

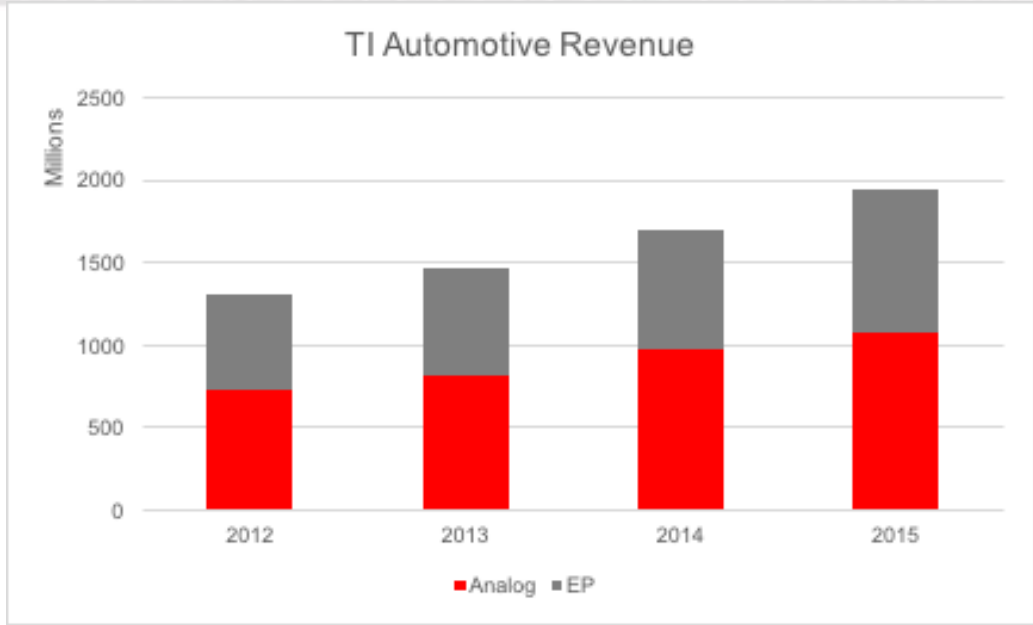
# TI Automotive ADAS Processor Solutions

TI Confidential – NDA Restrictions

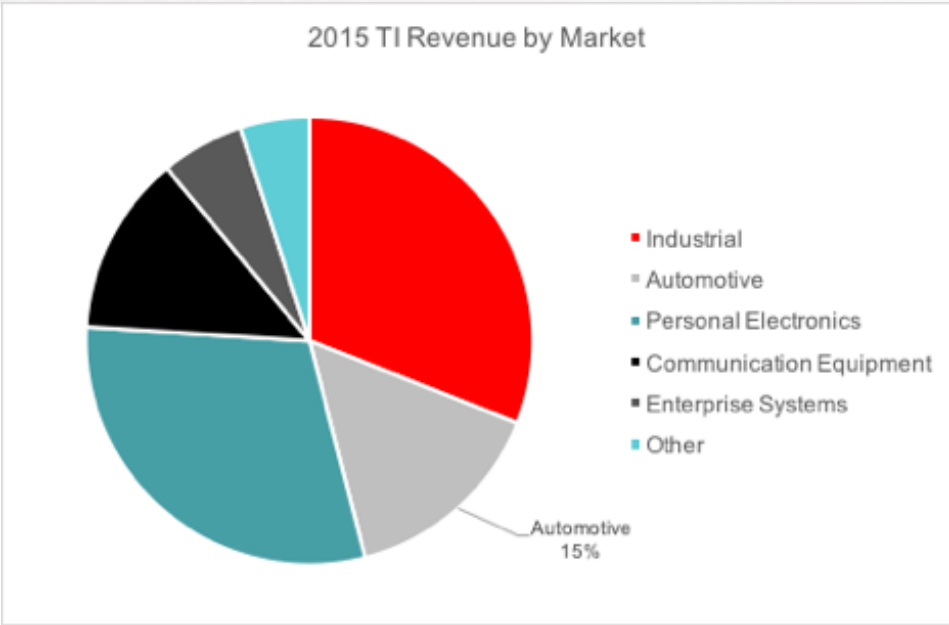
Oct 2016



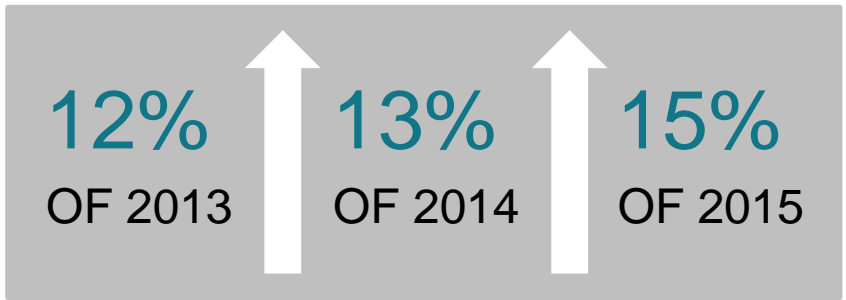
# TI IS COMMITTED TO THE AUTOMOTIVE MARKET



**15%**  
OF 2015  
TOTAL REVENUE



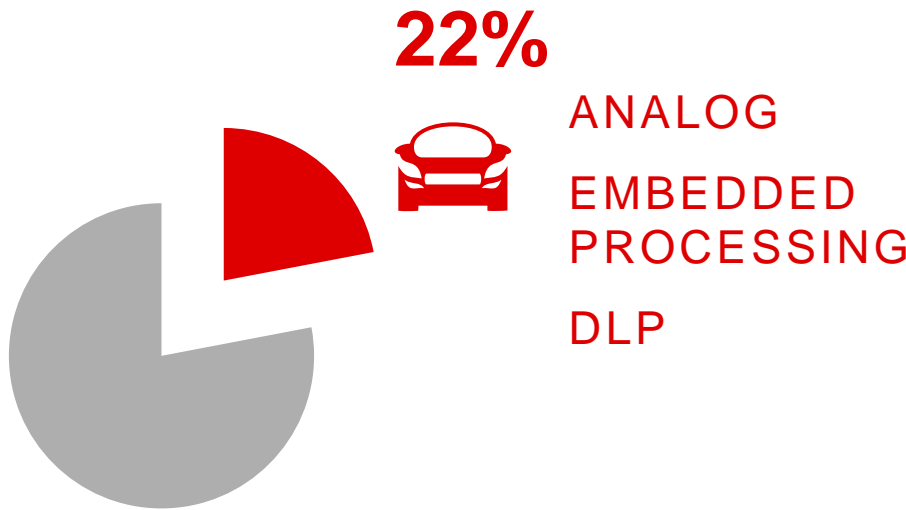
TI'S  
AUTOMOTIVE  
REVENUE IS:



TOTAL REVENUE



## TI R&D INVESTMENTS



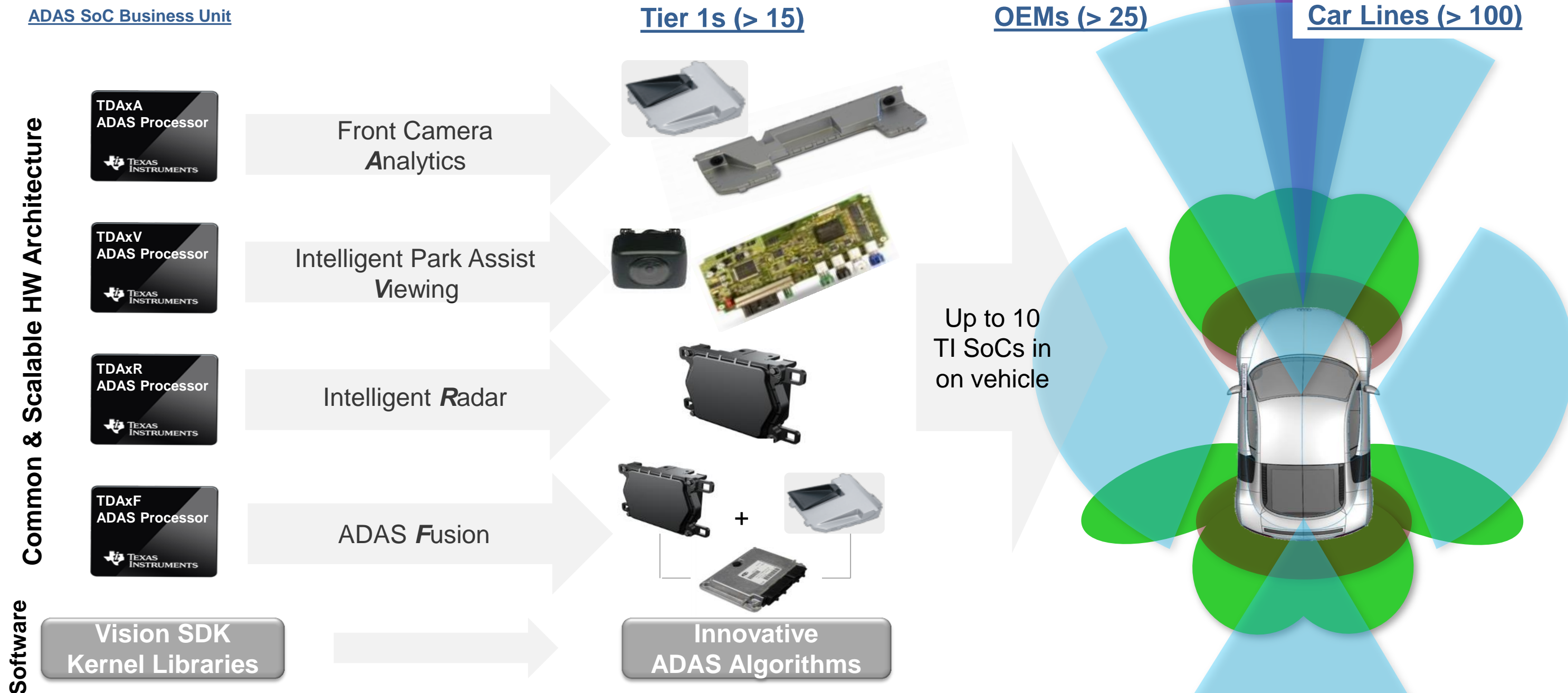
**>2X**

Increase in new products for automotive from 2013 to 2014



# TI ADAS SoC's in Active Safety & Autonomous Driving

Over 40 Million TI ADAS SoCs on the road through July 2016





# Target ADAS Applications

Core Applications

## Front Camera

**Scalable Performance  
Low Power  
Safety**



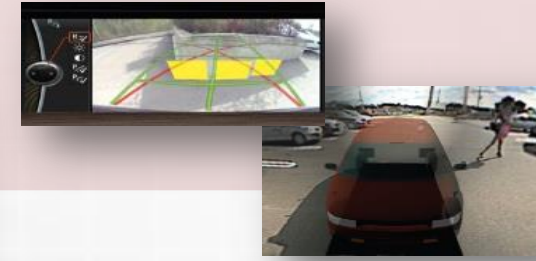
## Surround View

**Integrate 3D Graphics  
Scalable Analytics  
Security**



## Rear Camera

**Low Power  
Small Footprint  
Scalable Analytics**



## Radar

**Scalable performance  
MCU Integration  
Safety**



Emerging Applications

## Sensor Fusion

**High Performance  
Safety  
Security**



## Driver Monitoring

**Small Footprint  
ISP Integration Scalable  
Analytics**



## Mirror Replacement

**Performance  
ISP Integration  
Scalable Analytics**



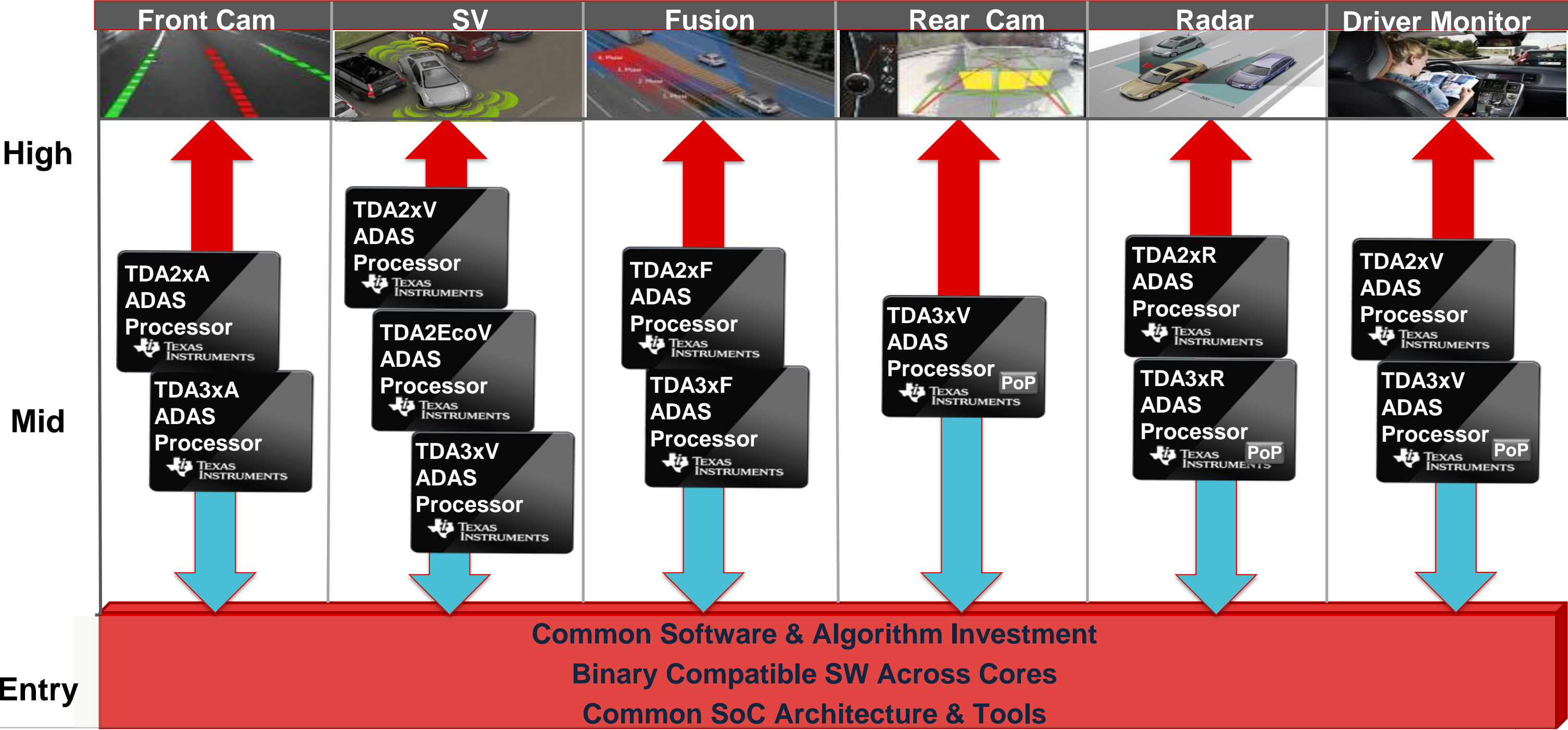
## Lidar

**Scalable Performance**

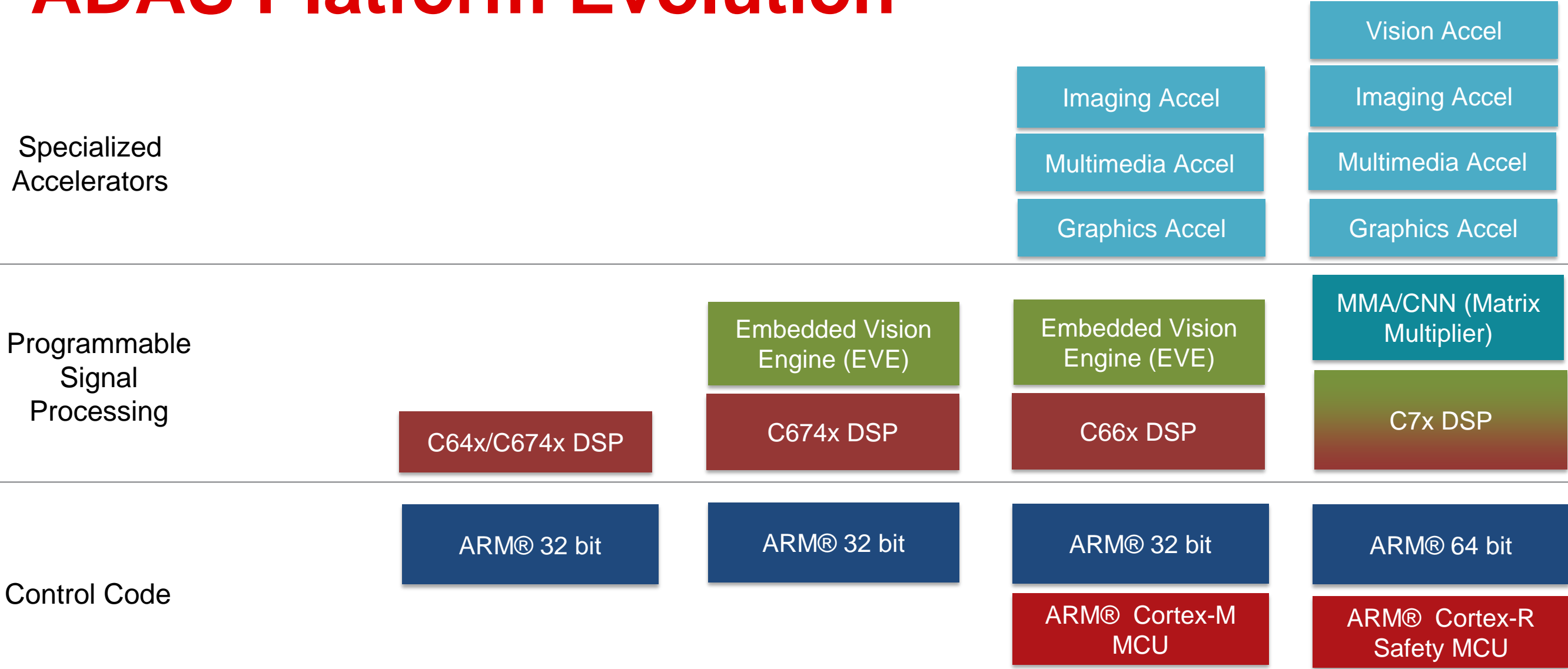


**Scalable premium to entry performance solutions.  
Fully programmable DSP, Vision Accelerators, and ARM cores.  
Software Development Kits and Libraries provide easy portability between platforms.**

# Current Gen TDA Family Scalability

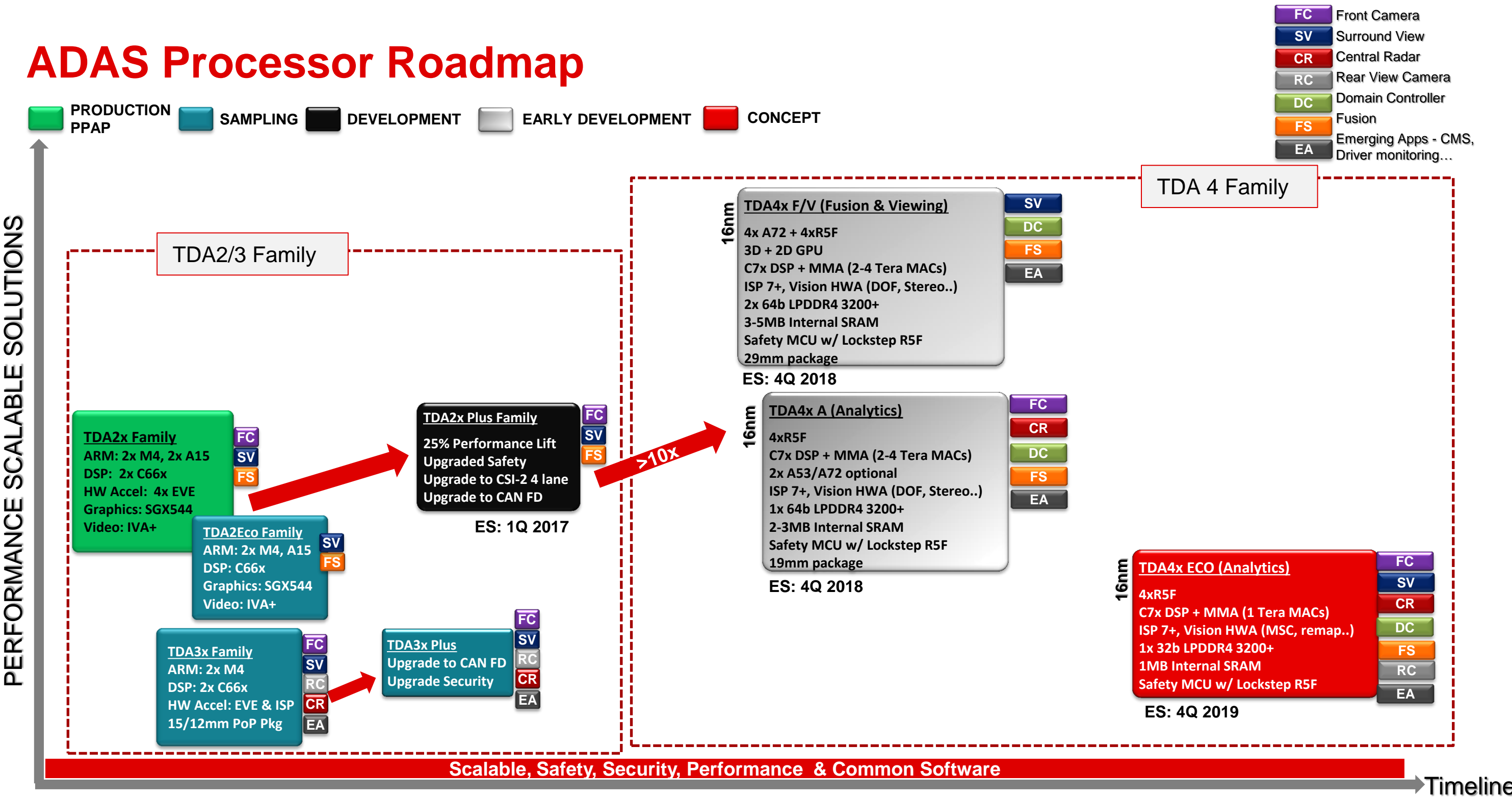


# ADAS Platform Evolution






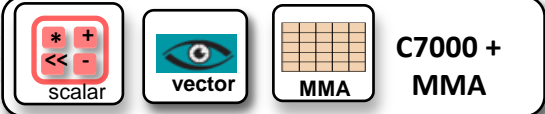
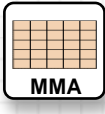











Generation	Gen 0/1	Gen 2	Gen 3	Gen 4
ASIL Enablement	A	B	B	C
Part Family	C67x/OMAPx/DMx	TDA1x	TDA2/3x	TDA4x

# ADAS Processor Roadmap



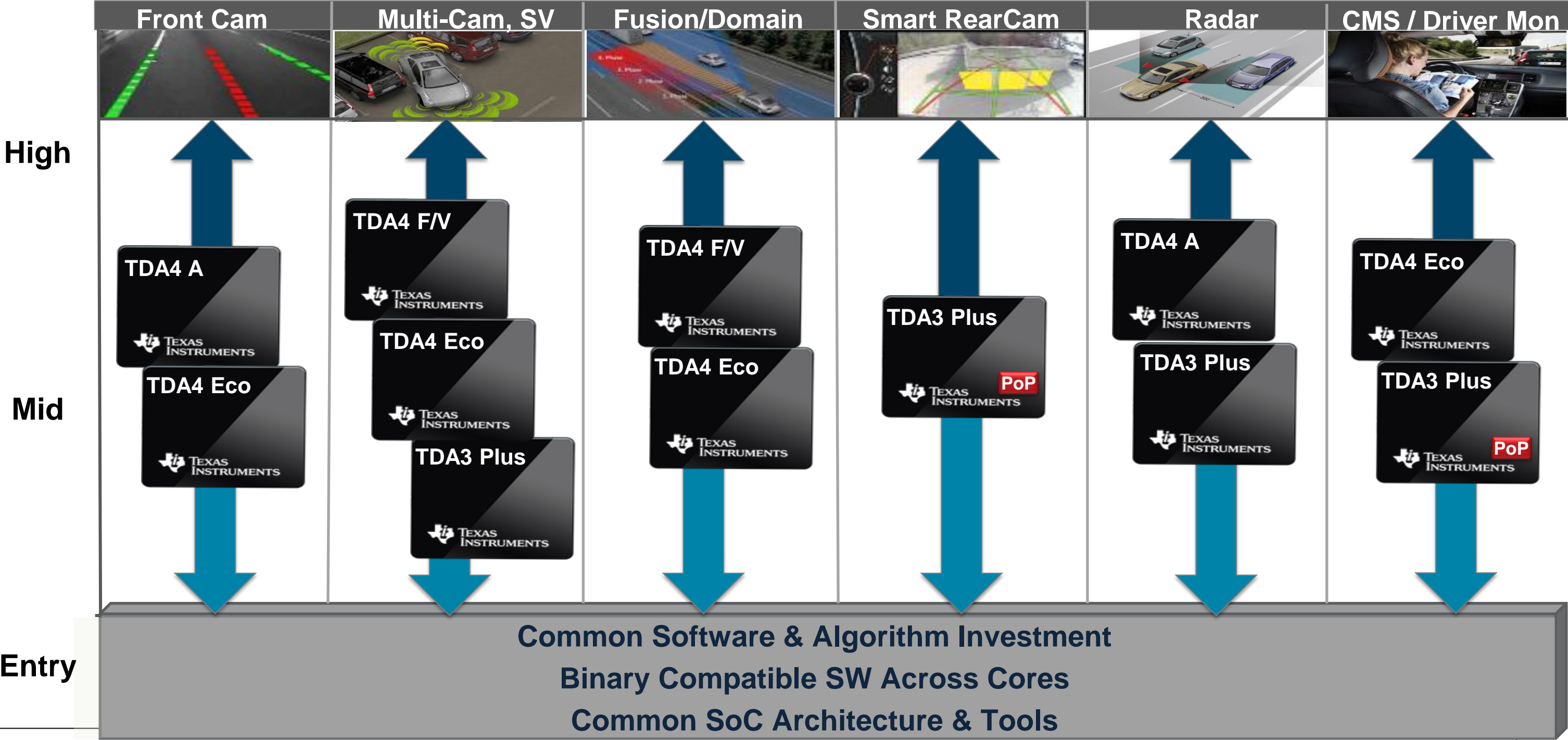


# TDA4 Platform Snapshot

CLUSTER	FEATURES			ENABLING
ARM CPU	 50K DMIPs	 4x Aux Cores	 Lockstep SafeTI™ MCU	<ul style="list-style-type: none"> <li>High performance Fusion DMIPS</li> <li>Integrated Safe MCU</li> </ul>
DSPs / Graphics	 C66x+EVE -> C7000 DSP	 4096 MAC/cycle	 250 GFlops	<ul style="list-style-type: none"> <li>Simplified SW Dev.</li> <li>&gt;4 TeraMACs deep learning accelerator</li> </ul>
Vision & Multimedia	 ISP 7.x, Vision HWA	 Multiple 2-4K display	 Encode + Decode	<ul style="list-style-type: none"> <li>&gt;10 2MP cameras at lowest BOM</li> <li>Optimized Acceleration</li> </ul>
High Speed IO	 >50 Gbytes/s	 PCIe 3, USB3.1, >10G Serdes	 10G Enet Switch	<ul style="list-style-type: none"> <li>Performance</li> <li>System Flexibility</li> <li>Switch integration</li> </ul>
Security & Security	 Enhanced Firewall	 Central Security & PWR	 Cryptos, security HWA	<ul style="list-style-type: none"> <li>V2V, V2X Security Ready</li> <li>Enhanced platform safety and FFI</li> </ul>
Software				<ul style="list-style-type: none"> <li>AutoSAR ready</li> <li>ISO26262 development compliant</li> </ul>

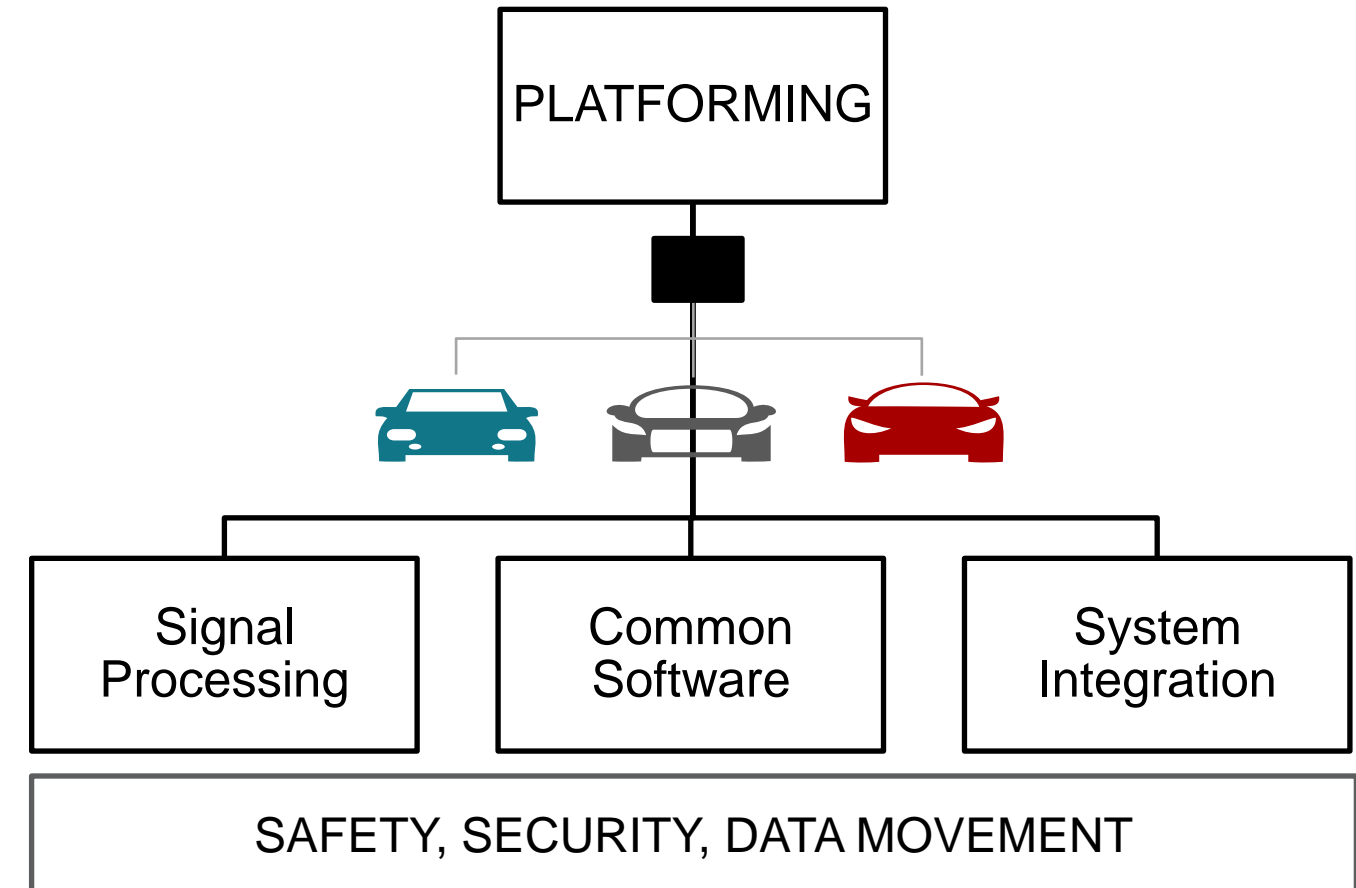


# Next Gen Scalable TDA Family



# Our strategy is to differentiate through...

- **Common & Scalable Platform**
  - Common Platform scaling from Entry, Mid to High
  - Scalable compute using HyperLink™
- **Common Software**
  - Vision SDK baseline
  - Dedicated Housekeeping MCU
  - Dedicated Safety MCU w/ AUTOSAR
- **Efficient Vision Compute**
  - Right tradeoff of programmable vs. fixed acceleration
  - Best power efficiency
- **Efficient Data Movement Architecture**
  - Cache, Data & IO Coherency
  - Data compression
  - Streaming based architecture
  - High bandwidth links with ultra low latency
- **Safety & Security**
  - Dedicated Safety MCU
  - Dedicated Security & Device Management Processor
  - Dedicated Security Accelerators
- **High System Integration**
  - On die. Extensive Analog Integration
  - Next Gen PM Solutions
  - Next Gen. Interfaces for Interprocessor communication & Chip to Chip connectivity

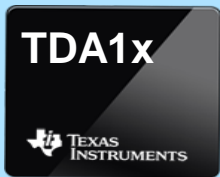


# TI Vision

## Gen 2 – ADAS

## Gen 3 – Highly Autonomous Driving

## Gen 4 – Fully Autonomous Driving



- DSP - C66x
- Vision -EVE
- **ISP – Imaging HWA**

- **More cores**
- C66x
- EVE

- C66x - DSP
- EVE – Vision coprocessor



- C7x – New powerful DSP with Vector Core
- ISP – Vision Optimized ISP
- DOF, Stereo
- MMA – Powerful programmable Matrix Co-processor optimized for CNN & other matrix operations
- High Security

16nm FF provides 5-6X performance boost at same power



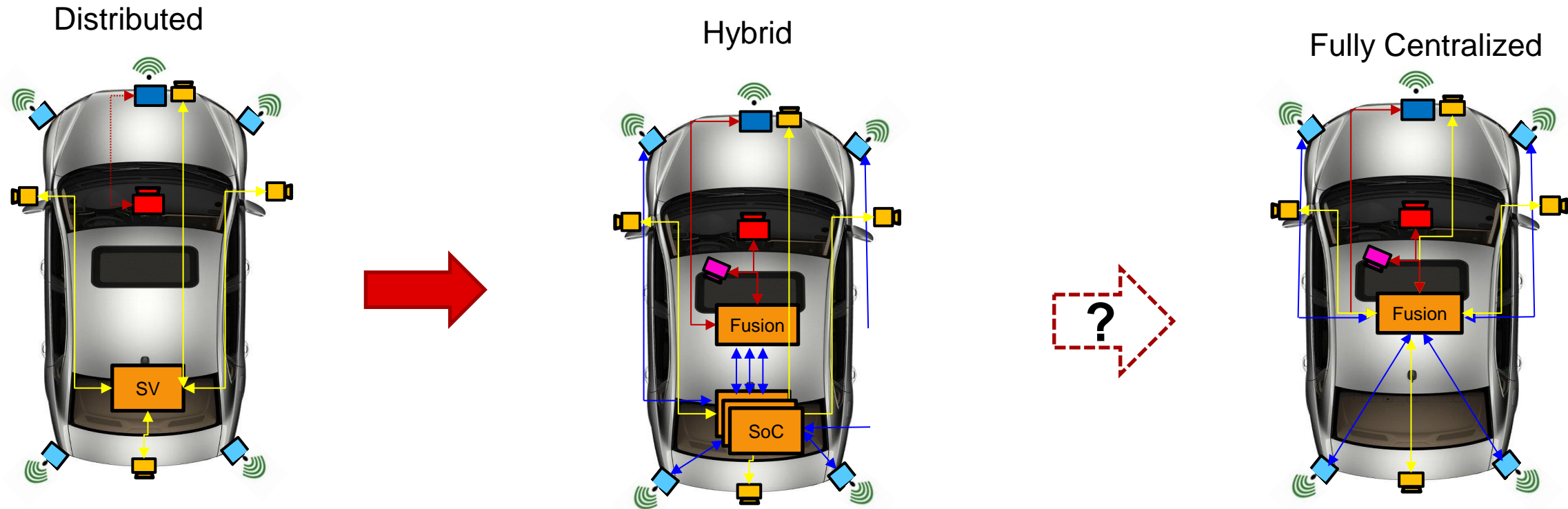
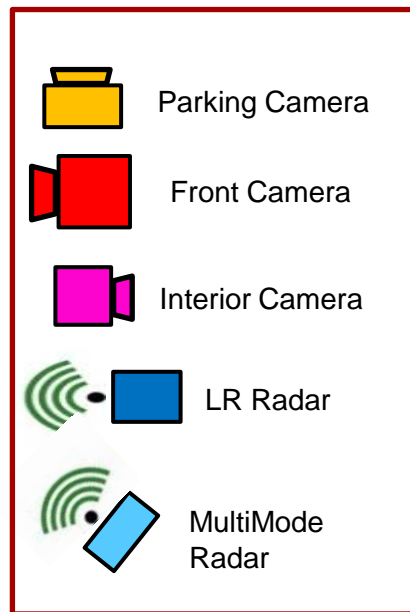
- C7x plus – Same architecture plus
- ISP plus – enhancements & speed increase
- Vision HWA plus – enhancements
  - DOF
  - Stereo
  - **Other**
- MMA – Enhancements for more powerful CNN & Matrix operation processing
- **Communication**
- **Bandwidth reductions & improvements**

ADAS

ADAS to Autonomous transition

Autonomous Driving

# ADAS System Migrations



## Distributed Systems

- State of the art today
- Processing on the edge – processor close to sensor
- Easy to manage - Clear ownership
- Power and size constraints

## Hybrid “Centralized” System

- Hi speed transmission of RAW data to dedicated centralized processor node
- Aggregate common sensor nodes into Central Fusion ECU - Each processor node transmits object data to fusion ECU
- Easy to manage - Clear ownership
- Easily Scalable
- Sensing Units can be very small
- Processing Units Power & Size can be relaxed

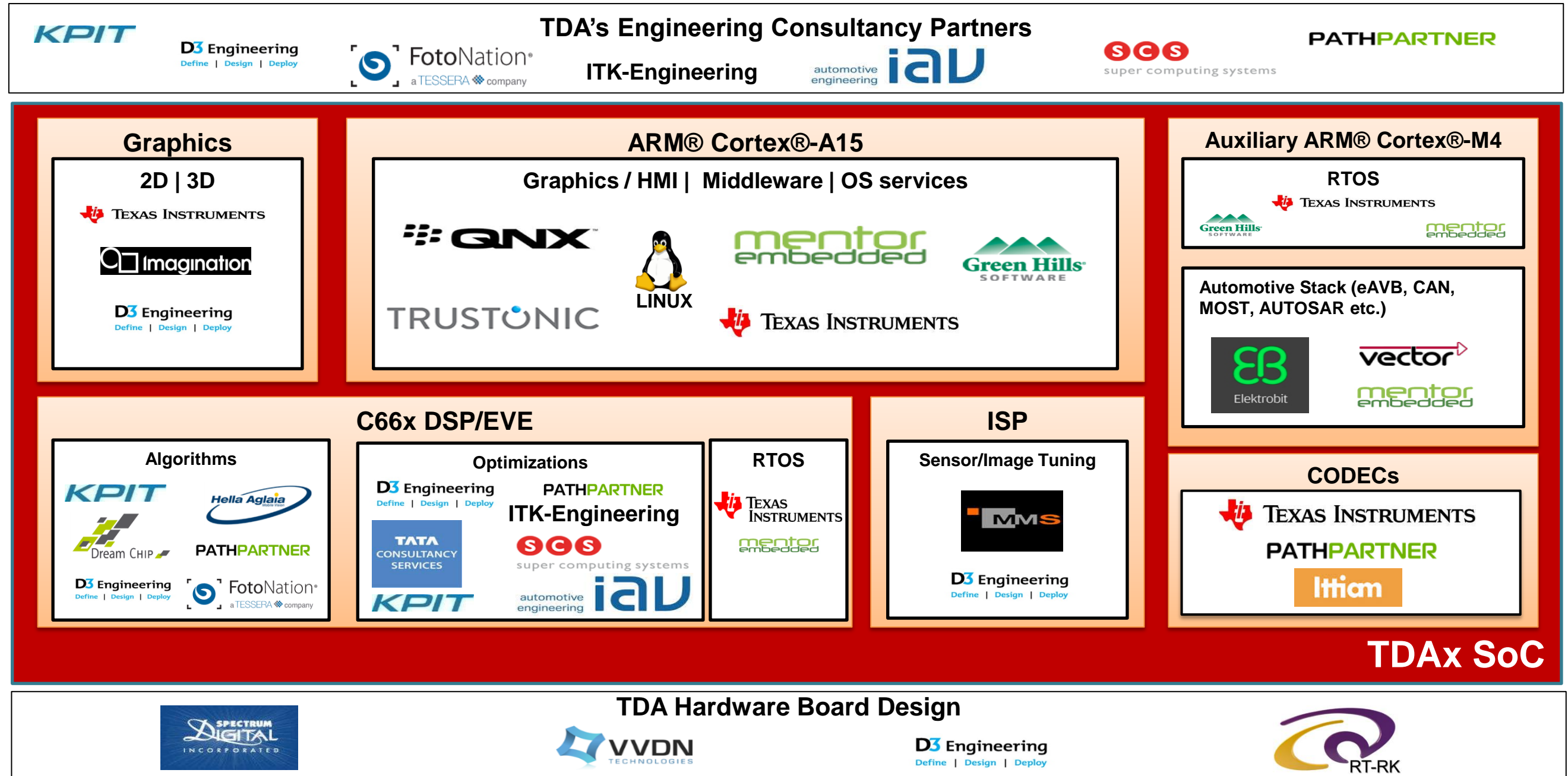
## Full Centralized Processing

- Very complex, expensive, and difficult to scale to lower cost vehicles (zFAS)
- Difficult to manage multi-vendor Collaboration on one chip
- Multiple vendor systems on one chip raises safety and responsibility issues

**TI has extensive knowledge and market presence in each of these building blocks on a common HW & SW platform, allowing easy migration between system architectures.**



# Ecosystem - ADAS



# D3 Engineering – RVP

## TDAx Rugged Vision Platform

- ✓ Small form factor
- ✓ Ready for on-vehicle testing and prototypes
- ✓ Automotive ready
- ✓ Production support from D3
- ✓ ISP tuning and algorithm optimization from D3
- ✓ Multiple sensors supported



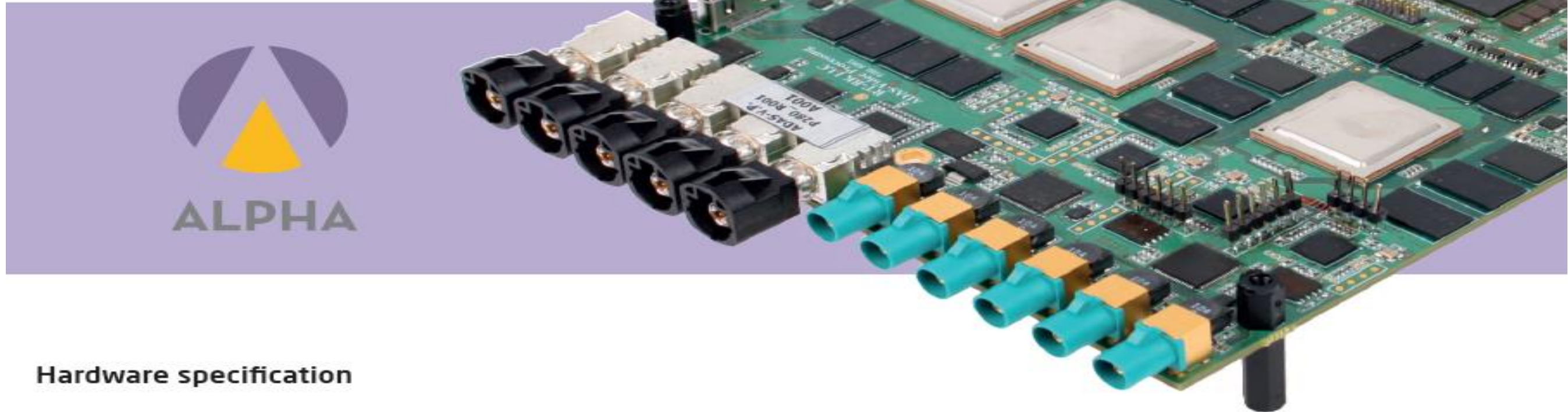
A fully functioning evaluation system speeds on-vehicle testing and development of multi-camera, real-time vision applications requiring intensive video analytics.



# RTRK Automotive Machine Vision (AMV)

## Target audience

- Car manufacturers (OEMs)
- Automotive design houses (Tier1/2/3) for rapid prototyping
- TI advanced automotive customers
- Algorithm developers for demo purposes



## Hardware specification

- Processors: 3 x TDA2x SoC (up to 2x ARM Cortex A15 and 2x ARM Cortex M4, 2x C66x Digital Signal Processor cores (DSP), 4x Embedded vision Engine (EVE)).

# TDA2x/2Ex/3x – Processor SDK – Vision (Vision SDK) 2016 ROADMAP

## v2.06

- Power Management
- ISS Image tuning tool (TDA3x)
- 4-Ch 2D Surround View Demo (TDA3x)
- AWB, AE library (TDA3x)
- Tuned AR140, OV10640 with WDR (TDA3x)
- Linux Kernel v3.14, GLSDK 7.0

Mar 5, 2015



## V2.07

- Boot optimization (TDA3x)
- TeSoc, ECC, CRC, WWDT (TDA3x)
- 4-ch low cost surround view with TI960H on TDA2x/2Ex, internal ISP on TDA3x
- Removal of Dynamic memory allocation from links/drivers
- SBL/StarterWare MISRA-C compliance

Jul 9, 2015



## V2.08

- Quality Managed (non safety) Production Ready
- EVE library, ISS Drivers and Vision-SDK Links MISRA-C compliance
- Linux Kernel v3.14, GLSDK 7.01
- Improved 3D Surround View SGX Demo

Oct 16, 2015



Jan'15 Feb'15 Mar'15 Apr'15 May'15 Jun'15 Jul'15 Aug'15 Sep'15 Oct'15 Nov'15 Dec'15

## 2.09

- ECC, RTI, DCC, ESM, FFI for DSP, EVE
- Diagnostic Library (SPI, ECC, ADC, CRC)
- Improved Object detect, Traffic Light recognition, Structure from Motion
- NCC on EVE Lib, CNN kernels on DSP VLIB
- Linux Kernel v3.14, GLSDK 7.03
- SGX Off screen rendering

Mar 30, 2016



## 2.10

- Secure boot on TDA2x/2Ex
- High throughput Ethernet
- TDA3x 3D SRV, 4 Ch 2A, 2D+3D, ~7s boot
- OpenCV/CL (A15)
- Linux Kernel v3.14, GLSDK 7.04

Jul 8, 2016



## 2.11

- TDA3x: Secure boot, MCAL: CAN-FD Alpha
- 3P (MMS, D3) 2A eval algorithms, 2MP Sensor
- TDA3x 3D SRV, WDR, ~2s boot,
- CSI2 capture driver on TDA2E
- Full 360 view generation tool for TDA3x SRV
- OpenCV, OpenCL, OpenVX, DSP acceleration
- Linux kernel 4.4, Processor Linux SDK 3.0
- Radar SDK (cut down for Radar only solutions)

Oct 30, 2016



Jan'16 Feb'16 Mar'16 Apr'16 May'16 Jun'16 Jul'16 Aug'16 Sep'16 Oct'16 Nov'16 Dec'16



# OpenCL, OpenVX and OpenCV

	OpenCL	OpenVX	OpenCV
Computer vision Library	NO	Yes	Yes
Defines a programming language	Yes	NO	NO
Defines an acceleration framework	Yes (Language based)	Yes (Graph based)	NO
Open standard API defined by Khronos	Yes	Yes	No (community driven open source)
Library Scope	NA	~43 vision kernels (v1.1) with user extension capability	~2500 vision and machine learning functions

# OpenXX Availability from TI

	OpenCL	OpenVX	OpenCV
Availability	Yes	VXLIB: Yes OpenVX API: TBD	Yes
Devices	<i>TDA2x, AM57xx, DRA7xx &amp; K2X</i>	<i>TDA2x, TDA3x, AM57xx, DRA7xx &amp; K2X</i>	<i>TDA2x, AM57xx, DRA7xx &amp; K2X</i>
Comments	DSP exposed as generic OpenCL compute device  EVE will be exposed as custom device	OpenVX Kernels will be available on DSP (VXLIB)  OpenVX API: Under implementation	Availability of modules on A15 and acceleration to EVE/DSP
Timelines	DSP (compute device) : 3Q-2016  EVE (custom device) : 1Q-2017	OpenVX Kernels on DSP (VXLIB): 3Q-2016 (Beta) 4Q-2016 (GA)	<ul style="list-style-type: none"> <li>• A15 <ul style="list-style-type: none"> <li>• Available</li> </ul> </li> <li>• DSP Acceleration <ul style="list-style-type: none"> <li>• 4Q-2016(Beta)</li> </ul> </li> <li>• EVE Acceleration <ul style="list-style-type: none"> <li>• 1Q-2017(Beta)</li> </ul> </li> </ul>