEWB

Test Case VISIONSDK-336: ISS_Capture_AR143_2PASS_WDR_PerformanceSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR143

Input : AR143 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as AR143 & Display Output as HDMI 1080P	Capture Source shuld be AR143 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed	
4	Press "P" & check for FPS	FPS should be in the range 29.5 - 30.5	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1257: AR0143 Sensor Support ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes ADASVISION-1604: Support sensor frame work		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-337: ISS_Capture_AR143_2PASS_WDR_Dynamic_RangeSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR143

Input : AR143 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as AR143 & Display Output as HDMI 1080P	Capture Source shuld be AR143 & Display device as HDMI 1080P	
2	Go to ISS setting	Selected ISS settings will be saved	

	Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR		
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct in dark as well as bright regions. Dark regions maybe noisier than bright regions but NSF effect should be visible.	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1257: AR0143 Sensor Support ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Failed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			
Execution notes	ADASVISION-1848: [TDA3x/TDA2Px] Known Image Quality issue with 2A & AEWB		

Test Case VISIONSDK-338: ISS_Capture_AR143_2PASS_WDR_AESummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR143

Input : AR143 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR143 & Display Output as HDMI 1080P	Capture Source shuld be AR143 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Noise levels should be very low. Moving to dark scene should cause AE adjustment and increase in noise level.	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1257: AR0143 Sensor Support ADASVISION-1456: ISS capture - mode ADASVISION-1472: ISS M2M -ISP - WDR modes ADASVISION-1490: Algorithm Link ISS 2A - Auto-exposure using H3A data as input ADASVISION-1491: Algorithm Link ISS 2A - Auto-white balance using H3A data as input ADASVISION-1492: Algorithm Link ISS 2A - Auto-exposure for WDR mode operation using H3A data as input		

<u>Keywords:</u>	tda3xx-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-339: ISS_Capture_AR143_2PASS_WDR_VTNFSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR143

Input : AR143 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR143 & Display Output as HDMI 1080P	Capture Source shuld be AR143 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = ON, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed All the details in the scene should be visible. Preview maybe noisy. Toggling between VTNF (0/1) should have visible impact on temporal noise.	

Execution type: AutomatedEstimated exec. duration (sec): 60.00Priority: Medium

<u>Requirements</u>	ADASVISION-1257: AR0143 Sensor Support ADASVISION-1456: ISS capture - mode ADASVISION-1457: ISS capture - interface ADASVISION-1459: ISS capture - resolution ADASVISION-1467: ISS M2M -ISP - GLBCE selection ADASVISION-1468: ISS M2M -ISP - resizer ADASVISION-1469: ISS M2M -ISP - output dataformat ADASVISION-1470: ISS M2M -ISP - input data format ADASVISION-1472: ISS M2M -ISP - WDR modes ADASVISION-1473: ISS M2M -ISP - resizer ADASVISION-1475: ISS M2M - H3A ADASVISION-1479: ISS M2M (LDC + VTNF) - VTNF data format ADASVISION-1481: ISS M2M (LDC + VTNF) - VTNF create time config ADASVISION-1483: ISS M2M RSZ - resizer ADASVISION-1484: ISS M2M RSZ - output dataformat ADASVISION-1485: ISS M2M RSZ - input data format ADASVISION-1490: Algorithm Link ISS 2A - Auto-exposure using H3A data as input ADASVISION-1491: Algorithm Link ISS 2A - Auto-white balance using H3A data as input ADASVISION-1492: Algorithm Link ISS 2A - Auto-exposure for WDR mode operation using H3A data as input
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Keywords: tda3xx-evm

Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual

Execution duration (sec):

Test Case VISIONSDK-340: ISS_Capture_AR143_2PASS_WDR_LDC

Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR143

Input : AR143 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as AR143 & Display Output as HDMI 1080P	Capture Source shuld be AR143 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = OFF, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed Preview must look undistorted	

Execution type: Automated

Estimated exec. duration (sec): 60.00

Priority: Medium

Requirements

- ADASVISION-1257: AR0143 Sensor Support
- ADASVISION-1456: ISS capture - mode
- ADASVISION-1457: ISS capture - interface
- ADASVISION-1459: ISS capture - resolution
- ADASVISION-1467: ISS M2M -ISP - GLBCE selection
- ADASVISION-1468: ISS M2M -ISP - resizer
- ADASVISION-1469: ISS M2M -ISP - output dataformat
- ADASVISION-1470: ISS M2M -ISP - input data format
- ADASVISION-1472: ISS M2M -ISP - WDR modes
- ADASVISION-1473: ISS M2M -ISP - resizer
- ADASVISION-1475: ISS M2M - H3A
- ADASVISION-1477: ISS M2M (LDC + VTNF) - LDC selection
- ADASVISION-1478: ISS M2M (LDC + VTNF) - LDC data format
- ADASVISION-1480: ISS M2M (LDC + VTNF) - LDC create time config
- ADASVISION-1483: ISS M2M RSZ - resizer
- ADASVISION-1484: ISS M2M RSZ - output dataformat
- ADASVISION-1485: ISS M2M RSZ - input data format
- ADASVISION-1490: Algorithm Link ISS 2A - Auto-exposure using H3A data as input
- ADASVISION-1491: Algorithm Link ISS 2A - Auto-white balance using H3A data as input
- ADASVISION-1492: Algorithm Link ISS 2A - Auto-exposure for WDR mode operation using H3A data as input

Keywords: tda3xx-evm

Execution Details

Build REL_3_7

Tester x0246581

Execution Result: **Passed**

Execution Mode: **Manual**

Execution duration (sec):

Test Case VISIONSDK-341: ISS_Capture_AR143_2PASS_WDR_LDC_VTNF

Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR143

Input : AR143 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as AR143 & Display Output as HDMI 1080P	Capture Source shuld be AR143 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = ON, WDR = 2 PASS WDR	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed LDC effect should be visible. If LDC has not been tuned for the lens used, it is OK if correction is not perfect but there should be no crash or corruption.	
<u>Execution type:</u>		Automated	
<u>Estimated exec. duration (sec):</u>		60.00	
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1257: AR0143 Sensor Support ADASVISION-1456: ISS capture - mode ADASVISION-1457: ISS capture - interface ADASVISION-1459: ISS capture - resolution ADASVISION-1467: ISS M2M -ISP - GLBCE selection ADASVISION-1468: ISS M2M -ISP - resizer ADASVISION-1469: ISS M2M -ISP - output dataformat ADASVISION-1470: ISS M2M -ISP - input data format ADASVISION-1472: ISS M2M -ISP - WDR modes ADASVISION-1473: ISS M2M -ISP - resizer ADASVISION-1475: ISS M2M - H3A ADASVISION-1477: ISS M2M (LDC + VTNF) - LDC selection ADASVISION-1478: ISS M2M (LDC + VTNF) - LDC data format ADASVISION-1479: ISS M2M (LDC + VTNF) - VTNF data format ADASVISION-1480: ISS M2M (LDC + VTNF) - LDC create time config ADASVISION-1481: ISS M2M (LDC + VTNF) - VTNF create time config ADASVISION-1482: ISS M2M (LDC + VTNF) - general ADASVISION-1483: ISS M2M RSZ - resizer ADASVISION-1484: ISS M2M RSZ - output dataformat ADASVISION-1485: ISS M2M RSZ - input data format ADASVISION-1490: Algorithm Link ISS 2A - Auto-exposure using H3A data as input ADASVISION-1491: Algorithm Link ISS 2A - Auto-white balance using H3A data as input ADASVISION-1492: Algorithm Link ISS 2A - Auto-exposure for WDR mode operation using H3A data as input	
<u>Keywords:</u>		tda3xx-evm	
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.4.3.6.Test Suite : ISS_SingleCam_Capture_Display_AR132**Test Case VISIONSDK-263: ISS_Capture_AR132_LM**Summary:

Linear mode - basic ISS functionality test

ISS Single channle Capture UC with AR132

Input : AR132 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/Display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as AR132 & Display Output as HDMI 1080P	Capture Source shuld be AR132 & Display device as HDMI 1080P	
2	Run "1CH ISS capture + ISS ISP + ISS LDC+VTNF + Display" UC	Display must come up and no buffer drops should be observed Exposure and colors should look correct. Most important - white/grey objects should not have any color cast	
Execution type:	Automated		
Estimated exec. duration (sec):	60.00		
Priority:	Medium		
Requirements	ADASVISION-1327: Support AR0132 HiSPI Raw/Bayer sensors ADASVISION-1328: Support AR0132 sensor with Parallel RAW 12-bit companded input format ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1435: Basic AR0132 capture + display use case ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1461: ISS capture - packing ADASVISION-1464: ISS capture -non OTF mode - output dataformat ADASVISION-1590: TDA3x - AR0132 sensor support		
Keywords:	tda3xx-evm c_stress c_qualification c_stability		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

Test Case VISIONSDK-264: ISS_Capture_AR132_LM_PerformanceSummary:

Linear mode - basic ISS, performance test

ISS Single channle Capture UC with AR132

Input : AR132 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as AR132 & Display Output as HDMI 1080P	Capture Source shuld be AR132 & Display device as HDMI 1080P	
2	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed.	
3	Press "P" & check for FPS	FPS should be in the range 29.5 - 30.5	

<u>Execution type:</u>	Automated
<u>Estimated exec. duration (sec):</u>	60.00
<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-1327: Support AR0132 HiSPI Raw/Bayer sensors ADASVISION-1328: Support AR0132 sensor with Parallel RAW 12-bit companded input format ADASVISION-1590: TDA3x - AR0132 sensor support
<u>Keywords:</u>	tda3xx-evm c_regression c_performance m_iss
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-265: ISS_Capture_AR132_LM_LDC_VTNFSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR132

Input : AR132 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR132 & Display Output as HDMI 1080P	Capture Source shuld be AR132 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = ON, WDR = OFF	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed LDC effect should be visible. If LDC has not been tuned for the lens used, it is OK if correction is not perfect but there should be no crash or corruption.	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1590: TDA3x - AR0132 sensor support ADASVISION-1591: TDA3x - AR0132 sensor Shall support capture from AR0132 Monochrome / Bayer sensor in RAW12 format ADASVISION-1593: TDA3x - AR0132 sensor M2M SIMCOP shall support single channel lens distortion correction and noise		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-266: ISS_Capture_AR132_LM_DUMP_RAW_FRAMESSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR132

Input : AR132 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR132 & Display Output as HDMI 1080P	Capture Source should be AR132 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = OFF, WDR = OFF	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC Capture RAW images using n/w tool	Display must come up and no buffer drops should be observed Captured images must be free of artifacts	

Execution type: ManualEstimated exec. duration (sec): 60.00Priority: Medium

Requirements ADASVISION-1590: TDA3x - AR0132 sensor support
 ADASVISION-1593: TDA3x - AR0132 sensor M2M SIMCOP shall support single channel lens distortion correction and noise

Keywords: tda3xx-evm**Execution Details**

Build REL_3_7

Tester x0246581

Execution Result: **Passed**Execution Mode: **Manual**Execution duration (sec):**Test Case VISIONSDK-267: ISS_Capture_AR132_LM_DUMP_YUV_FRAMES**Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR132

Input : AR132 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR132 & Display Output as HDMI 1080P	Capture Source should be AR132 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = ON, VTNF = OFF, WDR = OFF	Selected ISS settings will be saved	

3	Run 1CH ISS capture + ISS + Display UC Capture YUV images using n/w tool	Display must come up and no buffer drops should be observed Captured images must be free of artifacts YUV frame must match the display.
<u>Execution type:</u>	Manual	
<u>Estimated exec. duration (sec):</u>		
<u>Priority:</u>	Medium	
<u>Requirements</u>	ADASVISION-1590: TDA3x - AR0132 sensor support ADASVISION-1593: TDA3x - AR0132 sensor M2M SIMCOP shall support single channel lens distortion correction and noise	
<u>Keywords:</u>	tda3xx-evm	
Execution Details		
Build	REL_3_7	
Tester	x0246581	
<u>Execution Result:</u>	Passed	
<u>Execution Mode:</u>	Manual	
<u>Execution duration (sec):</u>		

Test Case VISIONSDK-268: ISS_Capture_AR132_LM_Read_Sensor_RegSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR132

Input : AR132 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR132 & Display Output as HDMI 1080P	Capture Source shuld be AR132 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = OFF	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine Use the command iss_read_sensor_reg to read chip ID (0x3000) and exposure register (0x3082)	Chip ID and exposure value must be read correctly	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1590: TDA3x - AR0132 sensor support		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		

Execution duration (sec):

Test Case VISIONSDK-269: ISS_Capture_AR132_LM_Write_Sensor_Reg

Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR132

Input : AR132 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR132 & Display Output as HDMI 1080P	Capture Source shuld be AR132 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = OFF	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine Use the command iss_write_sensor_reg to write 0, 4, 8 and c one by one to the exposure register (0x3082)	Change of exposure value must be clearly visible on the display	

Execution type: Manual

Estimated exec. duration (sec):

Priority: Medium

Requirements ADASVISION-1590: TDA3x - AR0132 sensor support

Keywords: tda3xx-evm

Execution Details

Build REL_3_7

Tester x0246581

Execution Result: **Passed**

Execution Mode: **Manual**

Execution duration (sec):

Test Case VISIONSDK-270: ISS_Capture_AR132_LM_Save_DCC_Profile

Summary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR132

Input : AR132 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR132 & Display Output as HDMI 1080P	Capture Source shuld be AR132 & Display device as HDMI 1080P	

2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = OFF	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine Get the sensor.bin file from driver and save it using iss_save_dcc_file network command	There should not be any error/assertion in saving dcc file	
<u>Execution type:</u>		Manual	
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1590: TDA3x - AR0132 sensor support	
<u>Keywords:</u>		tda3xx-evm	
Execution Details			
Build		REL_3_7	
Tester		x0246581	
<u>Execution Result:</u>		Passed	
<u>Execution Mode:</u>		Manual	
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-271: ISS_Capture_AR132_LM_Send_DCC_ProfileSummary:

WDR mode - basic ISS functionality test

ISS Single channle Capture UC with AR132

Input : AR132 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR132 & Display Output as HDMI 1080P	Capture Source shuld be AR132 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = OFF	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine and send new sensor.bin file using iss_send_dcc_file network command	New DCC profile must be used from the QSPI memory There should be a print on console indicating that	
<u>Execution type:</u>		Manual	
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1590: TDA3x - AR0132 sensor support	
<u>Keywords:</u>		tda3xx-evm	
Execution Details			
Build		REL_3_7	
Tester		x0246581	

<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-272: ISS_Capture_AR132_LM_Clear_DCC_ProfileSummary:

WDR mode - basic ISS functionality test

ISS Single channel Capture UC with AR132

Input : AR132 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR132 & Display Output as HDMI 1080P	Capture Source should be AR132 & Display device as HDMI 1080P	
2	Go to ISS setting Select LDC = OFF, VTNF = OFF, WDR = OFF	Selected ISS settings will be saved	
3	Run 1CH ISS capture + ISS + Display UC	Display must come up and no buffer drops should be observed. Exposure and colors should look correct.	
4	Open Command Prompt on Host machine and clear DCC profile from QSPI using iss_clear_dcc_qspi_mem network command	There should not be any error/assertion in cleaning dcc profile in qspi	

<u>Execution type:</u>	Manual
<u>Estimated exec. duration (sec):</u>	
<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-1590: TDA3x - AR0132 sensor support
<u>Keywords:</u>	tda3xx-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-286: ISS_Capture_AR132_LM_MonochromeSummary:

Linear mode - basic ISS functionality test

ISS Single channel Capture + ISS ISP Monochrome Display UC with AR132

Input : AR132 sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture/Display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR132	Capture Source should be AR132 & Display device as HDMI 1080P	

	& Display Output as HDMI 1080P		
2	Run "1CH ISS capture (AR0132) + ISS ISP Monochrome + Display" UC	Display must come up and no buffer drops should be observed Exposure and colors should look correct. Most important - white/grey objects should not have any color cast	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display ADASVISION-1435: Basic AR0132 capture + display use case ADASVISION-1436: Basic Capture + ISP processing + display use case ADASVISION-1590: TDA3x - AR0132 sensor support ADASVISION-1592: TDA3x - AR0132 sensor Shall support processing of RAW12 monochrome data in ISP LINK		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.4.3.7.Test Suite : ISS_Capture_Display_IPU_SMP_BIOS

Test Case VISIONSDK-358: ISS_Capture_Display_Input_OV10640_Output_HDMI_1080P			
<u>Summary:</u>			
Capture Display UC with IPU SMP BIOS			
supported on TDA3x/RVP			
Input : OV10640			
Output : HDMI 1080P			
<u>Preconditions:</u>			
Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps			
Binaries should be built with IPU_SMP_BIOS=yes			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10640 & Display Output as HDMI 1080P	Capture Source should be OV10640 & Display device as HDMI 1080P	
2	Run ISS 1 Ch capture + Display UC	Display must come up and no buffer drops should be observe	
3	Run other available UCs	Should be able to run UCs without any issues	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1835: Enable SMP support for IPU1_0 and IPU1_1		
<u>Keywords:</u>	None		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		

Execution duration (sec):

Test Case VISIONSDK-307: ISS_dump_frames_various_tap_points

Summary:

ISS Single channle Capture UC with AR140/OV10640/IMX224

Input : AR140/OV10640/IMX224 sensor

Output : HDMI 1080P

Preconditions:

Binaries should built with NDK enabled

Verify that Capture/Display is running on IPU1-0 at 30fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR140/OV10640/IMX224 & Display Output as HDMI 1080P	Capture Source shuld be AR140/OV10640/IMX224 & Display device as HDMI 1080P	
2	Run "1CH ISS capture + ISS ISP + ISS LDC+VTNF + Display" UC	Display must come up and no buffer drops should be observed Exposure and colors should look correct. Most important - white/grey objects should not have any color cast	
3	Run DCC tool for ISS image tuning Connect to target EVM (using IP) & dump frames from various tap-points	should be able to dump frames from various tap-points	

Execution type: Manual

Estimated exec. duration (sec): 60.00

Priority: Medium

Requirements
 ADASVISION-1395: 1CH 720p30 CSI2/LVDS/Paralle capture + ISS ISP M2M WDR + ISS M2M LDC+VTNF + Display
 ADASVISION-1436: Basic Capture + ISP processing + display use case
 ADASVISION-1511: ISS tuning tool
 ADASVISION-1587: TDA3x ISS UC - SDK links and Utils to support static memory allocation
 ADASVISION-1600: ISS - add various tap-points for dumping the frames
 ADASVISION-1604: Support sensor frame work
 ADASVISION-1671: APIs to read UB960/964/954/953 status registers and to enable test pattern

Keywords: None

Execution Details

Build REL_3_7

Tester x0246581

Execution Result: **Passed**

Execution Mode: **Manual**

Execution duration (sec):

Test Case VISIONSDK-357: ISS_Capture_OV10640_Output_ARGB32

Summary:

ISS Capture display UC

supported on TDA3x

Input : OV10640 Sensor

Output : ARGB32 over resizer window

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution</u>
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			<u>Status:</u>
1	Enable use-case in test suite& build Load Testsuite binaries on TDA3xx EVM & Run	Check Logs of iss_isp_display use-case Capture should be running on IPU1-0 at 30fps and display should be running on IPU1-0 at 60fps	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1927: ARGB32 output support for Iss_memResizer Link		
<u>Keywords:</u>	None		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.4.4.Test Suite : TIDL

1.4.4.1.Test Suite : TIDL_FILE_IO

Test Case VISIONSDK-158: TIDL_File_IO_UC_DSP_Performance

Summary:

TIDL File IO UC on DSP:

Check Performance numbers

Preconditions:

Verify below files should be present in SD card

1. Use case config file (TIDLCFG.TXT)
2. IN.RGB
3. PRM.BIN
4. NET.BIN

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	1. Select TIDL File IO UC from Main Menu 2. Select DSP 3. Select Dump Output frames to file	Frame will be dumped to SD card as OUT.BIN	
2	Press "P" to check performance numbers	On DSP should be <=120sec	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1163: Deep learning demo ADASVISION-1201: Validate TIDL use case on TDA3x		
<u>Keywords:</u>	tda2xx-evm tda3xx-evm c_performance		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-159: TIDL_File_IO_UC_DSP_Dump_Frames_File

Summary:

TIDL File IO UC on DSP:

Dumping frames to File

Preconditions:

Verify below files should be present in SD card

1. Use case config file (TIDLCFG.TXT)
2. IN.RGB

3. PRM.BIN

4. NET.BIN

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	1. Select TIDL File IO UC from Main Menu 2. Select DSP 3. Select Dump Output frmaes to file	Frame will be dumped to SD card as OUT.BIN	
2	Compare with Reference output	On comparing no differences should be seen	
Execution type:	Automated		
Estimated exec. duration (sec):	60.00		
Priority:	Medium		
Requirements	ADASVISION-1163: Deep learning demo ADASVISION-1201: Validate TIDL use case on TDA3x		
Keywords:	tda2xx-evm tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

Test Case VISIONSDK-160: TIDL_File_IO_UC_DSP_Free_RunSummary:

TIDL File IO UC on DSP:

Free Run

Preconditions:

Verify below files should be present in SD card

1. Use case config file (TIDLCFG.TXT)
2. IN.RGB
3. PRM.BIN
4. NET.BIN

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	1. Select TIDL File IO UC from Main Menu 2. Select DSP 3. Select Free run	No Display & also No Frame will be dumped to SD card	
Execution type:	Automated		
Estimated exec. duration (sec):	60.00		
Priority:	Medium		
Requirements	ADASVISION-1163: Deep learning demo ADASVISION-1201: Validate TIDL use case on TDA3x		
Keywords:	tda2xx-evm tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		

<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-161: TIDL_File_IO_UC_EVE_PerformanceSummary:

TIDL File IO UC on EVE:

Check Performance numbers

Preconditions:

Verify below files should be present in SD card

1. Use case config file (TIDLCFG.TXT)
2. IN.RGB
3. PRM.BIN
4. NET.BIN

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	1. Select TIDL File IO UC from Main Menu 2. Select EVE 3. Select Dump Output frames to file	Frame will be dumped to SD card as OUT.BIN	
2	Press "P" to check performance numbers	On EVE should be <=450sec	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1163: Deep learning demo ADASVISION-1201: Validate TIDL use case on TDA3x		
<u>Keywords:</u>	tda2xx-evm tda3xx-evm c_performance		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-162: TIDL_File_IO_UC_EVE_Dump_Frames_FileSummary:

TIDL File IO UC on EVE:

Dump frames to file

Preconditions:

Verify below files should be present in SD card

1. Use case config file (TIDLCFG.TXT)
2. IN.RGB
3. PRM.BIN
4. NET.BIN

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	1. Select TIDL File IO UC from Main Menu 2. Select EVE	Frame will be dumped to SD card as OUT.BIN	

	3. Select Dump Output frames to file		
2	Compare with Reference output	On comparing no differences should be seen	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1163: Deep learning demo ADASVISION-1201: Validate TIDL use case on TDA3x		
<u>Keywords:</u>	tda2xx-evm tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-163: TIDL_File_IO_UC_EVE_Free_Run			
<u>Summary:</u>			
TIDL File IO UC on EVE:			
Free Run			
<u>Preconditions:</u>			
Verify below files should be present in SD card			
1. Use case config file (TIDLCFG.TXT)			
2. IN.RGB			
3. PRM.BIN			
4. NET.BIN			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	1. Select TIDL File IO UC from Main Menu 2. Select EVE 3. Select Free run	No Display & also No Frame will be dumped to SD card	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1163: Deep learning demo ADASVISION-1201: Validate TIDL use case on TDA3x		
<u>Keywords:</u>	tda2xx-evm tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.4.5.Test Suite : MISC

1.4.5.1.Test Suite : NullSrc_Null_Link

Test Case VISIONSDK-372: NullSrc_Capture_Encode_MPEG4_Null

Summary:

NullSrc Capture Encode Null UC with MJPEG Frames

Input : YUV420 Plannar

Output : Encoded file dumped to SD card

Preconditions:

Verify that Capture is running on IPU1-0 at 5fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
2	Run usecase "p" NullSrc capture + ENC + Null UC	No buffer drops should be observe	
3	Press "P"	Check performance stats	
<u>Execution type:</u>		Automated	
<u>Estimated exec. duration (sec):</u>		60.00	
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-2224: MPEG4 Encoder Integration in DSP	
<u>Keywords:</u>		tda3xx-evm	
<u>Execution Details</u>			
Build		REL_3_7	
Tester		x0246581	
<u>Execution Result:</u>		Passed	
<u>Execution Mode:</u>		Manual	
<u>Execution duration (sec):</u>			

1.4.5.2.Test Suite : SyncLink

Test Case VISIONSDK-187: VIP_Capture_Sync_Null

Summary:

Single Cam Capture Sync Null UC

supported on TDA2x/TDA2Ex/TDA3x

Input : OV10635 Sensor

Output : Null

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Run Testsuite	Check Logs of Capture Sync Null UC Capture should be running on IPU1-0 at 30fps and display should be running on IPU1-0 at 60fps	
<u>Execution type:</u>		Manual	
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1518: Synchronization of frames across multiple channels	

<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm m_connector_links
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

1.4.5.3.Test Suite : DupLink

Test Case VISIONSDK-165: VIP_Capture_Dup_Display			
<u>Summary:</u>			
Single Cam Capture Dup Display UC			
supported on TDA2x/TDA2Ex/TDA3x			
Input : OV10635 Sensor			
Output : HDMI 1080P			
<u>Preconditions:</u>			
Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Run Testsuite	Check Logs of Capture Dup Display UC Capture should be running on IPU1-0 at 30fps and display should be running on IPU1-0 at 60fps	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1519: duplication of output		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm m_connector_links		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.4.5.4.Test Suite : MergeLink

Test Case VISIONSDK-166: VIP_Capture_Merge_Display			
<u>Summary:</u>			
Single Cam Capture Merge Display UC			
supported on TDA2x/TDA2Ex/TDA3x			
Input : OV10635 Sensor			
Output : HDMI 1080P			
<u>Preconditions:</u>			

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Run Testsuite	Check Logs of Capture Merge Display UC Capture should be running on IPU1-0 at 30fps and display should be running on IPU1-0 at 60fps	
Execution type:	Manual		
Estimated exec. duration (sec):			
Priority:	Medium		
Requirements	ADASVISION-1520: Merging of multiple outputs		
Keywords:	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm m_connector_links		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

1.4.5.5.Test Suite : StatisticsLogs

Test Case VISIONSDK-211: VIP_SingleCam_Capture_Display_Statistics_Logs			
<u>Summary:</u>			
Capture Display UC			
Input : OV10635			
Output : HDMI 1080P			
<u>Preconditions:</u>			
Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps			
#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P	Capture Source should be OV10635 & Display device as HDMI 1080P	
2	Run 1 Ch VIP capture + Display UC	Display must come up and no buffer drops should be observe	
3	Press "P"	It should print all performance statistics 1. Load on all cores 2. DDR BW usage 3. FPS for each Link 4. Latency to process frames	
<u>Execution type:</u>		Automated	
<u>Estimated exec. duration (sec):</u>		60.00	
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1536: System debug logs ADASVISION-1537: Statistics logs ADASVISION-1538: latency measurement ADASVISION-1539: system loading ADASVISION-1540: DDR BW measurement	

	ADASVISION-1541: Global timestamp ADASVISION-1563: Vision SDK Print Statistics for PM
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-212: Print_PRCM_Statistics_Dpll_StatusSummary:

Print PRCM Statistics Dpll Status

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings -> Print PRCM Statistics Press "1" for Dpll Status	On selecting "1" should print DPLL Statistics	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1561: power managemant Software Enhancements and Advanced Features for TDA2x/TDA3x/TDA2Ex ADASVISION-1562: power managemant - Profiling Support for Actual CPU idle time ADASVISION-1563: Vision SDK Print Statistics for PM		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-213: Print_PRCM_Statistics_TemperatureSummary:

Print PRCM Statistics Temperature

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings -> Print PRCM Statistics Press "2" for Temperature	On selecting "2" should print current min & max temperature on all cores	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		

<u>Requirements</u>	ADASVISION-1561: power managemant Software Enhancements and Advanced Features for TDA2x/TDA3x/TDA2Ex ADASVISION-1563: Vision SDK Print Statistics for PM ADASVISION-1566: PM - VSDKPRINTSTATS: Print the Temperature
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-214: Print_PRCM_Statistics_VoltageSummary:

Print PRCM Statistics Voltage

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings -> Print PRCM Statistics Press "3" for Voltage	On selecting "3" should print voltage usage	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1561: power managemant Software Enhancements and Advanced Features for TDA2x/TDA3x/TDA2Ex ADASVISION-1563: Vision SDK Print Statistics for PM ADASVISION-1567: PM - VSDKPRINTSTATS: Print the Voltage		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-215: Print_PRCM_Statistics_Module_Power_StateSummary:

Print PRCM Statistics Module Power State

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings -> Print PRCM Statistics Press "4" for Module Power State	On selecting "4" should print Module Power State Module Name & Module state Module SIDLE State Clock Activite State	

	Power Domain State	
<u>Execution type:</u>	Automated	
<u>Estimated exec. duration (sec):</u>	60.00	
<u>Priority:</u>	Medium	
<u>Requirements</u>	ADASVISION-1561: power managemant Software Enhancements and Advanced Features for TDA2x/TDA3x/TDA2Ex ADASVISION-1563: Vision SDK Print Statistics for PM ADASVISION-1565: PM - VSDKPRINTSTATS: Print Module Power State	
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp	
Execution Details		
Build	REL_3_7	
Tester	x0246581	
<u>Execution Result:</u>	Passed	
<u>Execution Mode:</u>	Manual	
<u>Execution duration (sec):</u>		

Test Case VISIONSDK-216: Print_PRCM_Statistics_CPU_Frequency
Summary:

Print PRCM Statistics CPU Frequency

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings -> Print PRCM Statistics Press "5" for CPU Frequency	On selecting "5" should print Frequency of all cores	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1561: power managemant Software Enhancements and Advanced Features for TDA2x/TDA3x/TDA2Ex ADASVISION-1563: Vision SDK Print Statistics for PM ADASVISION-1564: PM - VSDKPRINTSTATS: Print Module Frequencies		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-217: Print_PRCM_Statistics_Peripherals_Frequency
Summary:

Print PRCM Statistics Peripherals Frequency

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
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1	Go to System Settings -> Print PRCM Statistics Press "6" for Peripherals Frequency	On selecting "6" should print Peripherals Frequency of QSPI & DSS	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1561: power managemant Software Enhancements and Advanced Features for TDA2x/TDA3x/TDA2Ex ADASVISION-1563: Vision SDK Print Statistics for PM ADASVISION-1564: PM - VSDKPRINTSTATS: Print Module Frequencies		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-218: Print_PRCM_Statistics_Prcm_Register_DataSummary:

Print PRCM Statistics Prcm Register Data

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings -> Print PRCM Statistics Press "7" for Prcm Register Data	On selecting "6" should print Prcm Register Data of all POWER DOMAIN Reg. Address & Value	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1561: power managemant Software Enhancements and Advanced Features for TDA2x/TDA3x/TDA2Ex ADASVISION-1563: Vision SDK Print Statistics for PM ADASVISION-1565: PM - VSDKPRINTSTATS: Print Module Power State		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-219: Print_PRCM_Statistics_Power_ConsumptionSummary:

Print PRCM Statistics Power Consumption

Supported only on TDA2x

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings -> Print PRCM Statistics Press "8" for Power Consumption	On selecting "8" should print Power Consumption	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1561: power managemant Software Enhancements and Advanced Features for TDA2x/TDA3x/TDA2Ex ADASVISION-1563: Vision SDK Print Statistics for PM ADASVISION-1565: PM - VSDKPRINTSTATS: Print Module Power State		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-220: Print_PRCM_Statistics_All_PRCM_StatsSummary:

Print PRCM Statistics All PRCM Stats

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings -> Print PRCM Statistics Press "9" for All PRCM Stats	On selecting "9" should print All PRCM Stats Dpll Status Temperature Voltage Module Power State CPU frequency Peripherals Frequency Prcm register Data Power Consumption	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1536: System debug logs ADASVISION-1537: Statistics logs ADASVISION-1538: latency measurement ADASVISION-1539: system loading ADASVISION-1540: DDR BW measurement ADASVISION-1541: Global timestamp ADASVISION-1561: power managemant Software Enhancements and Advanced Features for TDA2x/TDA3x/TDA2Ex ADASVISION-1563: Vision SDK Print Statistics for PM ADASVISION-1564: PM - VSDKPRINTSTATS: Print Module Frequencies ADASVISION-1565: PM - VSDKPRINTSTATS: Print Module Power State		

	ADASVISION-1566: PM - VSDKPRINTSTATS: Print the Temperature ADASVISION-1567: PM - VSDKPRINTSTATS: Print the Voltage
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-287: VIP_SingleCam_Capture_Display_Statistics_Logs_CANSummary:

Capture Display UC

Input : OV10635

Output : HDMI 1080P

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P	Capture Source should be OV10635 & Display device as HDMI 1080P	
2	Run 1 Ch VIP capture + Display UC	Display must come up and no buffer drops should be observe	
3	Press "P"	It should print all performance statistics 1. Load on all cores 2. DDR BW usage 3. FPS for each Link 4. Latency to process frames	
4	Send Link statistics over CAN	User should be able to send Link statistics over CAN	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1536: System debug logs ADASVISION-1537: Statistics logs ADASVISION-1538: latency measurement ADASVISION-1539: system loading ADASVISION-1540: DDR BW measurement ADASVISION-1541: Global timestamp ADASVISION-1563: Vision SDK Print Statistics for PM ADASVISION-1578: Need ability to send "link statistics" over CAN [Magna]		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.4.5.6.Test Suite : FATFS

Test Case VISIONSDK-228: File_IO_UC_MMCSd_IPU1_0Summary:

File IO UC using MMCSd on IPU1_0

Read ApplImage from SD card &

write back same to SD card

Preconditions:

Verify FATFS running IPU1_0

Build SDK with FATFS flags enabled & NDK disabled and FATFS lib on IPU1_0

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	1. Select File IO UC from Menu	No Display On console, Time taken to read & write should be displayed	
Execution type:	Automated		
Estimated exec. duration (sec):	60.00		
Priority:	Medium		
Requirements	ADASVISION-1524: Dummy source with file read ADASVISION-1595: Support for FAT File system with MMC/SD card. (When networking is enabled FAT FS is disabled) ADASVISION-1601: SD card file system support with VSDK ADASVISION-743: FAT FS throughput measurements and optimizations		
Keywords:	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

1.4.5.7.Test Suite : Limp_Home_Mode**Test Case VISIONSDK-277: Limp_Home_Mode**Summary:

Limp Home Mode UC

Input : HDMI

Output : HDMI 1080P

Preconditions:Verify whether display shows a smooth stitching of the single cam views PD+TSR+VD+LD+TLR+SFM
All running at 15fps, Also check performance stats match with datasheet

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as HDMI & Display Output as HDMI 1080P	Capture Source should be HDMI & Display device as HDMI 1080P	
2	Run 1CH VIP capture (HDMI) + FrontCam Analytics 2 (PD+TSR+VD+LD+TLR+SFM) (DSPx, EVEx) + Display UC	Display must come up and no buffer drops should be observe	
3	Press "t"	Should Show Thermal Configuration Menu	

4	Choose below listed options one by one by one 1: Change THOT Temperature 2: Change TCOLD Temperature 3: Show current THOT Temperature 4: Show current TCOLD Temperature 5: Change Threshold Step Size 6: Show Limp Home Status 7: Switch to Limp Home Mode 8: Return to Normal Usecase Mode x: Exit Thermal Menu	Option should be selected On pressing "1" should display temperature to change ranging from 10 -100 deg c On pressing "2" should display temperature to change ranging from 10 -100 deg c On pressing "3" should display current THOT temperature On pressing "4" should display current TCOLD temperature On pressing "5" should display temperature to change ranging from 3 - 15 deg c On pressing "6" should display current Limp Home Status (Limp Home Mode = ACTIVE!! or IN-ACTIVE!! should display on console) On pressing "7" should switch to Limp Home Mode On pressing "8" Return to Normal Usecase Mode On pressing "x" should Exit from Thermal menu	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1527: API config outbound check ADASVISION-1568: PM - Limp Home Mode on Vision SDK ADASVISION-1569: PM - VSDKLIMPHOME: Demonstration of Limp Home ADASVISION-1607: EU-NCAP demo support with TDA2X/3X		
<u>Keywords:</u>	tda2xx-evm tda3xx-evm tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.4.5.8.Test Suite : Task_time_measure_utility

Test Case VISIONSDK-289: VIP_Capture_Display_task_time_measure_utility			
<u>Summary:</u> Capture Display UC supported on all platforms Input : OV10635 Output : HDMI 1080P			
<u>Preconditions:</u> Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps			
#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P	Capture Source shuld be OV10635 & Display device as HDMI 1080P	
2	Run 1 Ch VIP capture + Display UC	Display must come up and no buffer drops should be observe	
3	Press "4" for Demonstrate Task	On console should print Global time taken & actual time	

	Timer utility	taken by utility for function	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1199: Utility to measure time taken for a function in multi-task environment ADASVISION-1381: 1CH VIP capture + Display		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.4.5.9.Test Suite : TLFW_verify

Test Case VISIONSDK-309: TLFW_verification			
<u>Summary:</u> Verifying testlink fw			
<u>Preconditions:</u> staf should be running			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	1. Add all vision SDK test cases to test link, Map with requirements from JIRA 2. Create a test plan & under that create a build 3. Add test cases to execute for that particular build 4. Trigger all automated test cases from test link 5. Execute remaining manual test cases from test link 6. Generate test report	User should be able to trigger all automated test cases from test link & also able to update test result for manual test cases	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-369: Deploy TestLink for VSDK test-case management and automation		
<u>Keywords:</u>	None		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-325: VSDK_restructuring_directory_structure			
<u>Summary:</u> restructuring directory structure for VSDk 3.0 release			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>

1	Restructure directory structure for VSDK into separate Folder as below link_fw Make System (Common for FW & all Apps modules) sample_app apps algorithms docs testsuite	Directory structure should be as stated	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1205: VSDK 3.0 restructuring ADASVISION-929: SDK FW and App separation		
<u>Keywords:</u>	None		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.4.6.Test Suite : ECC_FFI

Test Case VISIONSDK-121: Capture_FrameCopy_FFI_DSP1_Display			
Summary:			
ECC FFI UC - 1CH VIP capture + QM Alg Frame Copy with FFI (DSP1) + Display			
Input : OV10635 sensor			
Output : HDMI 1080P			
Preconditions:			
Ensure Binaries build with ECC_FFI_INCLUDE=yes			
Verify that Capture/display is running on IPU1-0 at 30fps			
#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Run "1CH VIP capture + QM Alg Frame Copy with FFI (DSP1) + Display " UC	Display must come up and no buffer drops should be observed Performance stats must match with Datasheet	
Execution type:	Automated		
Estimated exec. duration (sec):	60.00		
Priority:	Medium		
Requirements	ADASVISION-1502: FFI (DSP CPU) - XMC ADASVISION-1505: FFI (DSP EDMA & EVE) - L3FW ADASVISION-1506: EMIF ECC support ADASVISION-1510: DCC support		
Keywords:	None		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

Test Case VISIONSDK-122: Capture_FrameCopy_FFI_EVE1_Display			
<u>Summary:</u>			
ECC FFI UC - 1CH VIP capture + QM Alg Frame Copy with FFI (EVE1) + Display (TDA3x only)			
Input : OV10635 sensor			
Output : HDMI 1080P			
<u>Preconditions:</u>			
Ensure Binaries build with ECC_FFI_INCLUDE=yes			
Verify that Capture/display is running on IPU1-0 at 30fps			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Run "1CH VIP capture + QM Alg Frame Copy with FFI (EVE1) + Display (TDA3x only)" UC	Display must come up and no buffer drops should be observed Performance stats must match with Datasheet	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		

<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-1505: FFI (DSP EDMA & EVE) - L3FW ADASVISION-1506: EMIF ECC support
<u>Keywords:</u>	None
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

1.4.7.Test Suite : IPC_LIB

Test Case VISIONSDK-123: IPC_LIB			
<u>Summary:</u>			
IPC LIB UC			
Input : OV10635 sensor			
Output : HDMI 1080P			
<u>Preconditions:</u>			
Build binaries for all platform with IPC_LIB_INCLUDE=yes			
Verify that Capture/display is running on IPU1-0 at 30fps			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Run all UCc one by one from UC menu	Display must come up and no buffer drops should be observed Performance stats must match with Datasheet	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-925: Safe IPC implementation and integration with Vision SDK		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm m_ipc		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-240: Low_Latency_IPC			
<u>Summary:</u>			
Low Latency IPC UC			
Input : OV10635 sensor			
Output : HDMI 1080P			
<u>Preconditions:</u>			
Build binaries for all platform with IPC_LIB_INCLUDE=yes & WORKQ_INCLUDE=yes			
Verify that Capture/display is running on IPU1-0 at 30fps			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Run all UCc one by one from UC menu	Display must come up and no buffer drops should be observed Performance stats must match with Datasheet	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			

<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-1137: Low latency IPC support in VSDK to reduce the CPU load and latency ADASVISION-925: Safe IPC implementation and integration with Vision SDK
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

1.4.8.Test Suite : RTI

Test Case VISIONSDK-226: VIP_Capture_Display_suspend_IPU1_0			
<u>Summary:</u>			
Capture Display UC			
Input : OV10635			
Output : HDMI 1080P			
<u>Preconditions:</u>			
Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps			
verify RTI configuration with expiry detection and recovery support			
Load the binaries using CCS/SD card			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P	Capture Source should be OV10635 & Display device as HDMI 1080P	
2	Run 1 Ch VIP capture + Display UC	Display must come up and no buffer drops should be observe	
3	Suspend/reset the IPU core through CCS	System should re-start automatically RTI logs should displayed on console	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1509: RTI support ADASVISION-1594: RTI configuration with expiry detection and recovery support		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-227: VIP_Capture_FrameCopy_Display_suspend_DSP_EVE			
<u>Summary:</u>			
Capture Framecopy Display UC on DSP1/EVE1			
Input : OV10635			
Output : HDMI 1080P			
<u>Preconditions:</u>			
Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps			
verify RTI configuration with expiry detection and recovery support			
Load the binaries using CCS/SD card			

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P	Capture Source should be OV10635 & Display device as HDMI 1080P	
2	Run 1 Ch VIP capture + Framecopy + Display UC	Display must come up and no buffer drops should be observed	
3	Suspend/reset the DSP/EVE core through CCS	CPU load bar of suspended core shown as red RTI logs should be displayed on console	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1509: RTI support ADASVISION-1594: RTI configuration with expiry detection and recovery support		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.5.Test Suite : Open_Compute

1.5.1.Test Suite : OpenVX

Test Case VISIONSDK-223: OpenVX_Confirmation_Test

Summary:

OpenVX Confirmation Test v1.1

supported on both Bios/Linux

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Boot EVM Run OpenVX Confirmation Test v1.1	Confirmation test should run automatically	

Execution type:

Manual

Estimated exec. duration (sec):

60.00

Priority:

Medium

Requirements

ADASVISION-1553: Algorithm Link Support In place computation support
ADASVISION-936: OpenVX framework - BIOS, Linux (Phase 1)

Keywords:

tda2xx-evm
tda2ex-evm
tda3xx-evm
tda2ex-entry
tda2px-evm

Execution Details

Build

REL_3_7

Tester

x0246581

Execution Result:

Passed

Execution Mode:

Manual

Execution duration (sec):

Test Case VISIONSDK-224: OpenVX_Tutorials			
<u>Summary:</u>			
OpenVX Tutorials			
supported on both Bios/Linux			
<u>Preconditions:</u>			
Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Boot EVM Run OpenVX Tutorials	Tutorials should run automatically	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-936: OpenVX framework - BIOS, Linux (Phase 1)		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm		
Execution Details			

Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-225: VIP_Capture_OpenVX_Display_Input_OV10635_Output_HDMI_1080PSummary:

OpenVX Capture Display UC supported on Bios

Input : OV10635

Output : HDMI 1080P

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10635 Sensor & Display Output as HDMI 1080P	Capture Source should be OV10635 Sensor & Display device as HDMI 1080P	
2	Run "VIP Single Channel Capture + OpenVX + Display" UC	Display must come up and no buffer drops should be observed	
Execution type:	Manual		
Estimated exec. duration (sec):	60.00		
Priority:	Medium		
Requirements	ADASVISION-936: OpenVX framework - BIOS, Linux (Phase 1)		
Keywords:	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

Test Case VISIONSDK-368: ISS_Capture_OpenVX_Display_Input_AR140_Output_HDMI_1080PSummary:

OpenVX Capture Display UC supported on Bios

Input : AR140

Output : HDMI 1080P

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as AR140 Sensor & Display Output as HDMI 1080P	Capture Source should be AR140 Sensor & Display device as HDMI 1080P	
2	Run "ISS Single Channel Capture + OpenVX + Display" UC	Display must come up and no buffer drops should be observe	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration</u>	60.00		

<u>(sec):</u>	
<u>Priority:</u>	Medium
<u>Requirements</u>	ADASVISION-2170: [DMS] Create use case with openvx compute with links for sensor driver and display ADASVISION-936: OpenVX framework - BIOS, Linux (Phase 1)
<u>Keywords:</u>	tda3xx-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

1.6.Test Suite : Multi_Cam

1.6.1.Test Suite : Multi_Channel_LVDS_Capture_Display

Test Case VISIONSDK-22: VIP_4CH_Capture_Display_OV10635_913deser			
<u>Summary:</u>			
4 Channel Capture Display UC			
Input : OV10635 with 913/914 deserializer			
Output : HDMI 1080P			
<u>Preconditions:</u>			
Verify whether display shows a smooth stitching of the 4 views in Mosaic All running at 30fps. Also check performance stats match with datasheet			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P	Capture Source should be OV10635 & Display device as HDMI 1080P	
2	Run "4CH VIP Capture + Mosaic Display" UC Select "0" For Single channel mode Select "1" For Multi channel mode	On selecting "0" Display must come up with CH0 preview on full screen and no buffer drops should be observe On selecting "1" Display must come up with 4CH mosaic on full screen and no buffer drops should be observe	
<u>Execution type:</u>	Automated		
<u>Estimated exec. duration (sec):</u>	60.00		
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1275: VIP Capture Link to support Multi channel capture ADASVISION-1276: VIP Capture Link to support Multi channel capture ADASVISION-1277: VIP Capture Link- VIP port Config per VIP instance in multi-VIP port mode ADASVISION-1282: VIP Capture Link to support Multi instance link support ADASVISION-1294: VIP Capture Link to support Multi-channel capture upto 4CH ADASVISION-1304: Display Link - Display Multi instance support ADASVISION-1306: Display Link - HDMI display support ADASVISION-1324: multi sensors support ADASVISION-1325: support LVDS capture ADASVISION-1387: 4CH LVDS VIP Capture + VPE + Sync + Alg DMA SW Mosaic (IPU1-0) + Display ADASVISION-1580: Support for TDA2Ex (J6-Eco) in vision SDK ADASVISION-1582: Shall support LVDS multi-channel capture upto 4 channel ADASVISION-1584: Shall support all the Bios single multi camera usecases which use one DSP & M4 ADASVISION-1668: Custom SWMS link to use VPE (scalar) internally to avoid DMA copy ADASVISION-897: Add single camera capture display using lvds for all platforms		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm c_regression c_qualification m_capture m_display		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		

<u>Execution duration (sec):</u>	
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Test Case VISIONSDK-132: CSI2_4CH_Capture_Display_OV10635_964deserSummary:

4 Channel Capture Display UC

Input : OV10635 with 964 deserializer

Output : HDMI 1080P

Preconditions:

Verify whether display shows a smooth stitching of the 4 views in Mosaic
All running at 30fps. Also check performance stats match with datasheet

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as "OV10635 Sensor for Mosaic Display - SAT0088/OV10635 (TDA2EX & TDA3x)" & Display Output as HDMI 1080P	Capture Source should be "OV10635 Sensor for Mosaic Display - SAT0088/OV10635 (TDA2EX & TDA3x)" & Display device as HDMI 1080P	
2	Run "OV10635 & UB964 4CH CSI2 Capture + Display" UC Select "1" For Multi channel mode	On selecting "1" Display must come up with 4CH mosaic on full screen and no buffer drops should be observe	

Execution type: AutomatedEstimated exec. duration (sec): 60.00Priority: Medium

Requirements
 ADASVISION-1133: Capture & Display usecase with UB9640 & 4 modules of SAT0088 on TDA2x 17x17 package
 ADASVISION-1582: Shall support LVDS multi-channel capture upto 4 channel
 ADASVISION-1584: Shall support all the Bios single multi camera usecases which use one DSP & M4
 ADASVISION-1604: Support sensor frame work

Keywords:
 tda2ex-evm
 tda3xx-evm
 tda2ex-entry

Execution Details

Build REL_3_7

Tester x0246581

Execution Result: **Passed**Execution Mode: **Manual**Execution duration (sec):

1.6.2.Test Suite : SelectLink

Test Case VISIONSDK-186: VIP_4CH_Capture_Select_Display			
<u>Summary:</u>			
Multi Cam Capture Select Display UC			
supported on TDA2x/TDA2Ex/TDA3x			
Input : OV10635 Sensor			
Output : HDMI 1080P			
<u>Preconditions:</u>			
Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Run Testsuite	Check Logs of LVDS Capture Select Display UC Capture should be running on IPU1-0 at 30fps and display should be running on IPU1-0 at 60fps	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1521: select a particular channel		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.6.3.Test Suite : VIP_4CH_Capture_Color_To_Gray_Display

Test Case VISIONSDK-188: VIP_4CH_Capture_Color_To_Gray_Display

Summary:

Multi Cam Capture Color to Gray Display UC

supported on TDA2x/TDA2Ex/TDA3x

Input : OV10635 Sensor

Output : HDMI 1080P

Preconditions:

Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Run Testsuite	Check Logs of LVDS Capture Color to Gray Display UC Capture should be running on IPU1-0 at 30fps and display should be running on IPU1-0 at 60fps	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1558: Support Sample Algorithm Link (Color to Gray Plug-Ins) with inplace buffer processing		
<u>Keywords:</u>	tda2xx-evm tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.6.4.Test Suite : VIP_4CH_Capture_VPE_Sync_DMA_SWMS_Display

Test Case VISIONSDK-192: VIP_4CH_Capture_VPE_Sync_DMA_SWMS_Display			
<u>Summary:</u>			
Multi Cam Capture VPE Sync DMA SWMS Display UC			
supported on TDA2x/TDA3x			
Input : OV10635 Sensor			
Output : HDMI 1080P			
On IPU/A15: System EDMA			
On DSP: Local DMA			
<u>Preconditions:</u>			
Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Run Testsuite	Check Logs of LVDS Capture VPE Sync DMA SWMS Display UC Capture should be running on IPU1-0 at 30fps and display should be running on IPU1-0 at 60fps	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1559: Sample Algorithm Link (DMA SW Mosaic Plug-Ins)		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm c_integration m_vpe		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.6.5.Test Suite : Rear_View_Panorama

Test Case VISIONSDK-301: RSVP_4CH_VIP_Capture_960deser_IMI			
<u>Summary:</u> RSVP UC: 4CH VIP Capture + Stereo (DSPx, EVEx) + Image Transform (DSP1) + Seam Detection (DSP2) + Stitching (DSP1) + Display (HDMI) (TDA3X)UC Input : IMI OV10640 with 960 deserializer Output : HDMI 1080P			
<u>Preconditions:</u> Ensure TDA3x folder present in SD card with CHARTPOS.BIN & LENS.BIN Run SRV calibration UC if required to generate LUT.BIN Verify whether display shows a smooth stitching of all 4 cameras. All running at 30fps, Also check performance stats match with datasheet			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Go to System Settings Select Capture Source as "OV10640 Sensor for SV - IMI (TDA3x ONLY)" & Display Output as HDMI 1080P	Capture Source should be OV10640 Sensor for SV - IMI (TDA3x ONLY) & Display device as HDMI 1080P	
2	Run "4CH VIP Capture + Stereo (DSPx, EVEx) + Image Transform (DSP1) + Seam Detection (DSP2) + Stitching (DSP1) + Display (HDMI) (TDA3X)" UC	Display must come up and no buffer drops should be observed	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1432: Integrate statistics on Stereo ISP ADASVISION-1433: Integrate 2A support on Stereo ISP ADASVISION-1437: TISMO integration on DSP (C66x) ADASVISION-1438: Stereo capture use case implementation ADASVISION-1439: Stereo output interpolation and display ADASVISION-1440: Stereo performance benchmarking		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-302: RSVP_Manual_LDC_LUT_Generation			
<u>Summary:</u> RSVP UC:			

"Manual RSVP LDC LUT generation for Stereo (DSPx, EVEx) + Image Transform (DSP1) + Seam Detection (DSP2) + Stitching (DSP1) + Display (HDMI) (TDA3X)" UC

Input : IMI OV10640 with 960 deserializer

Output : HDMI 1080P

Preconditions:

Ensure TDA3x folder present in SD card with CHARTPOS.BIN & LENS.BIN

Run SRV calibration UC if required to generate LUT.BIN

Verify whether display shows a smooth stitching of all 4 cameras.

All running at 30fps, Also check performance stats match with datasheet

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as "OV10640 Sensor for SV - IMI (TDA3x ONLY)" & Display Output as HDMI 1080P	Capture Source should be OV10640 Sensor for SV - IMI (TDA3x ONLY) & Display device as HDMI 1080P	
2	Run "Manual RSVP LDC LUT generation for Stereo (DSPx, EVEx) + Image Transform (DSP1) + Seam Detection (DSP2) + Stitching (DSP1) + Display (HDMI) (TDA3X)" UC	Display must come up and no buffer drops should be observed	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1432: Integrate statistics on Stereo ISP ADASVISION-1433: Integrate 2A support on Stereo ISP ADASVISION-1437: TISMO integration on DSP (C66x) ADASVISION-1438: Stereo capture use case implementation ADASVISION-1439: Stereo output interpolation and display ADASVISION-1440: Stereo performance benchmarking		
<u>Keywords:</u>	tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.7.Test Suite : Radar

Test Case VISIONSDK-150: Radar_AR12_Capture_Null

Summary:

Radar Capture Null UC

Input : AR12

Output : Null

Supported on : TDA3x/TDA3x ALPS/TDA2x Cascade

Preconditions:

Ensure AR12 sensor Radar HW is connected to TDA3x EVM

Debug prints will be in UART2

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Boot TDA3x with Radar setup/TDA3xx ALPS Board/TDA2x Cascade	Shoul display Main Menu	
2	Run "Radar (Single AR1243) Capture + Null (TDA3xx Only) usecase" UC	No Display	
3	Press "P"	Check performance stats	

Execution type:

Manual

Estimated exec. duration (sec):

Priority:

Medium

Requirements

ADASVISION-1441: AR12xx sensor capture
ADASVISION-1445: RADAR processing performance benchmarking
ADASVISION-992: Radar Data Processing Usecase using AR12xx Sensor Data input

Keywords:

c_regression
c_qualification
tda3xx-alps
tda3xx-AR12-Booster

Execution Details

Build

REL_3_7

Tester

x0246581

Execution Result:

Passed

Execution Mode:

Manual

Execution duration (sec):

Test Case VISIONSDK-152: Radar_AR12_Capture_Radar_FrameCopy_DSP1_Null			
<u>Summary:</u>			
Radar Capture Radar Frame copy on DSP1 Null UC			
Input : AR12			
Output : Null			
<u>Preconditions:</u>			
Ensure AR12 sensor Radar HW is connected to TDA3x EVM			
Debug prints will be in UART2			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Boot TDA3x with Radar setup/TDA3xx ALPS Board	Should display Main Menu	

2	Run "Radar (Single AR1243) Capture + Radar Frame Copy (DSP1) + Null (TDA3xx Only) usecase" UC	No Display	
3	Press "P"	Check performance stats	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1269: [RADAR] Integrate Beam Forming Algorithm in SDK ADASVISION-1441: AR12xx sensor capture ADASVISION-1442: RADAR algorithm porting on DSP Alg link ADASVISION-985: Radar Processing Alg Plugin ADASVISION-986: Radar Processing Alg Plugin Flexibility ADASVISION-987: Radar Processing Single Alg Plugin on DSP and EVE ADASVISION-992: Radar Data Processing Usecase using AR12xx Sensor Data input		
<u>Keywords:</u>	c_stress c_qualification c_stability tda3xx-alps tda3xx-AR12-Booster		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-154: NullSrc_Capture_Radar_FFT_EVE1_Null_Read_Frames_SDcard

Summary:

Null Source Capture(SD card) Radar FFT on EVE1 Null UC

Input : AR12

Output : Null

Preconditions:

Input files present in SD card

Debug prints will be in

UART1 for TDA2x & UART2 for TDA3x

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Boot TDA2x/TDA3x	Should display Main Menu	
2	Run "Null Source (SD/Network) Input + Radar FFT (EVE1) + Null (SD/Network)" UC Select Data Read/Write Mode as SD card	No display	
3	Press "P"	Check performance stats	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1115: [RADAR] Support for build support and file based capture read process write ADASVISION-1255: Radar Advance frame configuration & dynamic configuration support ADASVISION-1269: [RADAR] Integrate Beam Forming Algorithm in SDK ADASVISION-1442: RADAR algorithm porting on DSP Alg link ADASVISION-1445: RADAR processing performance benchmarking ADASVISION-1570: power mamagement - CPU IDLE ADASVISION-1571: power mamagement - CPUIDLE: MPU Core 0/1 Idle ADASVISION-1572: power mamagement - CPUIDLE: IPU Core Idle ADASVISION-1573: power mamagement - CPUIDLE: DSP 1/2 Core Idle ADASVISION-1574: power mamagement - CPUIDLE: EVE 1/2/3/4 Core Idle ADASVISION-1575: PM - CPUIDLE: Vision SDK Integration of CPU IDLE ADASVISION-1699: [RADAR] Propagate each output channel info properly in RadarProcess Link Alg Plugin		

	ADASVISION-985: Radar Processing Alg Plugin ADASVISION-986: Radar Processing Alg Plugin Flexibility ADASVISION-987: Radar Processing Single Alg Plugin on DSP and EVE ADASVISION-989: Radar data read from SD card ADASVISION-990: Radar Data output to SD Card ADASVISION-993: Radar Data Processing Usecase using File Sensor Data input
<u>Keywords:</u>	tda2xx-evm tda3xx-evm
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-155: NullSrc_Capture_Radar_FFT_EVE1_Null_Write_Frames_SDcard

Summary:

Null Source Capture(SD card) Radar FFT on EVE1 Null UC

Input : AR12

Output : Null

Preconditions:

Input files present in SD card

Debug prints will be in

UART1 for TDA2x & UART2 for TDA3x

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Boot TDA2x/TDA3x	Should display Main Menu	
2	Run "Null Source (SD/Network) Input + Radar FFT (EVE1) + Null (SD/Network)" UC Select Data Read/Write Mode as SD card	No display	
3	Select File IO menu Write single frame to SD card	Writing single frame to SD card should be successful	

Execution type: Manual

Estimated exec. duration (sec):

Priority: Medium

Requirements

ADASVISION-1115: [RADAR] Support for build support and file based capture read process write
 ADASVISION-1269: [RADAR] Integrate Beam Forming Algorithm in SDK
 ADASVISION-1570: power mamagement - CPU IDLE
 ADASVISION-1571: power mamagement - CPUIDLE: MPU Core 0/1 Idle
 ADASVISION-1572: power mamagement - CPUIDLE: IPU Core Idle
 ADASVISION-1573: power mamagement - CPUIDLE: DSP 1/2 Core Idle
 ADASVISION-1574: power mamagement - CPUIDLE: EVE 1/2/3/4 Core Idle
 ADASVISION-1575: PM - CPUIDLE: Vision SDK Integration of CPU IDLE
 ADASVISION-985: Radar Processing Alg Plugin
 ADASVISION-986: Radar Processing Alg Plugin Flexibility
 ADASVISION-987: Radar Processing Single Alg Plugin on DSP and EVE
 ADASVISION-989: Radar data read from SD card
 ADASVISION-990: Radar Data output to SD Card
 ADASVISION-993: Radar Data Processing Usecase using File Sensor Data input

Keywords: tda2xx-evm
tda3xx-evm

Execution Details

Build REL_3_7

Tester x0246581

Execution Result: **Passed**

Execution Mode: **Manual**

Execution duration (sec):

Test Case VISIONSDK-156: NullSrc_Capture_Radar_FFT_EVE1_Null_Read_Frames_NWSummary:

Null Source Capture(Network) Radar FFT on EVE1 Null UC

Input : AR12

Output : Null

Preconditions:

Ensure NDK is enabled in build

Input files sent through network using network_tx

Debug prints will be in

UART1 for TDA2x & UART2 for TDA3x

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Boot TDA2x/TDA3x	Should display Main Menu	
2	Run "Null Source (SD/Network) Input + Radar FFT (EVE1) + Null (SD/Network)" UC Select Data Read/Write Mode as Network	No display	
3	Press "P"	Check performance stats	
4	using network_ctrl tool send a different parameter set	should be able to update with new parameter set	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1269: [RADAR] Integrate Beam Forming Algorithm in SDK ADASVISION-1699: [RADAR] Propagate each output channel info properly in RadarProcess Link Alg Plugin ADASVISION-1919: Radar: Allow accepting mmwave messages from Network to translate to AWR1243 SPI commands - Base Infr ADASVISION-985: Radar Processing Alg Plugin ADASVISION-986: Radar Processing Alg Plugin Flexibility ADASVISION-987: Radar Processing Single Alg Plugin on DSP and EVE ADASVISION-991: Radar data input and output via Ethernet		
<u>Keywords:</u>	tda2xx-evm tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-157: NullSrc_Capture_Radar_FFT_EVE1_Null_Write_Frames_NWSummary:

Null Source Capture(Network) Radar FFT on EVE1 Null UC

Input : AR12

Output : Null

Preconditions:

Ensure NDK is enabled in build

Input files sent through network using network_tx

Debug prints will be in

UART1 for TDA2x & UART2 for TDA3x

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Boot TDA2x/TDA3x	Should display Main Menu	

2	Run "Null Source (SD/Network) Input + Radar FFT (EVE1) + Null (SD/Network)" UC Select Data Read/Write Mode as Network	No display	
3	Run network_rx to dump files	Should be able to dump frmaes	
4	Using network_ctrl tool send a different parameter set	should be able to update with new parameter set	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1269: [RADAR] Integrate Beam Forming Algorithm in SDK ADASVISION-1919: Radar: Allow accepting mmwave messages from Network to translate to AWR1243 SPI commands - Base Infr ADASVISION-985: Radar Processing Alg Plugin ADASVISION-986: Radar Processing Alg Plugin Flexibility ADASVISION-987: Radar Processing Single Alg Plugin on DSP and EVE ADASVISION-991: Radar data input and output via Ethernet ADASVISION-993: Radar Data Processing Usecase using File Sensor Data input		
<u>Keywords:</u>	tda2xx-evm tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-232: Radar_AR12_Capture_Radar_Object_Detect_EVE1_NullSummary:

Radar Capture Radar Object Detect on EVE1 Null UC

Input : AR12

Output : Null

Preconditions:

Ensure AR12 sensor Radar HW is connected to TDA3x EVM

Debug prints will be in UART2

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Boot TDA3x with Radar setup/TDA3xx ALPS Board	Should display Main Menu	
2	Run "Radar (Single AR1243) Capture + Radar Object Detect (EVE1) + Null (TDA3xx Only) usecase" UC	No Display	
3	Select Normal Frame/Advanced Frame.	Depending upon selection Normal Frame/Advanced Frame should be selected	
4	Press "P"	Check performance stats	
5	Press 'c' to read back and verify parameters.	Should be able to read and verify parameters	
6	Press 'd' to dynamically change the slope.	Slope should be changed dynamically	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1269: [RADAR] Integrate Beam Forming Algorithm in SDK ADASVISION-985: Radar Processing Alg Plugin ADASVISION-986: Radar Processing Alg Plugin Flexibility ADASVISION-987: Radar Processing Single Alg Plugin on DSP and EVE ADASVISION-992: Radar Data Processing Usecase using AR12xx Sensor Data input		
<u>Keywords:</u>	tda3xx-alps tda3xx-AR12-Booster		
Execution Details			
Build	REL_3_7		

Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-233: Radar_AR12_Capture_Radar_Object_Detect_EVE1_DisplaySummary:

Radar Capture Radar Object Detect on EVE1 Display UC

Input : AR12

Output : HDMI

Preconditions:

Ensure AR12 sensor Radar HW is connected to TDA3x EVM

Debug prints will be in UART2

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Boot TDA3x with Radar setup	Should display Main Menu	
2	Run "Radar (Single AR1243) Capture + Radar Object Detect (EVE1) + Display (TDA3xx Only) usecase" UC	Display should come up & no buffer drops should observed	
3	Select Normal Frame/Advanced Frame.	Depending upon selection Normal Frame/Advanced Frame should be selected	
4	Press "P"	Check performance stats	
5	Press 'c' to read back and verify parameters.	Should be able to read and verify parameters	
6	Press 'd' to dynamically change the slope.	Slope should be changed dynamically	

Execution type: ManualEstimated exec. duration (sec):Priority: Medium

Requirements

ADASVISION-1255: Radar Advance frame configuration & dynamic configuration support
 ADASVISION-1268: [RADAR] Integrate Peak Detection EVE Algorithm in SDK
 ADASVISION-1269: [RADAR] Integrate Beam Forming Algorithm in SDK
 ADASVISION-1441: AR12xx sensor capture
 ADASVISION-1443: Radar output interpolation for display
 ADASVISION-1444: Simple RADAR capture + display use case
 ADASVISION-1672: [Radar] Add Radar System planner to the Release Package
 ADASVISION-985: Radar Processing Alg Plugin
 ADASVISION-986: Radar Processing Alg Plugin Flexibility
 ADASVISION-987: Radar Processing Single Alg Plugin on DSP and EVE
 ADASVISION-988: Radar output visualization
 ADASVISION-990: Radar Data output to SD Card
 ADASVISION-992: Radar Data Processing Usecase using AR12xx Sensor Data input
 ADASVISION-993: Radar Data Processing Usecase using File Sensor Data input

Keywords:

c_regression
 c_stress
 c_stability
 tda3xx-AR12-Booster

Execution Details

Build REL_3_7

Tester x0246581

Execution Result: **Passed**Execution Mode: **Manual**Execution duration (sec):**Test Case VISIONSDK-243: Radar_Flash_AR12_Firmware**Summary:

Radar AR12 Firmware Flash UC

supported on TDA3x ALPS board

Input : AR12 Firmware

Preconditions:

AR12 firmware is part of binaries

Debug prints will be in UART2

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Boot TDA3xx ALPS Board	Shoul display Main Menu	
2	Run "AR12 Firmware Flash (ALPS board Only)" UC	No Display	
3	Erase AR12xx Flash	Should erase previous firmware from flash	
4	Flash AR12xx Firmware	New firmware should be flashed	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1106: [RADAR] Add support for ALPS Hardware ADASVISION-1107: [RADAR] Support for Flashing firmware to AR12 flash on ALPS		
<u>Keywords:</u>	tda3xx-alps		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-313: Radar_AR12_Multi_Capture_Radar_FFT_EVE1_Display

Summary:

Radar Capture Radar FFT on EVE1 Display UC

Input : AR12

Output : HDMI

Preconditions:

Ensure AR12 sensor Radar HW is connected to TDA3x EVM

Debug prints will be in UART2

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Boot TDA3x/RVP with Radar setup	Should display Main Menu	
2	Run "Radar (Single AR1243) Capture + Radar FFT (EVE1) + Display (TDA3xx Only) usecase" UC	Display should come up & no buffer drops should observed	
3	Select Normal Frame/Advanced Frame.	Depending upon selection Normal Frame/Advanced Frame should be selected	
4	Press "P"	Check performance stats	
5	Press 'c' to read back and verify parameters.	Should be able to read and verify parameters	
6	Press 'd' to dynamically change the slope.	Slope should be changed dynamically	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1255: Radar Advance frame configuration & dynamic configuration support ADASVISION-1268: [RADAR] Integrate Peak Detection EVE Algorithm in SDK ADASVISION-1269: [RADAR] Integrate Beam Forming Algorithm in SDK ADASVISION-1441: AR12xx sensor capture ADASVISION-1443: Radar output interpolation for display ADASVISION-1444: Simple RADAR capture + display use case ADASVISION-1873: 4 x AWR1243 Satellite Demo ADASVISION-1875: Satellite radar chip support in Radar SDK		

	ADASVISION-985: Radar Processing Alg Plugin ADASVISION-986: Radar Processing Alg Plugin Flexibility ADASVISION-987: Radar Processing Single Alg Plugin on DSP and EVE ADASVISION-988: Radar output visualization ADASVISION-990: Radar Data output to SD Card ADASVISION-992: Radar Data Processing Usecase using AR12xx Sensor Data input ADASVISION-993: Radar Data Processing Usecase using File Sensor Data input
<u>Keywords:</u>	c_regression c_stress c_stability tda3xx-AR12-Booster
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-314: Radar_Test_Source_Object_Detection

Summary:

Radar Test Source Object Detection

Input : testdata

Output : HDMI

Preconditions:

Ensure AR12 sensor Radar HW is connected to TDA3x EVM

Debug prints will be in UART2

<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Enable Macro ENABLE_TEST_SOURCE in chains_common_ar12xx.c & configure test source in ChainsCommon_ar12xxEnableTestSource	Should be able to configure test source	
2	Build the code by running below command make -s -j depend; make -s -j	should be able to build	
3	Run "Radar (Single AR1243) Capture + Radar Object Detect (EVE1) + Display (TDA3xx Only) usecase" UC Select Normal Frame/Advanced Frame.	Depending upon selection Normal Frame/Advanced Frame should be selected	
4	Press "P"	Check performance stats	
5	Press 'c' to read back and verify parameters.	Should be able to read and verify parameters	
6	Press 'd' to dynamically change the slope.	Slope should be changed dynamically	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1255: Radar Advance frame configuration & dynamic configuration support ADASVISION-1268: [RADAR] Integrate Peak Detection EVE Algorithm in SDK ADASVISION-1269: [RADAR] Integrate Beam Forming Algorithm in SDK ADASVISION-1441: AR12xx sensor capture ADASVISION-1443: Radar output interpolation for display ADASVISION-1444: Simple RADAR capture + display use case ADASVISION-1677: [RADAR] Dynamic chirp configuration and thorough dynamic configuration testing ADASVISION-985: Radar Processing Alg Plugin ADASVISION-986: Radar Processing Alg Plugin Flexibility ADASVISION-987: Radar Processing Single Alg Plugin on DSP and EVE ADASVISION-988: Radar output visualization ADASVISION-990: Radar Data output to SD Card ADASVISION-992: Radar Data Processing Usecase using AR12xx Sensor Data input ADASVISION-993: Radar Data Processing Usecase using File Sensor Data input		
<u>Keywords:</u>	c_regression c_stress c_stability tda3xx-AR12-Booster		

Execution Details	
Build	REL_3_7
Tester	x0246581
Execution Result:	Passed
Execution Mode:	Manual
Execution duration (sec):	

1.8.Test Suite : Build

1.8.1.Test Suite : VSDK_Builds

Test Case VISIONSDK-249: VSDK_BIOS_different_builds			
<u>Summary:</u>			
VSDK BIOS different configurations Build			
<u>Preconditions:</u>			
Follow UG to Install release package			
All ti_cmponents (including PDK) should be part of release package			
Copy all necessary components (gcc tool,linaro tool chain)			
#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Navigate to (vsdk_install_path)/vision_sdk/build & run make -s showconfig	Should display config for tda2xx_evm_bios_all	
2	Modify Rules.mk file to other available MAKECONFIG & run make -s showconfig	Should display config for MAKECONFIG selected	
3	run make -s -j depend & then make -s -j	Should build binaries without any error	
4	run make -s appimage	should create Appimage	
5	run make -s sbl	Should create SBL	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1080: TDA2Px (J6+) Support with VSDK ADASVISION-1081: J6 Entry support for VSDK ADASVISION-1095: Platform support & maintainability ADASVISION-1167: Error handling requirements ADASVISION-1348: AppImage generation ADASVISION-1350: CPU selection ADASVISION-1351: Multiple Memory maps ADASVISION-1352: Multiple platforms support ADASVISION-1354: Build profile selection ADASVISION-1355: 256MB memory map ADASVISION-1356: 1GB memory map ADASVISION-1357: 128MB memory map ADASVISION-1358: 512MB memory map ADASVISION-1359: MMU configs of different CPUs ADASVISION-1360: Platform selection ADASVISION-1361: Selective builds for following links - VPE, ISS ADASVISION-1408: shall support Bios only build ADASVISION-1409: shall support bios + Liux on A15 ADASVISION-1529: Multiple heap support ADASVISION-1530: Cache configuration ADASVISION-1531: Memory config ADASVISION-1532: External Memory allocation ADASVISION-1533: Internal memory allocation from OCMC ADASVISION-1534: Internal memory allocation from DSP L2 SRAM at create time only, no run time allocation and de-alloc ADASVISION-1535: Internal memory allocation from DSP L1 SRAM ADASVISION-1570: power mamagemant - CPU IDLE ADASVISION-1571: power mamagemant - CPUIDLE: MPU Core 0/1 Idle ADASVISION-1572: power mamagemant - CPUIDLE: IPU Core Idle ADASVISION-1573: power mamagemant - CPUIDLE: DSP 1/2 Core Idle ADASVISION-1574: power mamagemant - CPUIDLE: EVE 1/2/3/4 Core Idle ADASVISION-1575: PM - CPUIDLE: Vision SDK Integration of CPU IDLE ADASVISION-1580: Support for TDA2Ex (J6-Eco) in vision SDK ADASVISION-1586: Static memory allocation in Vision SDK and its component		

	ADASVISION-1633: Migrate DSP CGT version of VSDK to use CGT 8.2.4 ADASVISION-1652: TDA2EX ETH SRV platform board Support with VSDK ADASVISION-1751: Support in the makefile to allow for file specific compile options ADASVISION-1857: [TDA3x-RVP] Support 1GB memory map ADASVISION-1980: Add support for the TDA2PX RVP to vision SDK ADASVISION-648: Improve the build time and build process ADASVISION-666: [BSP/STW] Removal of dynamic allocation from BSP and STW libraries ADASVISION-892: RVP support in vision SDK ADASVISION-930: PDK integration with Vision SDK. ADASVISION-955: RVP support in PSDK & VSDK
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp c_integration
<u>Attached files</u>	<ul style="list-style-type: none"> • BIOS Different Build Config : build_vsdk.sh • build_vsdk.sh
Execution Details	
Build	REL_3_7
Tester	x0246581
<u>Execution Result:</u>	Passed
<u>Execution Mode:</u>	Manual
<u>Execution duration (sec):</u>	

Test Case VISIONSDK-278: VSDK_KW_build			
<u>Summary:</u>			
VSDK Klocwork Build			
<u>Preconditions:</u>			
Jenkin Node is up & running			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Login to Jenkin server & trigger VSK_KW_build projet	Should build KW project & sent a report with open criticcal & major MISRA-C issues	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1353: Static code checker Klockwork ADASVISION-1517: Static code checker MISRA-C ADASVISION-1525: Follow coding guidelines		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.8.2.Test Suite : Radar_Builds

Test Case VISIONSDK-242: Radar_default_build			
Summary:			
Radar Default Build			
Preconditions:			
Follow UG to Install release package			
Copy all necessary components (gcc tool)			
#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Navigate to (radar_install_path)/vision_sdk/build & run make -s showconfig	Should display config for tda3xx_evm_bios_radar	
2	Check default config	By default all IPU1_0, IPU1_1, DSP1, EVE1 are enabled Memory should be 128MB NDK should be disabled & A15_TARGET_OS=Bios	
3	run make -s -j depend & then make -s -j	Should build binaries without any error	
4	run make -s appimage	should create Appimage	
5	run make -s sbl	Should create SBL	
Execution type:	Manual		
Estimated exec. duration (sec):			
Priority:	Medium		
Requirements	ADASVISION-1108: [RADAR] Support for 128 MB build by default ADASVISION-1348: AppImage generation		
Keywords:	tda3xx-evm c_qualification		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

Test Case VISIONSDK-280: Radar_BIOS_different_builds			
<u>Summary:</u> Radar different configurations Build			
<u>Preconditions:</u> Follow UG to Install release package All ti_components (including PDK) should be part of release package Copy all necessary components (gcc tool,linaro tool chain)			
#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Navigate to	Should display config for	

	(vsdk_install_path)/vision_sdk/build & run make -s showconfig	tda3xx_evm_bios_radar	
2	Modify Rules.mk file to other available MAKECONFIG & run make -s showconfig	Should display config for MAKECONFIG selected	
3	run make -s -j depend & then make -s -j	Should build binaries without any error	
4	run make -s appimage	should create Appimage	
5	run make -s sbl	Should create SBL	
Execution type:	Manual		
Estimated exec. duration (sec):			
Priority:	Medium		
Requirements	ADASVISION-1106: [RADAR] Add support for ALPS Hardware ADASVISION-1108: [RADAR] Support for 128 MB build by default ADASVISION-1115: [RADAR] Support for build support and file based capture read process write ADASVISION-1348: ApplImage generation ADASVISION-1350: CPU selection ADASVISION-1351: Multiple Memory maps ADASVISION-1352: Multiple platforms support ADASVISION-1354: Build profile selection ADASVISION-1359: MMU configs of different CPUs ADASVISION-1360: Platform selection ADASVISION-1755: [RADAR] Add support for TDA2px EVM ADASVISION-1853: [RADAR] VSDK to support TDA2x cascade radar		
Keywords:	tda2xx-evm tda3xx-evm tda3xx_rvp tda3xx-alps tda3xx-AR12-Booster c_integration		
Attached files	<ul style="list-style-type: none">• Radar Different Build Config : build_radar.sh• build_radar.sh		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

1.9.Test Suite : Release_Process

Test Case VISIONSDK-245: VSDK_Radar_release_check_list			
<u>Summary:</u>			
VSDK & Radar release check list			
<u>Preconditions:</u>			
VSDK & Radar RC package already installed & tested			
Verify that release goes through the standard release process			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Check for licenses, mainfest, release notes, test reports, datasheets	Release shall comply for the basic release process such as export license, OSRB approval etc.	
2	Check there are test cases for all product requirements (planned in release) & executed in testing phase	Tracebility report (Req -> Test) should have all req mapped to tc Test result matrix should have nothing in "Not Run" state	
3	Check updated project plan, test pain, test strategy docs for release are all available in clearcase	All updated version of docs should be available in clearcase	
4	Check for all docs available in vision_sdk/docs folder	All updated docs for current release should be available	
5	Check for all docs available in vision_sdk/docs folder	All updated docs for current release should be available	
6	Check all links in the "index.html" Remove unwanted links	All links in the "index.html" should work properly	
7	Check all links in the "index.html" Remove unwanted links	All links in the "index.html" should work properly	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1094: Software release process ADASVISION-1168: SW quality requirements ADASVISION-1513: Release process ADASVISION-1528: Product requirements ADASVISION-1672: [Radar] Add Radar System planner to the Release Package ADASVISION-1675: Processor SDK Vision ti.com landing page - clean-up ADASVISION-1690: Process: Update Software Integration and Test Strategy document ADASVISION-1752: [Radar] Add Radar System planner to the Release Package ADASVISION-875: Develop a How to Debug best practices document, that outlines how to rapidly load binaries, restart		
<u>Keywords:</u>	None		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-246: VSDK_pacckage_creation_and_installation

Summary:

VSDK package creation & installation on windows & linux machine

Preconditions:

VSDK RC package installed & tested

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Modify MPI files to pick correct ti_components Modify InstallJammer Environment script Trigger Jenking project for packaging	Windows & Linux installer should be created	
2	Install on windows machine Check for all customer collaterals & Build with default config	Installation should be success Release package should include all customer collaterals such as user guide, data sheet, Release notes, Test reports, Developer guide etc Build should be success	
3	Install on Linux machine Check for all customer collaterals & Build with default config	Installation should be success Release package should include all customer collaterals such as user guide, data sheet, Release notes, Test reports, Developer guide etc Build should be success	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1096: packaging and installation ADASVISION-1512: Single installer for vision SDK ADASVISION-1514: Customer collaterals		
<u>Keywords:</u>	c_qualification		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

Test Case VISIONSDK-247: Radar_pacckage_creation_and_installationSummary:

Radar package creation & installation on windows & linux machine

Preconditions:

Radar RC package installed & tested

#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Modify MPI files to pick correct ti_components Modify InstallJammer Environment script Trigger Jenking project for packaging	Windows & Linux installer should be created	
2	Install on windows machine Check for all customer collaterals	Installation should be success Release package should include all customer collaterals such as user guide, data sheet, Release notes, Test reports, Developer guide etc	

	& Build with default config	Build should be success	
3	Install on Linux machine	Installation should be success	
	Check for all customer collaterals	Release package should include all customer collaterals such as user guide, data sheet, Release notes, Test reports, Developer guide etc	
	& Build with default config	Build should be success	
<u>Execution type:</u>		Manual	
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>		Medium	
<u>Requirements</u>		ADASVISION-1096: packaging and installation ADASVISION-1514: Customer collaterals ADASVISION-917: Separate packaging for Radar SDKs	
<u>Keywords:</u>		c_qualification	
Execution Details			
Build		REL_3_7	
Tester		x0246581	
<u>Execution Result:</u>		Passed	
<u>Execution Mode:</u>		Manual	
<u>Execution duration (sec):</u>			

1.10.Test Suite : Boot_Modes

1.10.1.Test Suite : Secure_Boot

Test Case VISIONSDK-229: VIP_Capture_Display_UC_HS_Sample			
Summary:			
Capture Display UC on HS Sample			
Input : OV10635			
Output : HDMI 1080P			
Preconditions:			
Build SBL & Appimage with HS_SAMPLE=yes			
&load binaries on HS sample			
Verify that Capture is running on IPU1-0 at 30fps and display running on IPU1-0 at 60fps			
#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Go to System Settings Select Capture Source as OV10635 & Display Output as HDMI 1080P	Capture Source should be OV10635 & Display device as HDMI 1080P	
2	Run 1 Ch VIP capture + Display UC	Display must come up and no buffer drops should be observe	
3	Run all UC one by one	Display must come up and no buffer drops should be observe	
Execution type:	Manual		
Estimated exec. duration (sec):			
Priority:	Medium		
Requirements	ADASVISION-1515: Secure boot mode ADASVISION-888: Security Enablement “ TDA2x ADASVISION-913: TDA3x Security - SBL		
Keywords:	tda2xx-evm tda2ex-evm tda3xx-evm		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

1.10.2.Test Suite : QSPI_Boot

Test Case VISIONSDK-274: Load_Binaries_using_QSPI			
Summary:			
Load Binaries using QSPI			
Preconditions:			
Build Appimage & SBL for QSPI			
#:	Step actions:	PASS/FAIL Criteria:	Execution Status:
1	Connect EVM through CCS debug & Follow UG to set SYSBOOT PIN for CCS debug	SYSBOOT PINs should be for debug	
2	Follow UG to Flash SBL & ApplImage to QSPI	SBL & ApplImage should be flashed to QSPI	
3	Discoonect CCS & Follow UG to set SYSBOOT PIN for QSPI Boot	SYSBOOT PIN should be for QSPI Boot	
4	Boot EVM	EVM should boot with binaries & Display Main Menu	
Execution type:	Manual		
Estimated exec. duration (sec):			
Priority:	Medium		
Requirements	ADASVISION-1346: QSPI boot mode ADASVISION-1347: Flashing method		
Keywords:	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
Execution Result:	Passed		
Execution Mode:	Manual		
Execution duration (sec):			

1.10.3.Test Suite : QSPI_SD_Boot

Test Case VISIONSDK-275: Load_Binaries_using_QSPI_SD			
<u>Summary:</u>			
Load Binaries using QSPI SD			
supported only on TDA3x/RVP			
<u>Preconditions:</u>			
Build Appimage & SBL for QSPI SD Boot			
Copy AppImage to SD card			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Connect EVM through CCS debug & Follow UG to set SYSBOOT PIN for CCS debug	SYSBOOT PINs should be for debug	
2	Follow UG to Flash SBL	SBL should be flashed to QSPI	
3	Disconnect CCS Insert SD card to SD card slot Follow UG to set SYSBOOT PIN for QSPI SD Boot	SYSBOOT PIN should be for QSPI SD Boot	
4	Boot EVM	EVM should boot with binaries & Display Main Menu	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	ADASVISION-1344: SD boot mode ADASVISION-1347: Flashing method ADASVISION-1423: Basic board bringup (serial, pinmux, ddr, nand) using SBL ADASVISION-1425: Boot mode bringup ADASVISION-1601: SD card file system support with VSDK		
<u>Keywords:</u>	tda3xx-evm tda3xx_rvp		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			

1.10.4.Test Suite : CCS_Boot

Test Case VISIONSDK-332: Load_Binaries_using_CCS			
<u>Summary:</u>			
Load Binaries using CCS			
<u>Preconditions:</u>			
Build binaries			
<u>#:</u>	<u>Step actions:</u>	<u>PASS/FAIL Criteria:</u>	<u>Execution Status:</u>
1	Connect EVM through CCS debug & Follow UG to set SYSBOOT PIN for CCS debug	SYSBOOT PINs should be for debug	
2	Load binaries on each core separately or use the ".js" script available under vision_sdk/build/rtos/scripts to load on all cores at once	Binaries should be load on each core successfully & Display main menu on uart console	
3	From Main Menu run any UC	UC should run successfully	
4	Check for few register address whether displaying proper data or not	Data should be proper	
<u>Execution type:</u>	Manual		
<u>Estimated exec. duration (sec):</u>			
<u>Priority:</u>	Medium		
<u>Requirements</u>	None		
<u>Keywords:</u>	tda2xx-evm tda2ex-evm tda3xx-evm tda2ex-entry tda2px-evm tda3xx_rvp tda3xx-alps tda3xx-AR12-Booster		
Execution Details			
Build	REL_3_7		
Tester	x0246581		
<u>Execution Result:</u>	Passed		
<u>Execution Mode:</u>	Manual		
<u>Execution duration (sec):</u>			